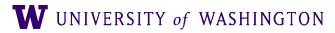
Linear Algebra

Ling 575j: Deep Learning for NLP C.M. Downey Spring 2023







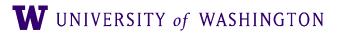
Today's Plan

- Review vector and matrix operations
- Discuss vector independence and span
- Dissect matrix multiplication
- Introduce linear transformations













• Scalars

- Single numbers
- What you're used to elsewhere in math
- examples: 0, 1, 3.14, π, 7/22





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x =

2 3





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 - *Lists* of scalars
- Matrices
 - Lists of vectors

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23





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- examples: 0, 1, 3.14, π, 7/22
- Vectors
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- **Matrices**
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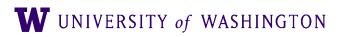
 ${\mathcal X}$

$\begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix}$ 2 3























$\begin{array}{c|c} 1 \\ x = & 2 \\ 3 \end{array}$

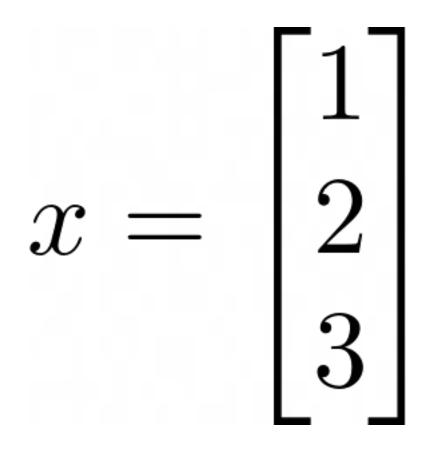








• *Transposed* vectors are rows



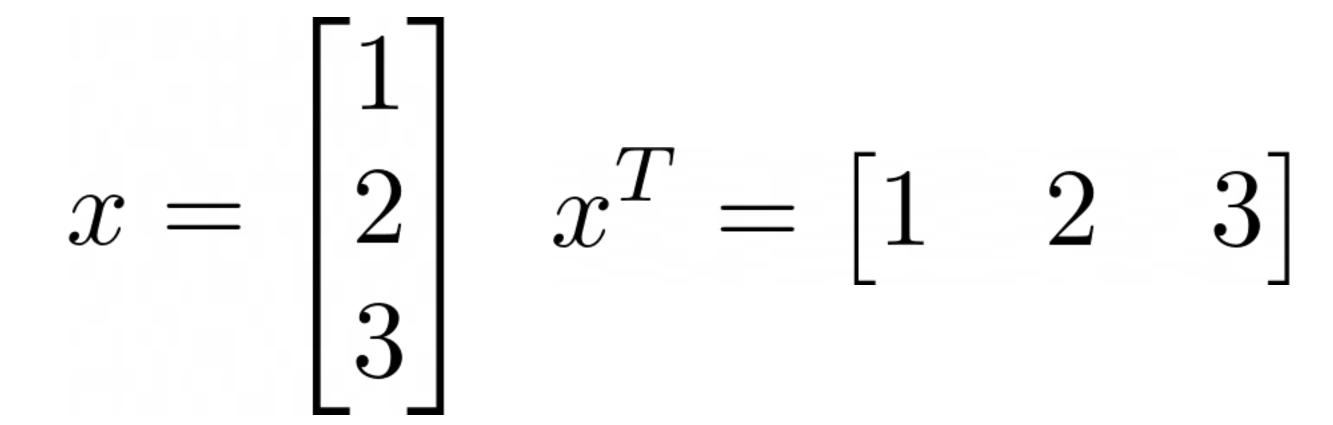








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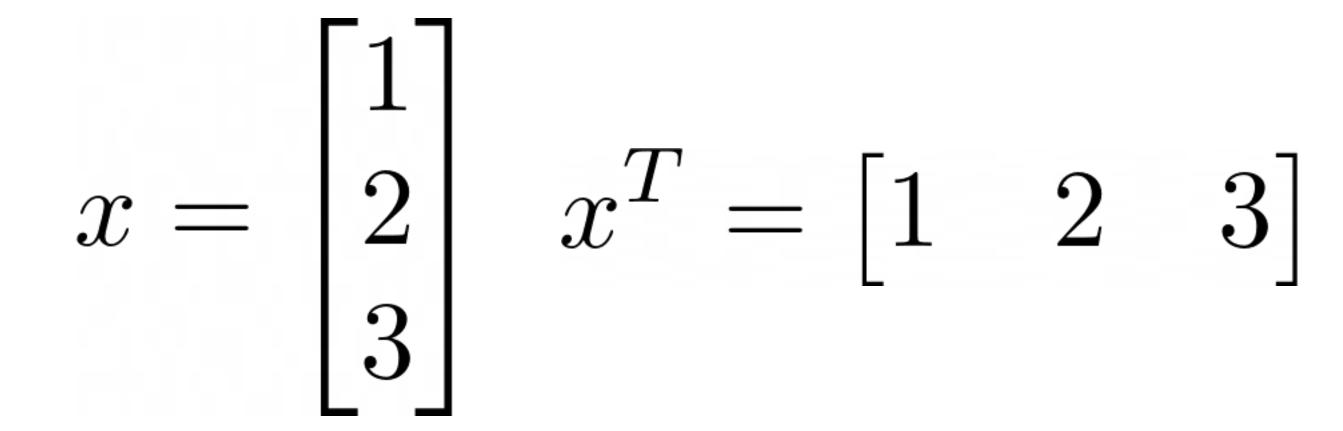


Vectors





- By default, vectors are considered to be *columns*
 - *Transposed* vectors are rows
 - Often visualized as **arrows** or **points** in space

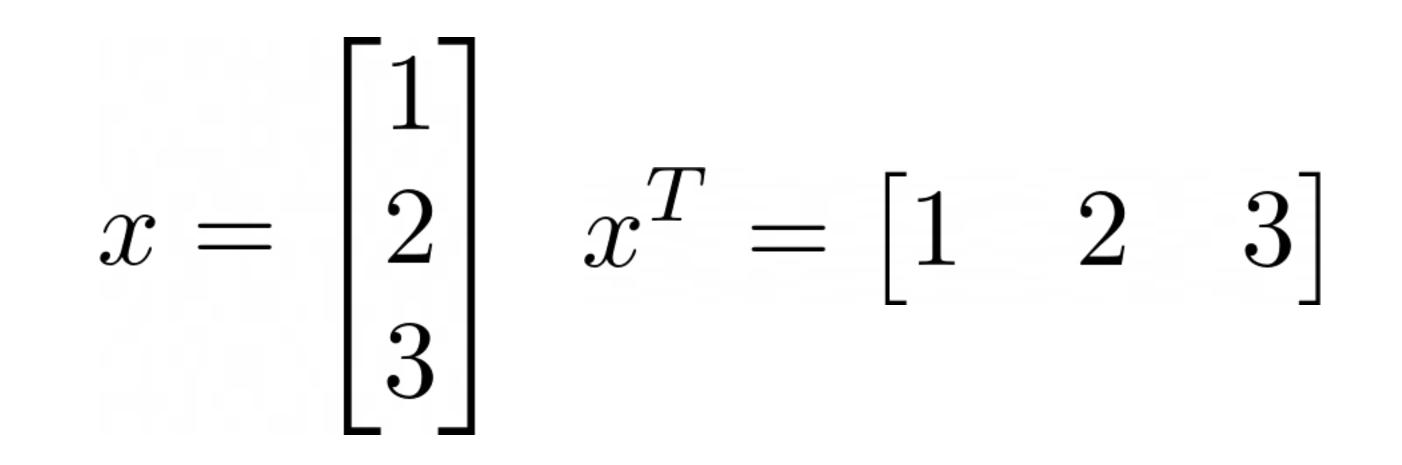


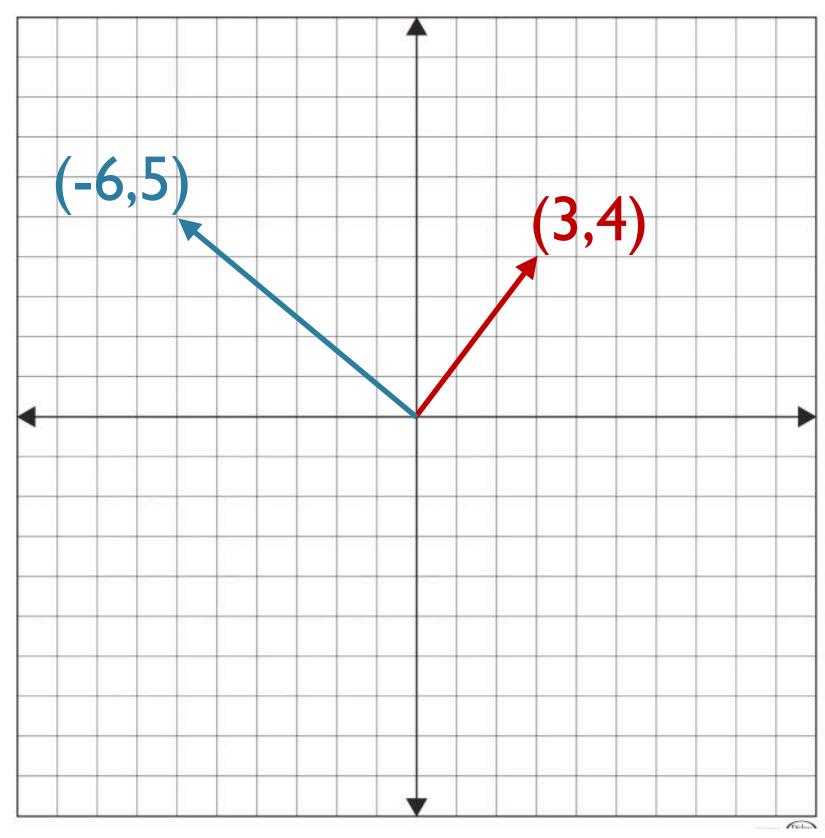






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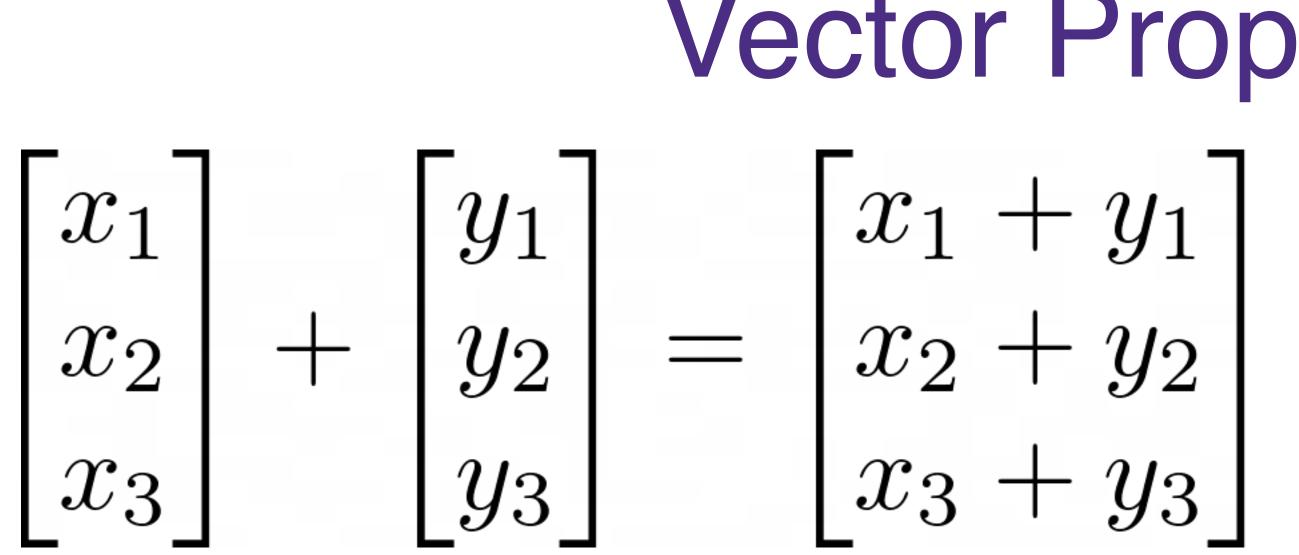


Vector Properties







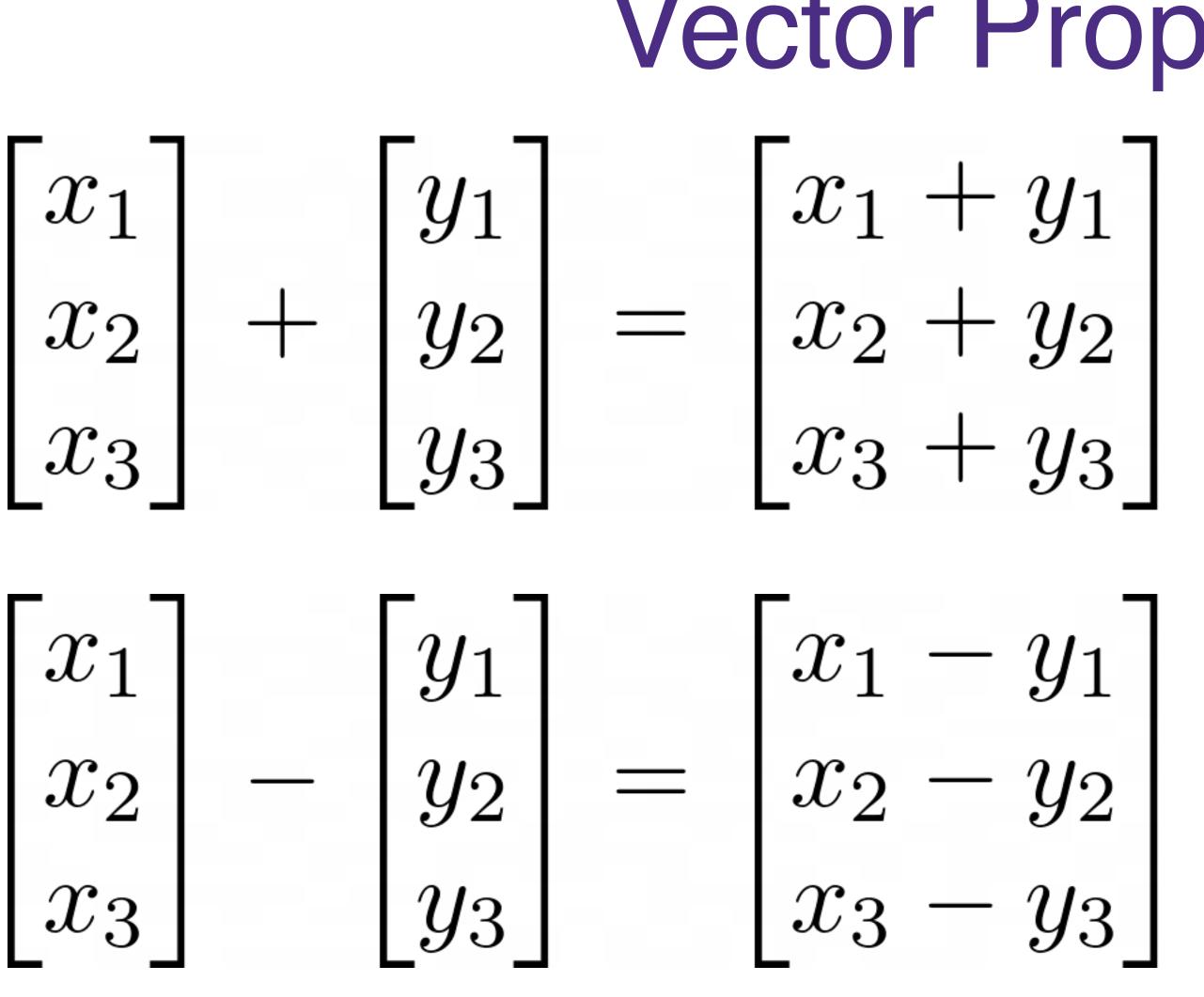


Vector Properties

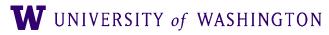






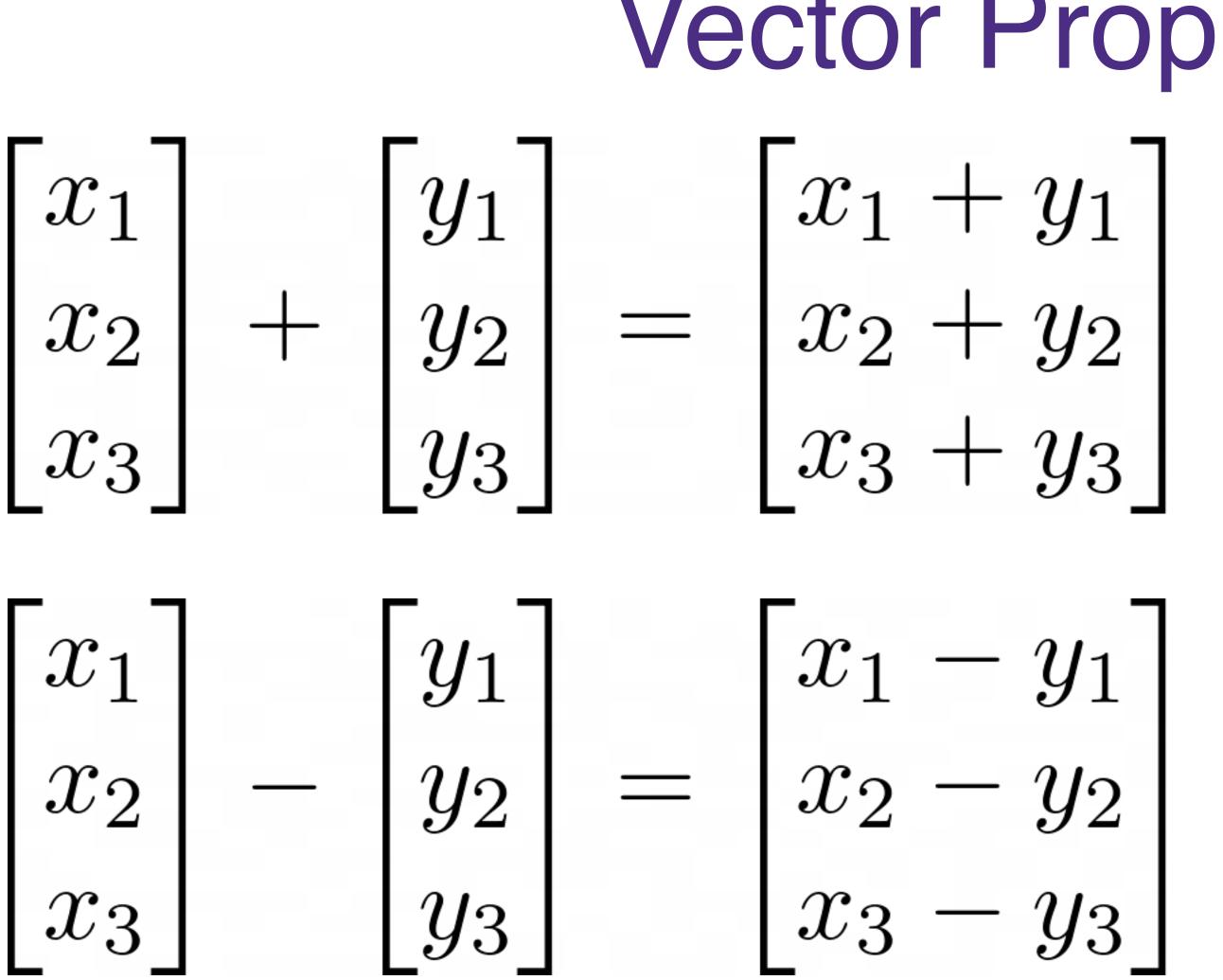


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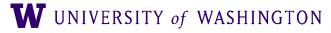








Vector Properties x_1 $C\mathcal{X}_1$ Cx_2 , \boldsymbol{C} x_2 x_3 $x_1 - y_1$ $x_2 - y_2$ (c is a scalar) $y_3 - y_3$







Vector Spans and Spaces







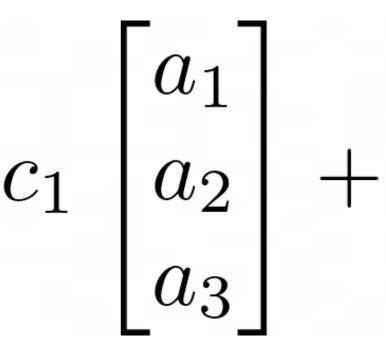
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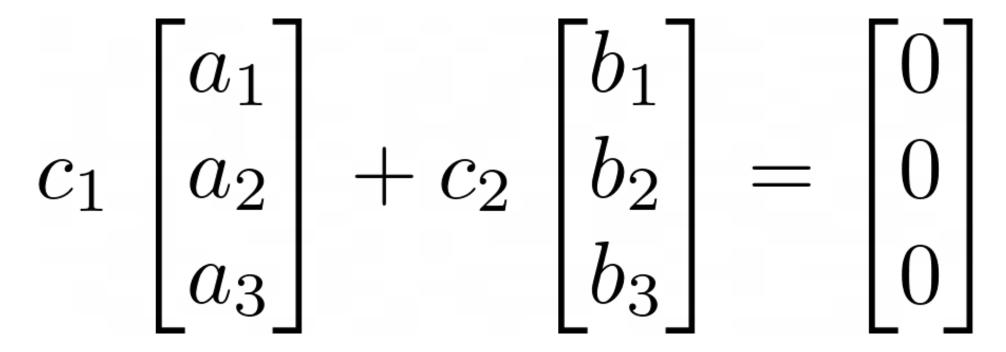




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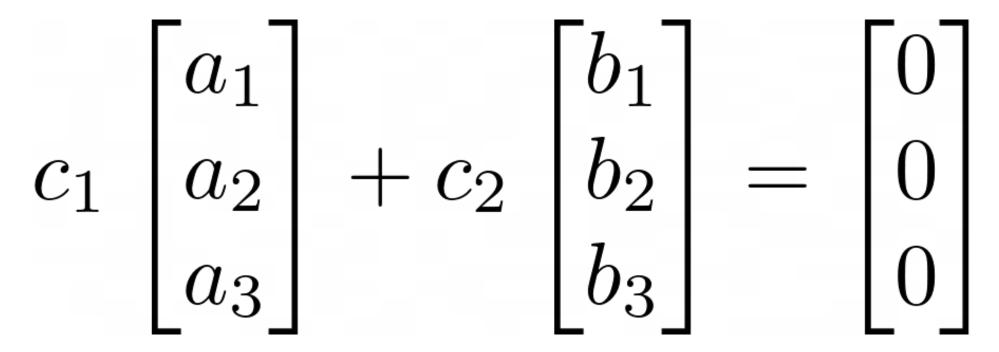






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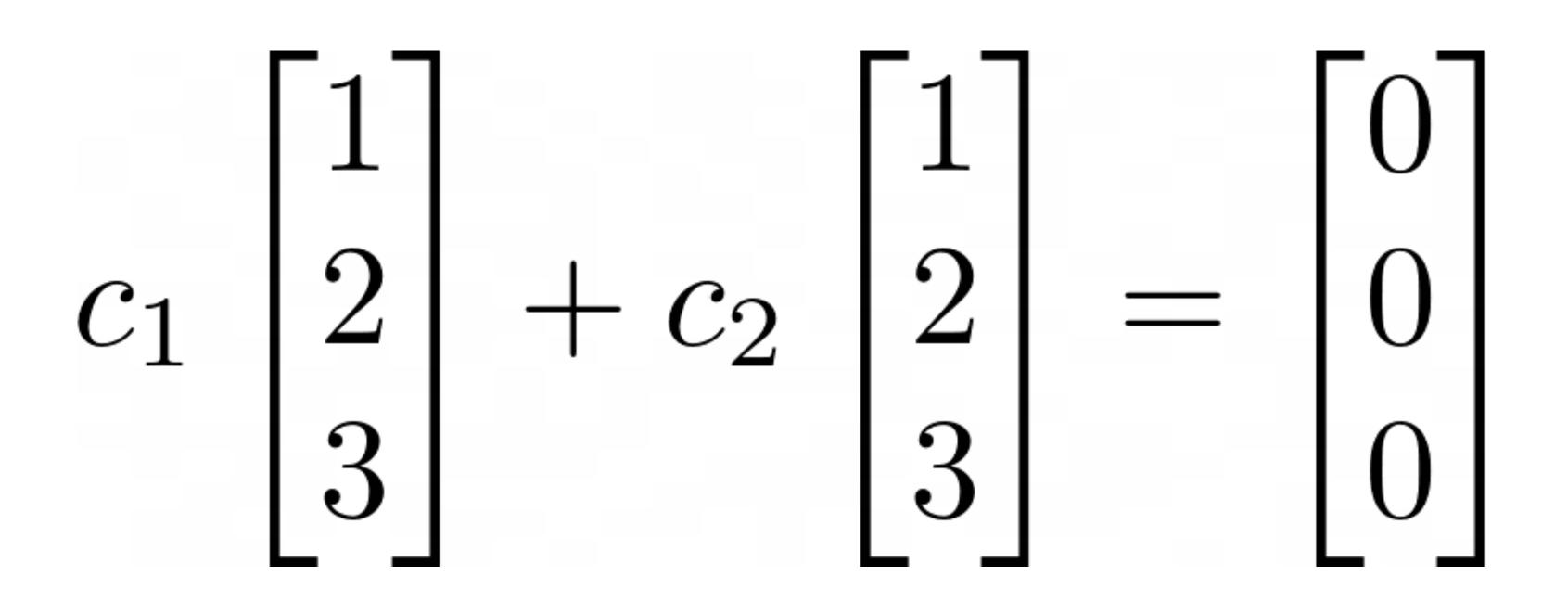
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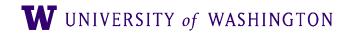
- ...except for $c_1 = c_2 = 0$ (which always gives the zero vector)
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- Definition applies to any number of vectors and constants
- Note: a = 0 is used to indicate a vector of zeros

	b_1		$\begin{bmatrix} 0 \end{bmatrix}$
c_2	b_2	—	0
	b_3		0

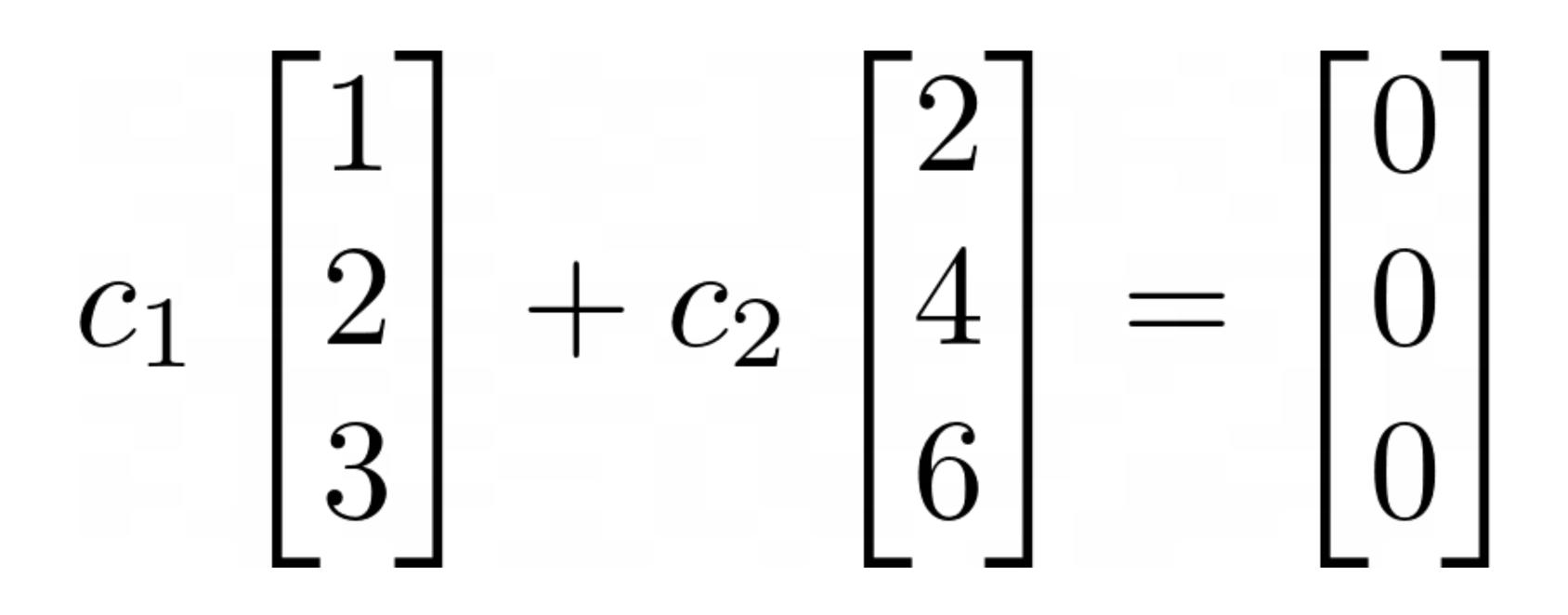






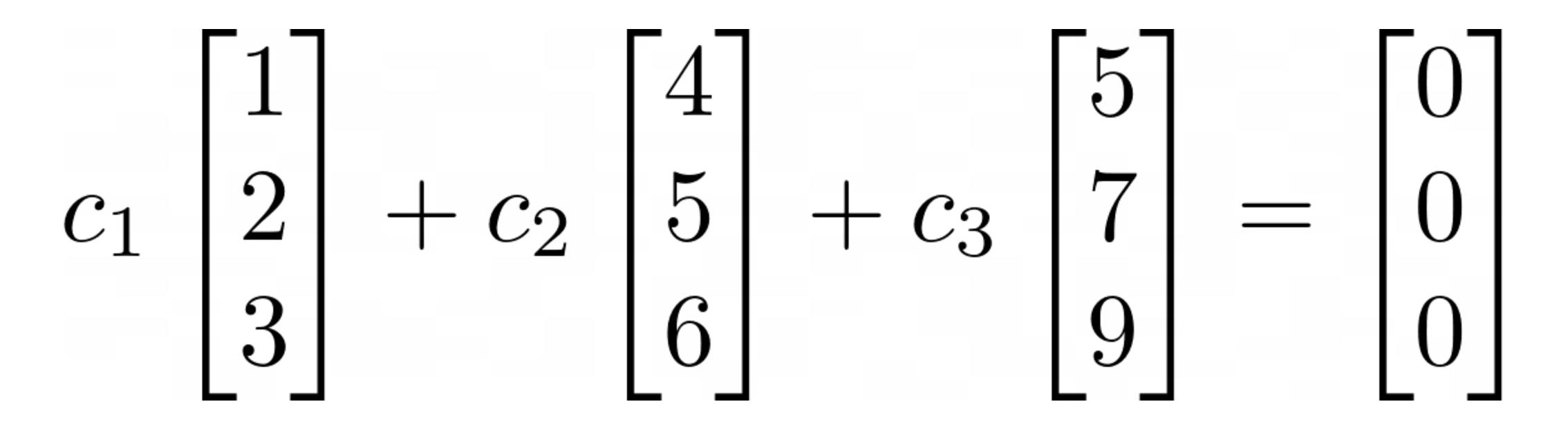


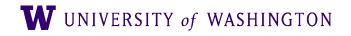






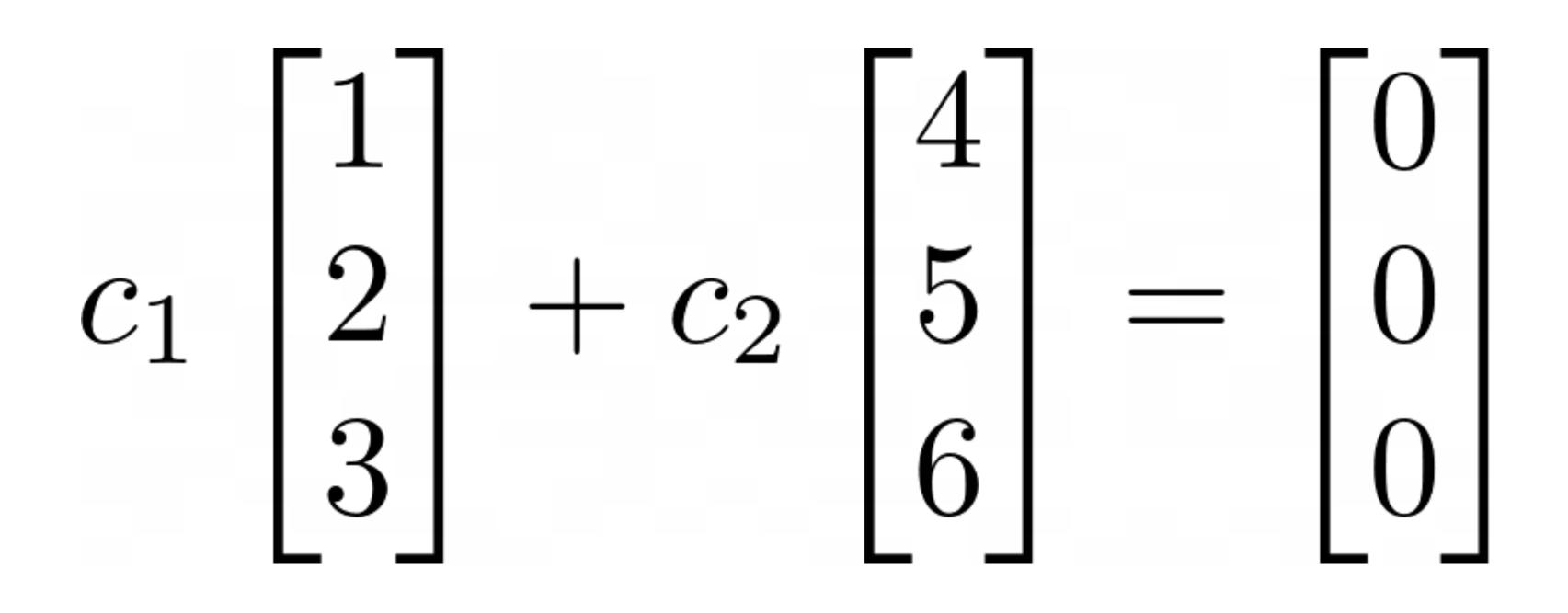


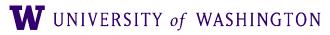




















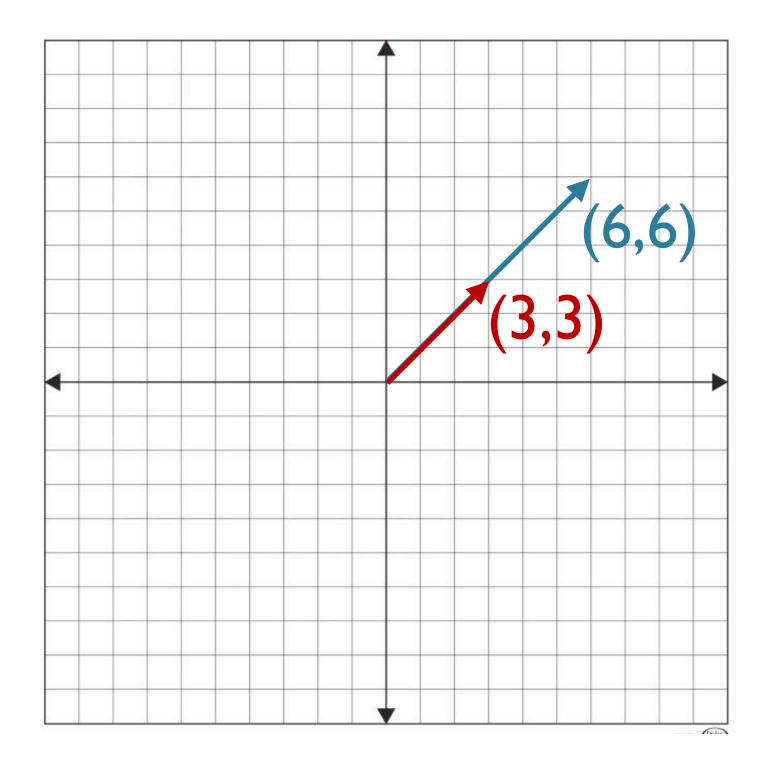
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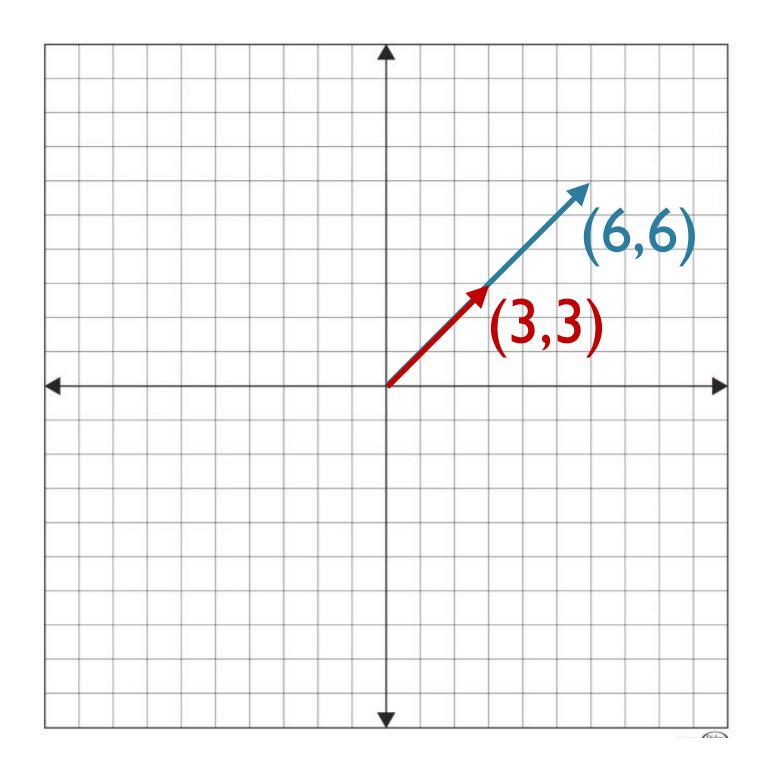








- Vectors are dependent if they are **colinear**
- Non-colinear vectors can also be dependent

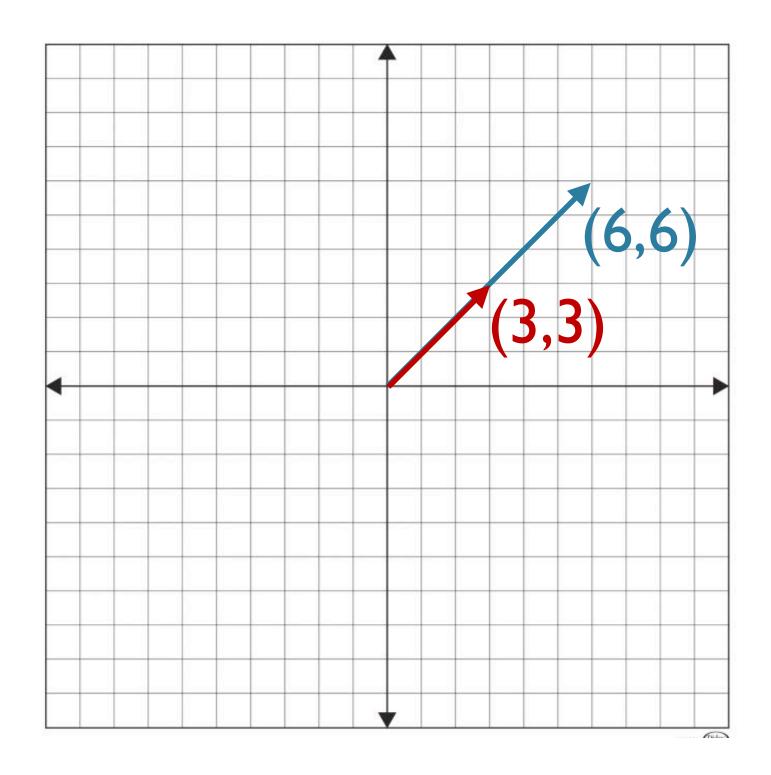




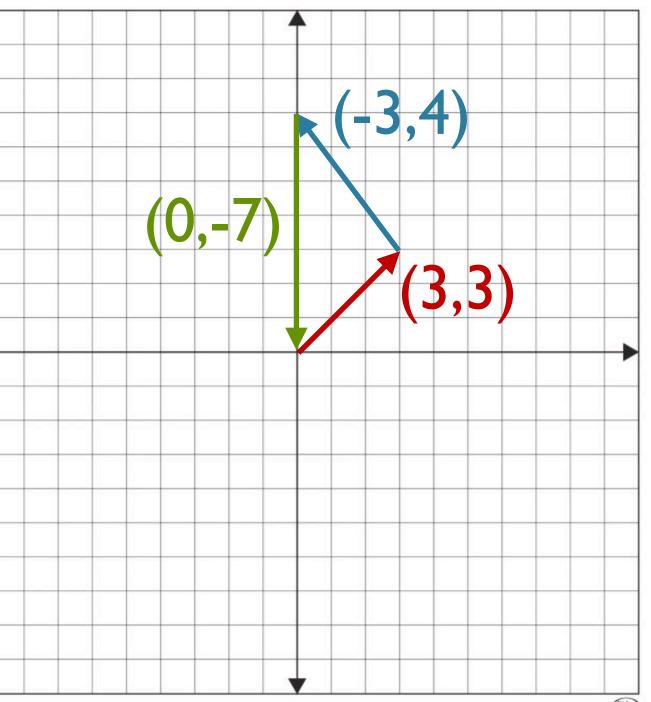




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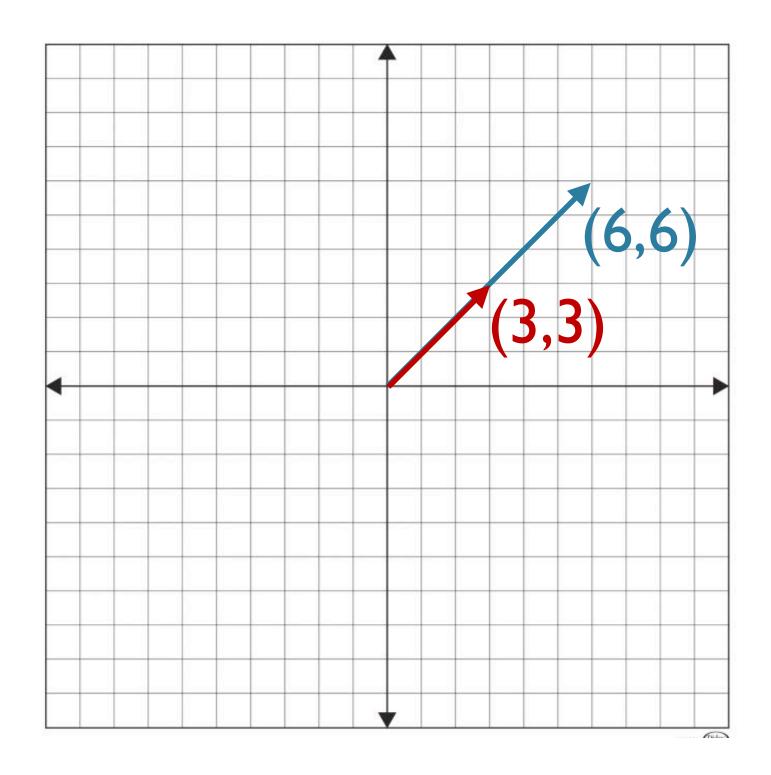




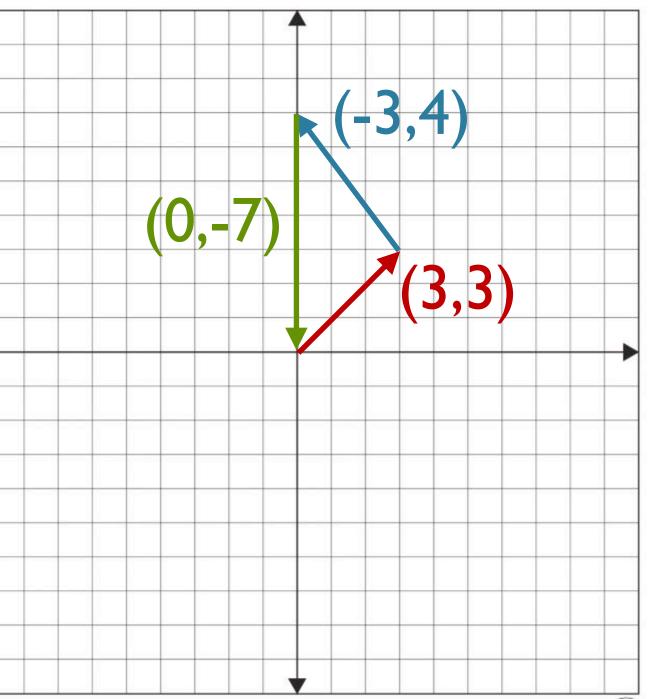




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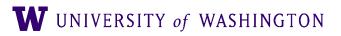
(this is what adding vectors looks like)







Vector Spans











Adding together vectors with different constants is called a linear **combination** of those vectors

Vector Spans











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Vector Spans

• The set of all linear combinations of some vectors is called their span



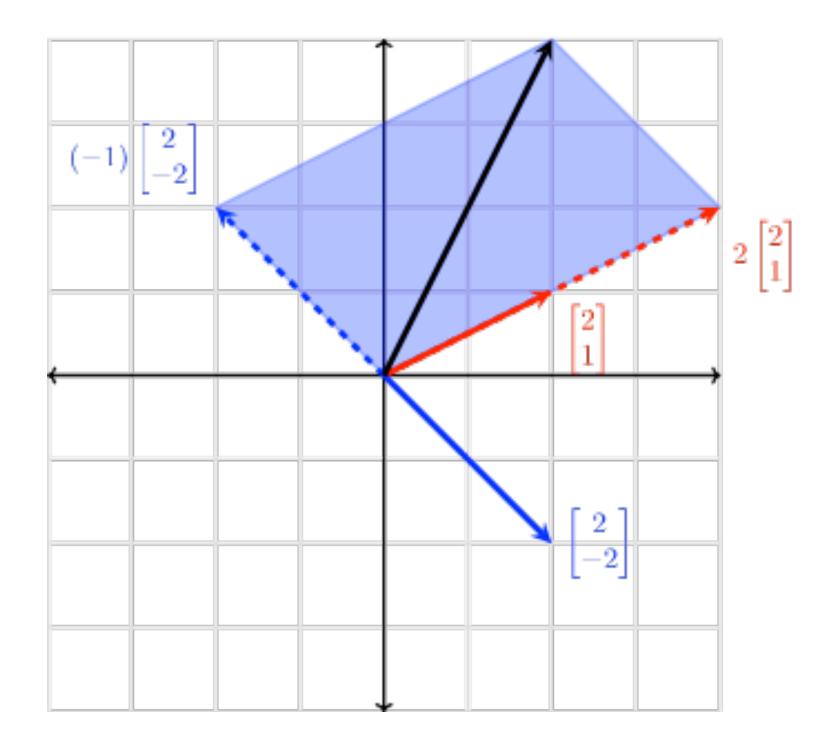




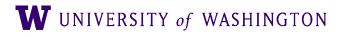


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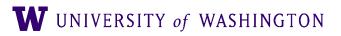


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- The entirety of 1-dimensional space is called R^{\perp}
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 $a = \begin{vmatrix} 1 \\ 2 \\ 3 \end{vmatrix} b = \begin{vmatrix} 4 \\ 5 \\ 6 \end{vmatrix}$



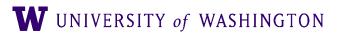


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 - Ex: **a** and **b** above span a **2-D** plane in R^3

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• A set of independent vectors that span a space are called a **basis** for that space







- space
 - The simplest bases for R^2 and R^3 are known as the **Standard Basis**:

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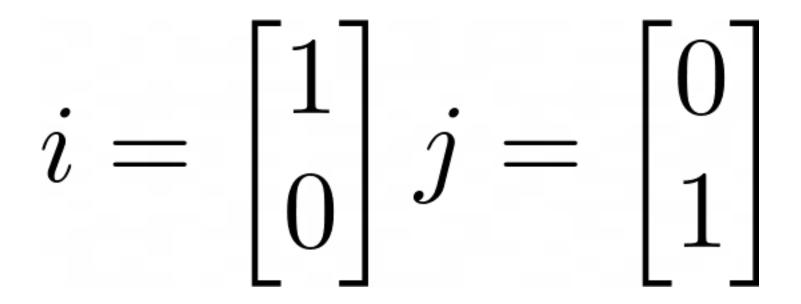






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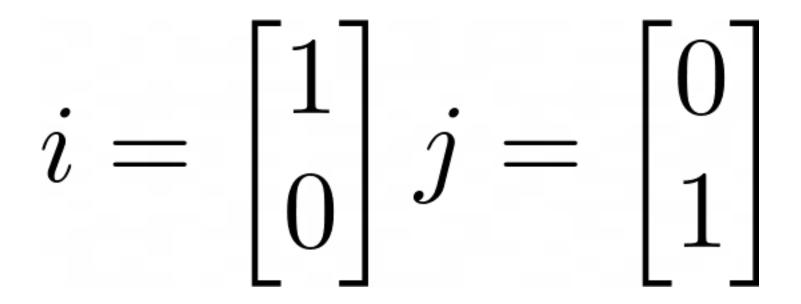




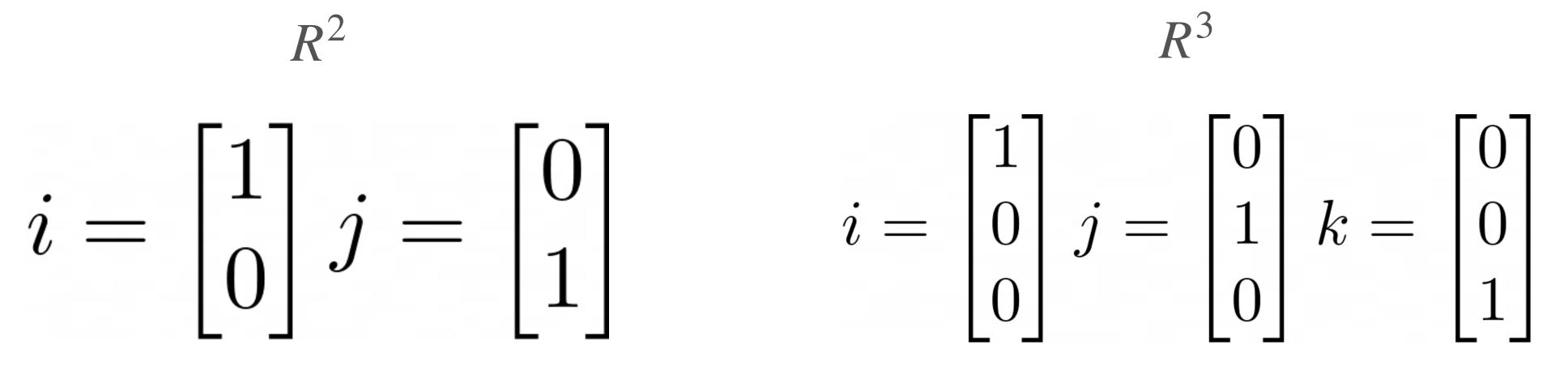


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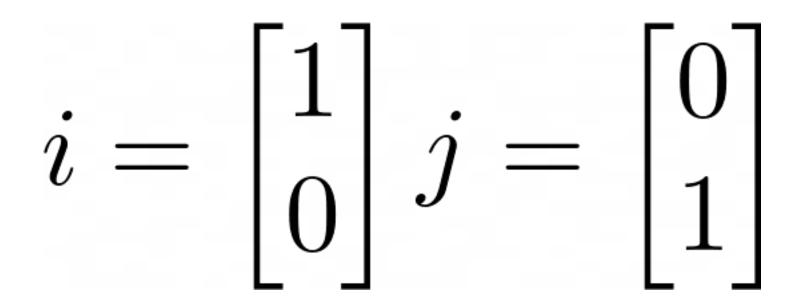






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 - These are not the only bases for these spaces

$$R^2$$



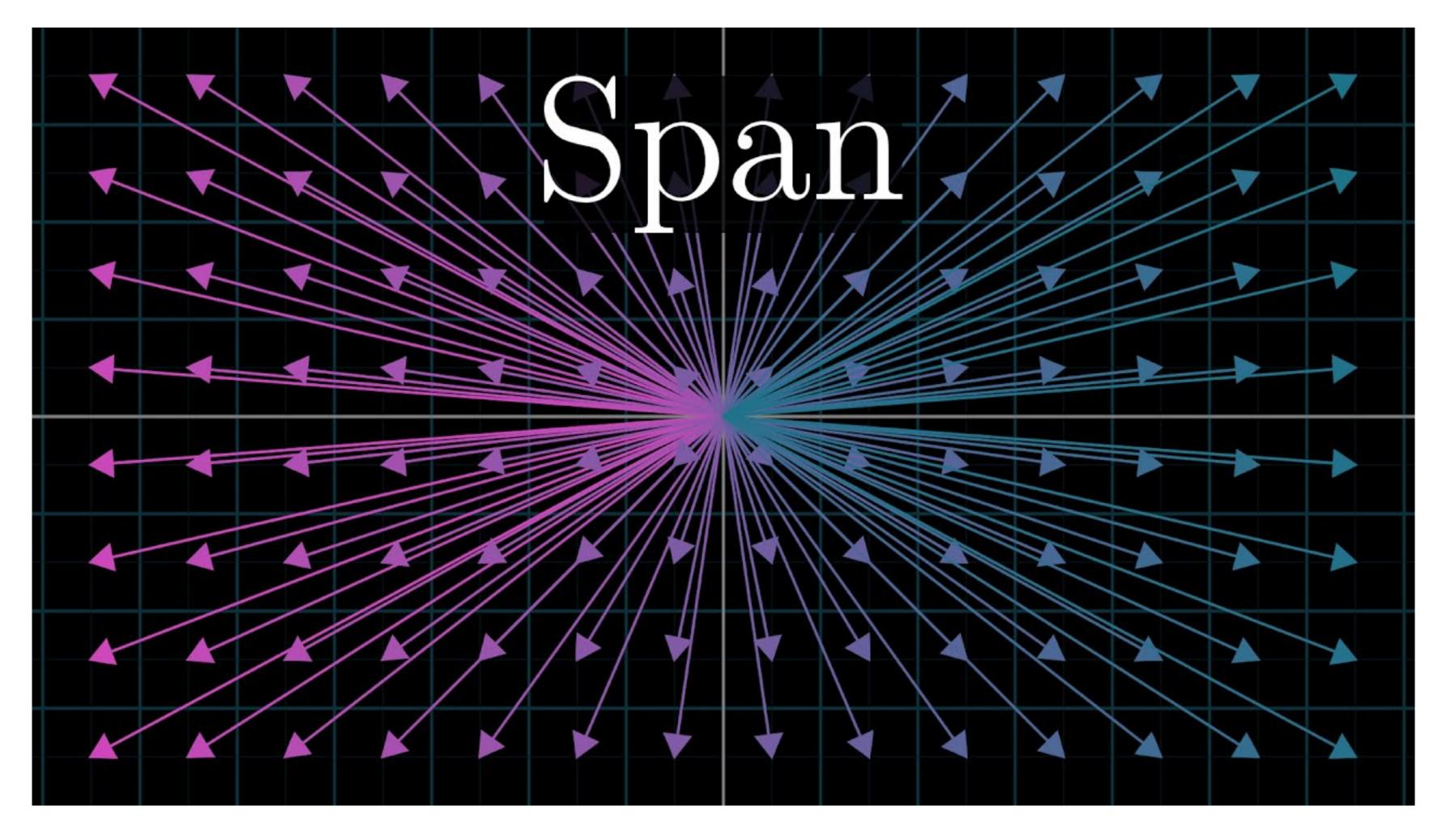
• A set of independent vectors that span a space are called a **basis** for that

 R^3 $i = \begin{vmatrix} 1 \\ 0 \end{vmatrix} j = \begin{vmatrix} 0 \\ 1 \end{vmatrix} \qquad i = \begin{vmatrix} 1 \\ 0 \\ 0 \end{vmatrix} j = \begin{vmatrix} 0 \\ 1 \\ 0 \end{vmatrix} k = \begin{vmatrix} 0 \\ 0 \\ 1 \end{vmatrix}$





Span Video

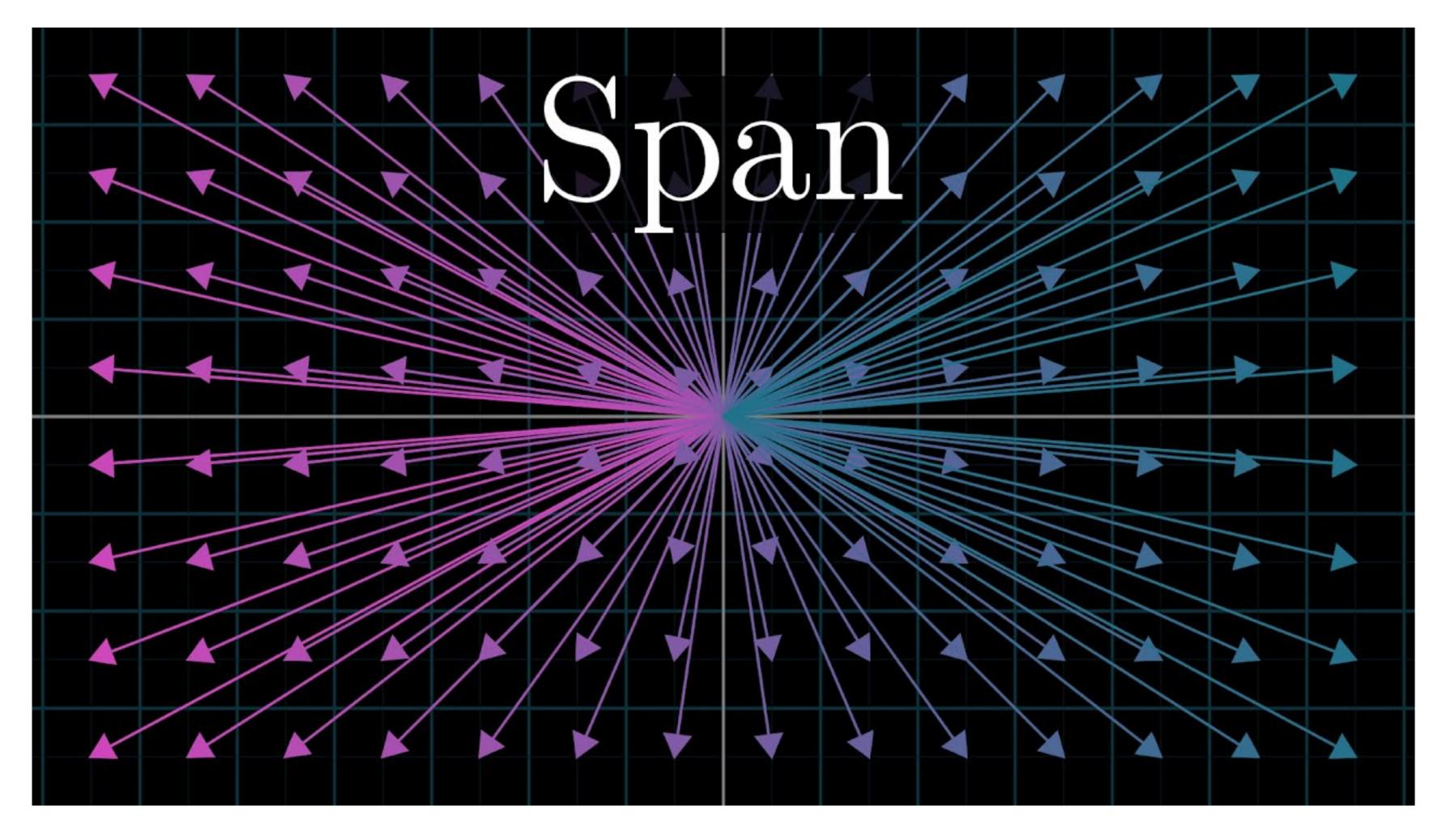


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Span Video



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Matrix Multiplication



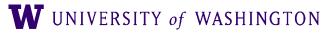






Quick reminder: Dot Product

$a \cdot b = a^T b = a_1 b_1 + a_2 b_2 \dots + a_n b_n$









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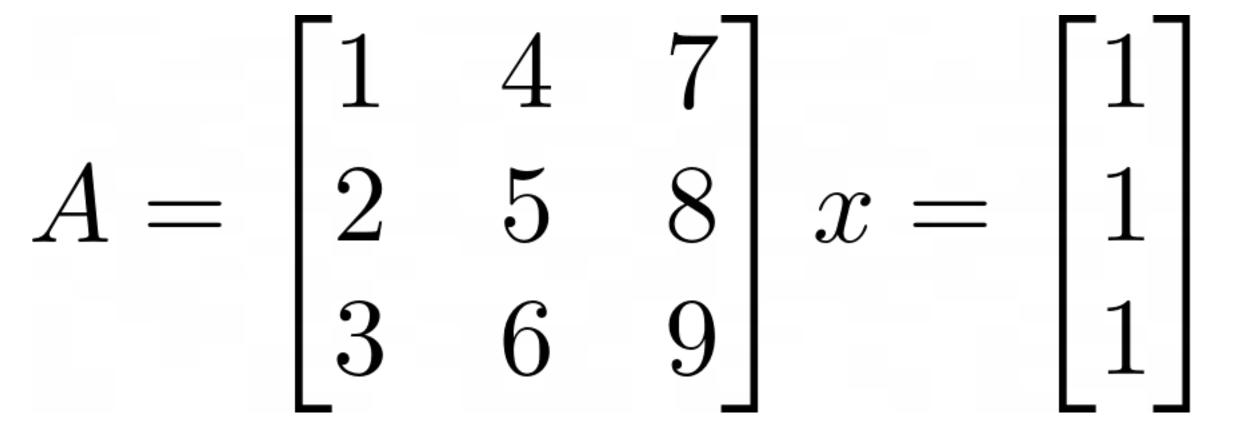
(vectors need to be the same length)







Matrix-Vector Multiplication



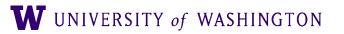
Ax = ?

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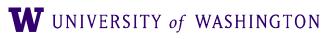
• Matrix multiplication is **not** commutative: $Ax \neq xA$







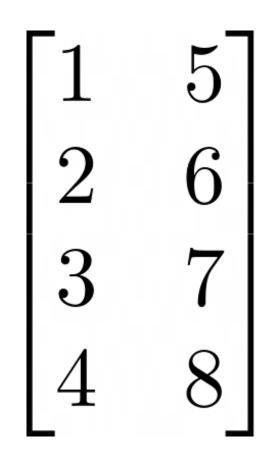
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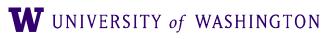






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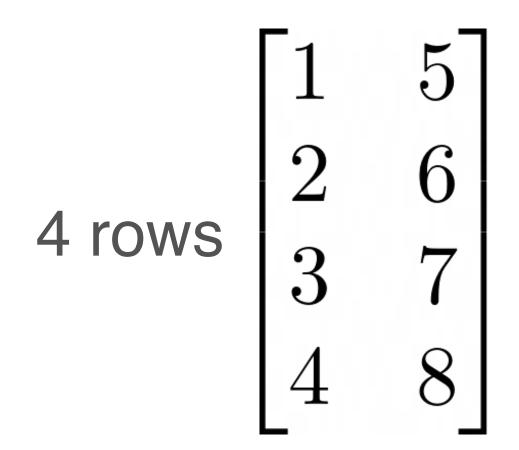








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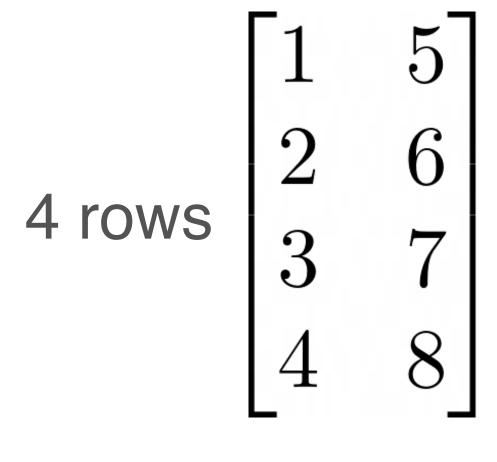








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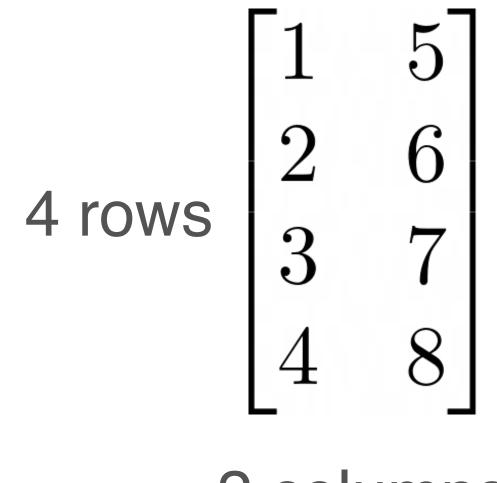
2 columns







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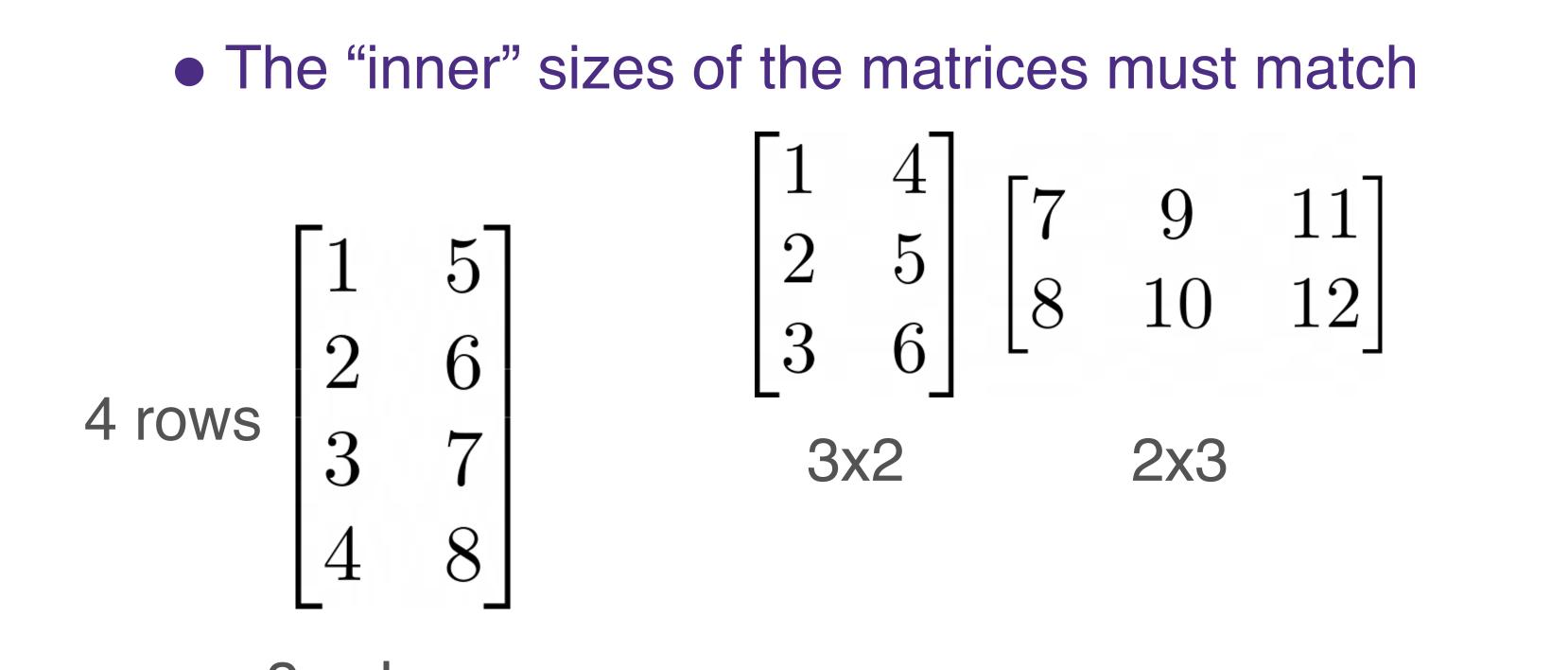
"4x2 matrix"







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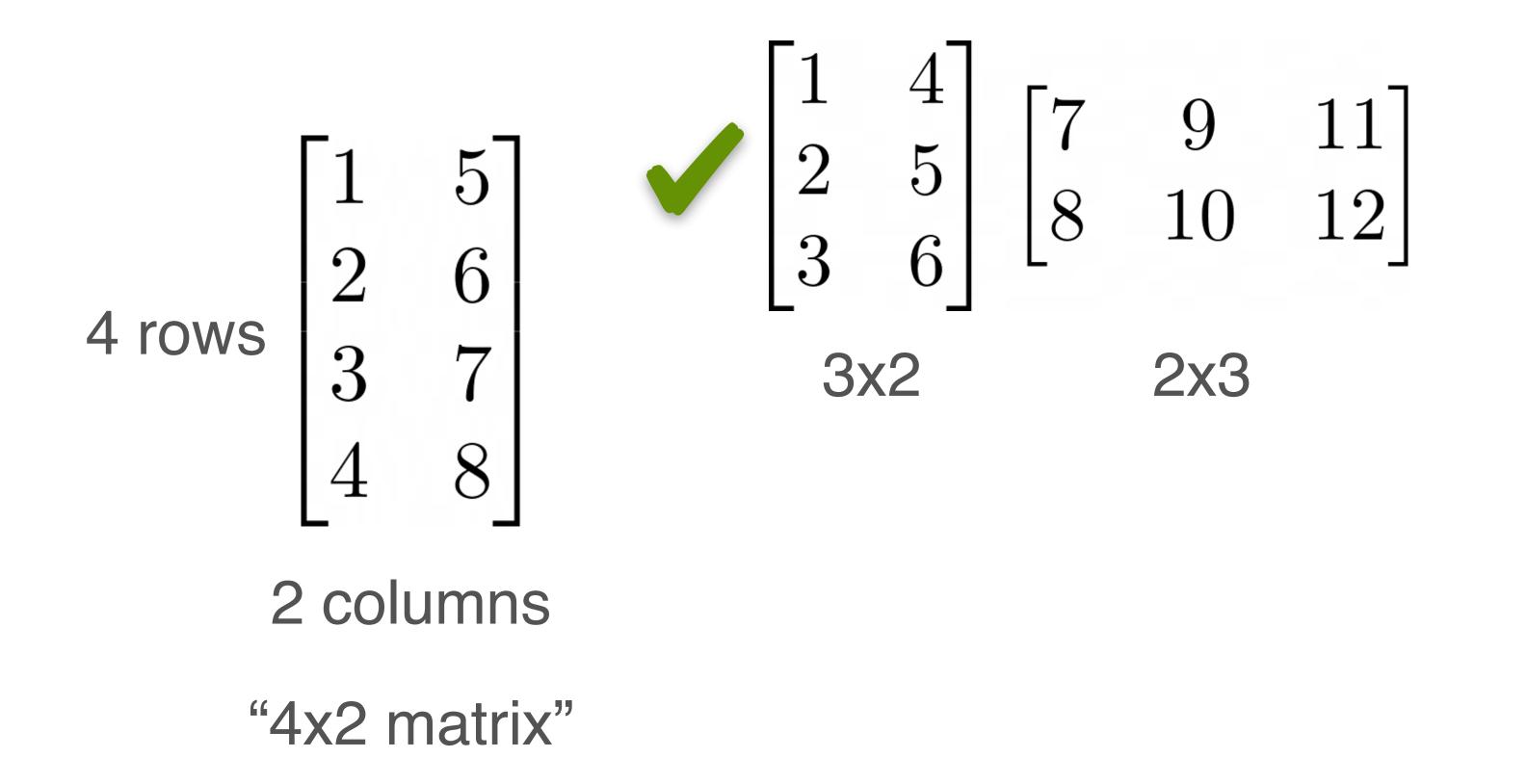
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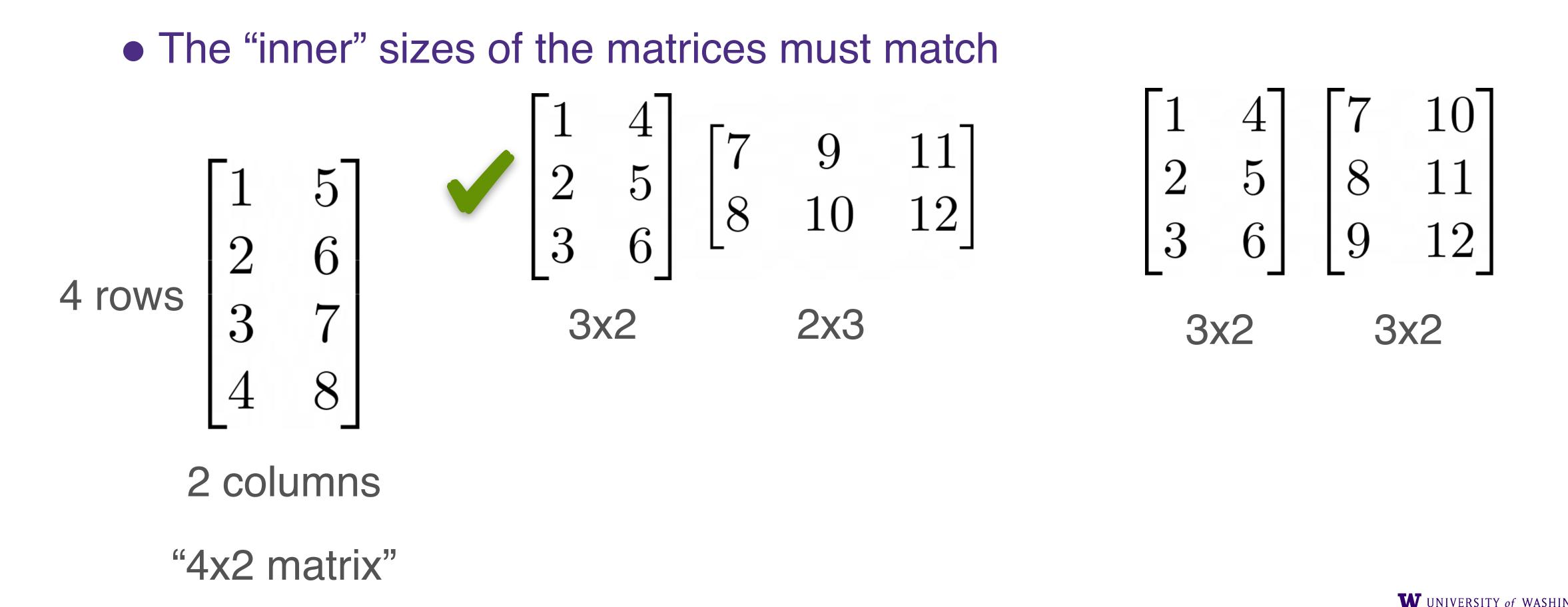


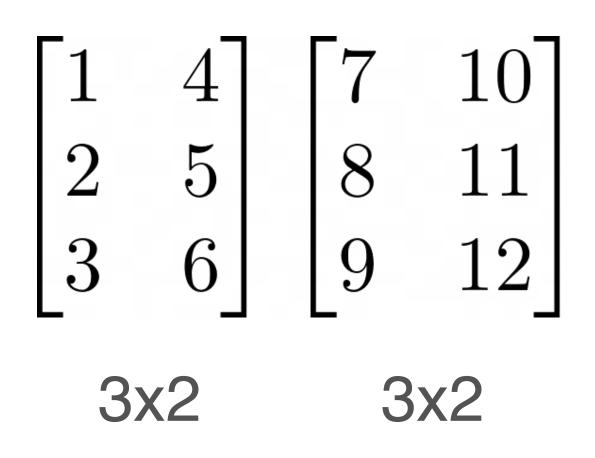






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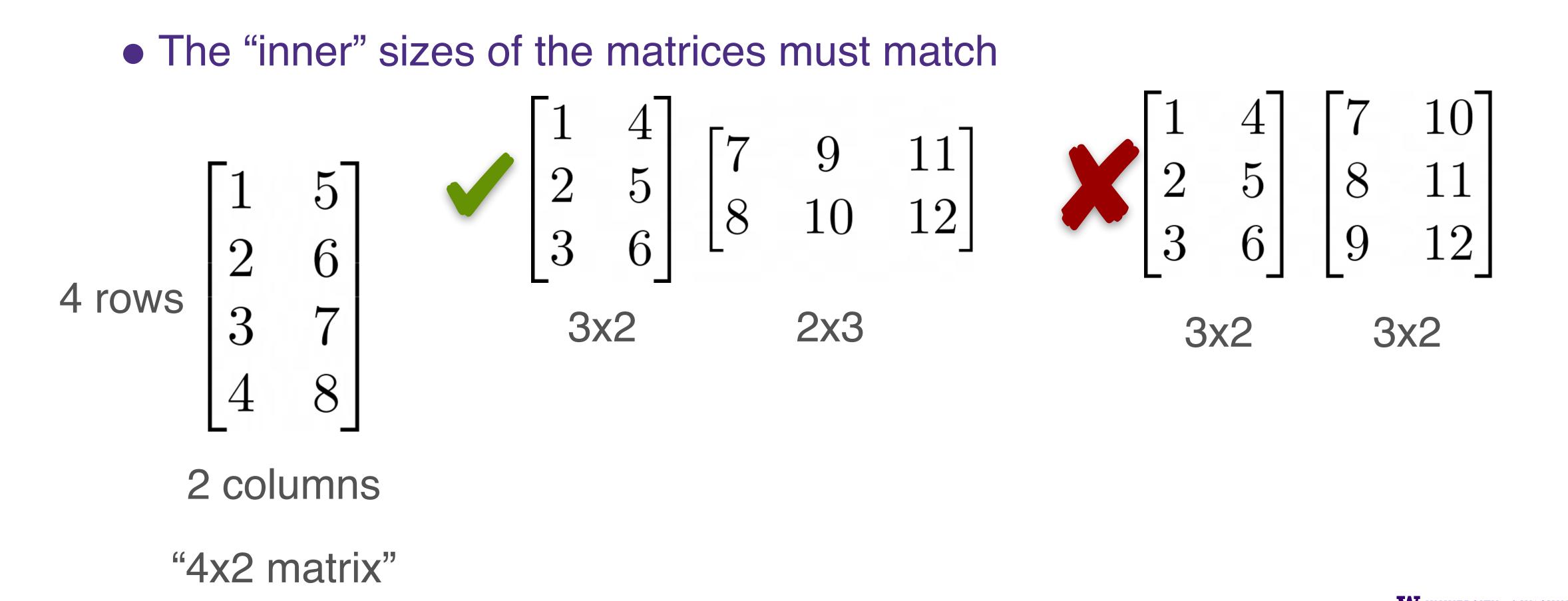


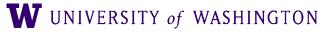






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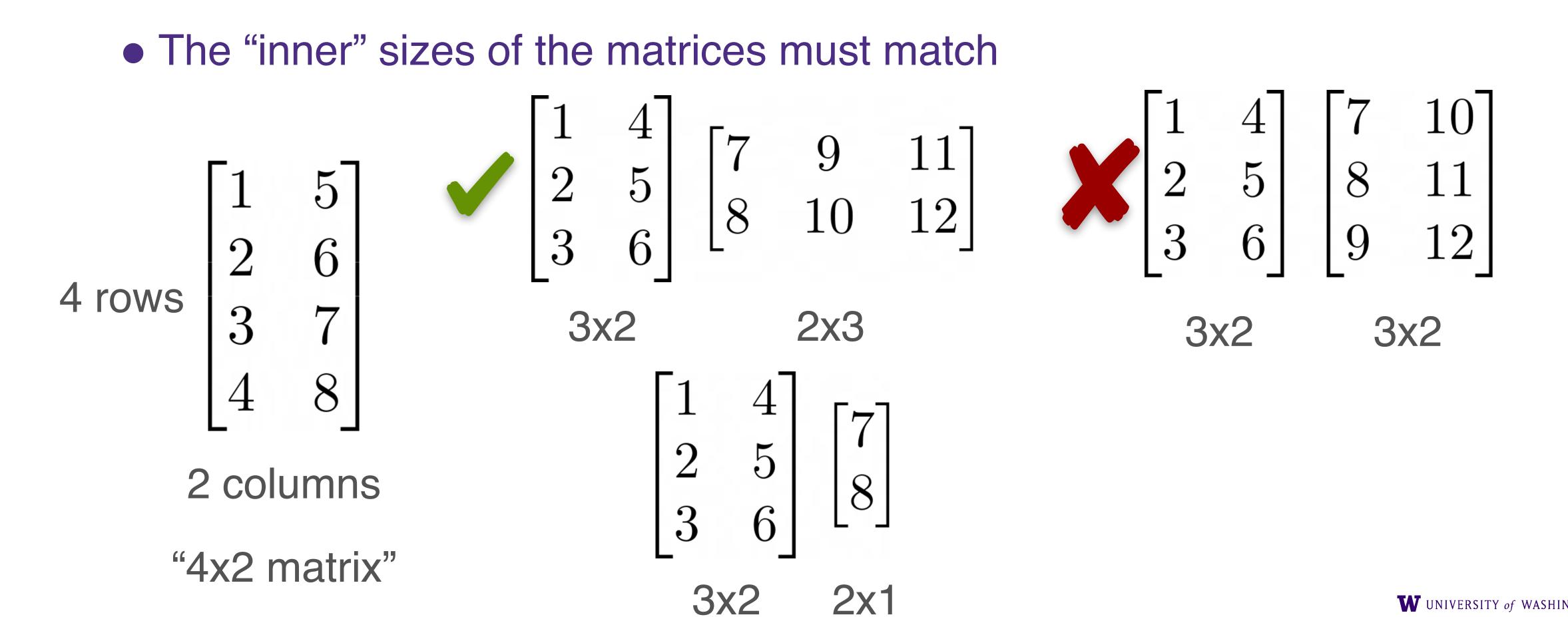








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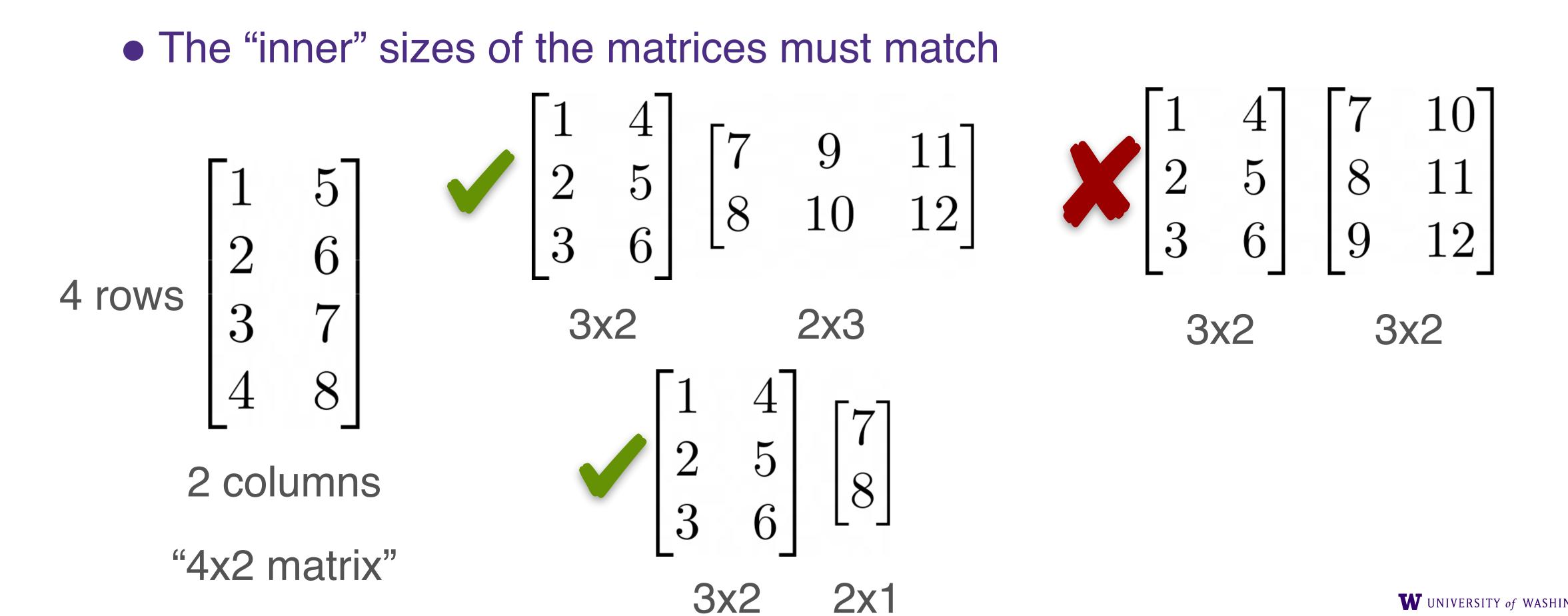


$$\begin{bmatrix} 7\\ 8 \end{bmatrix}$$





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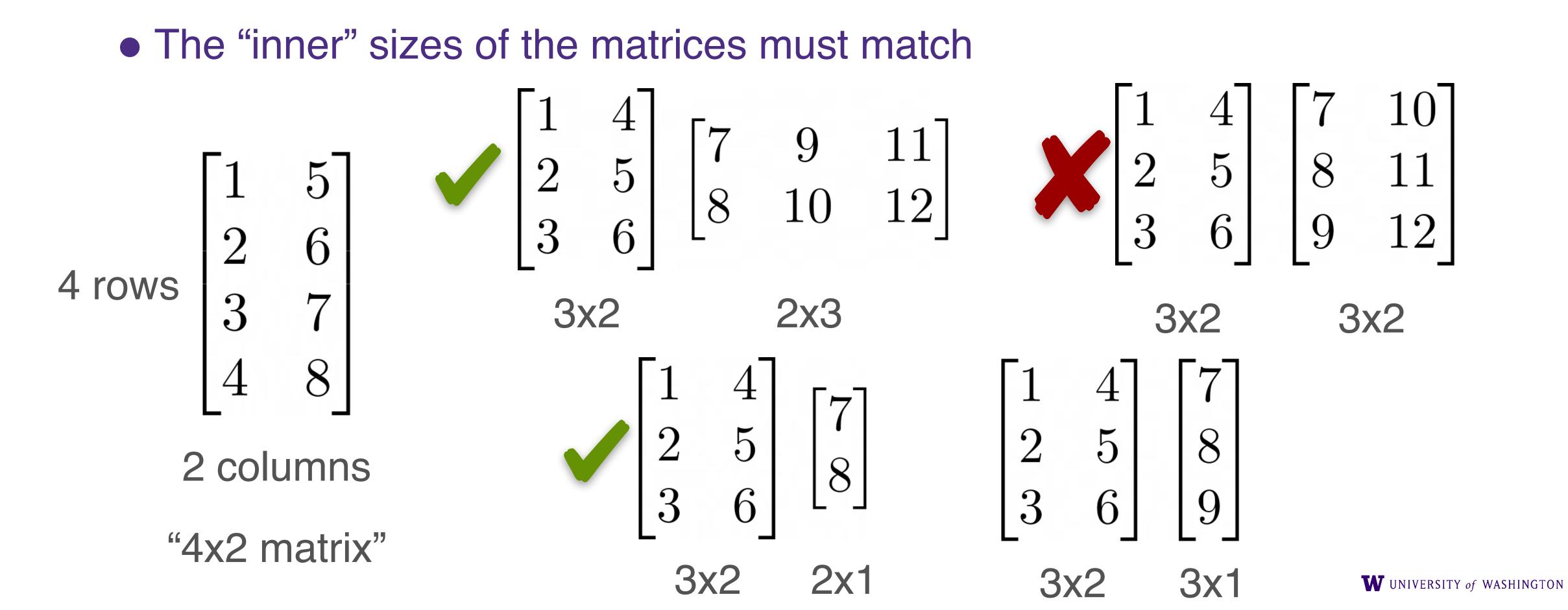


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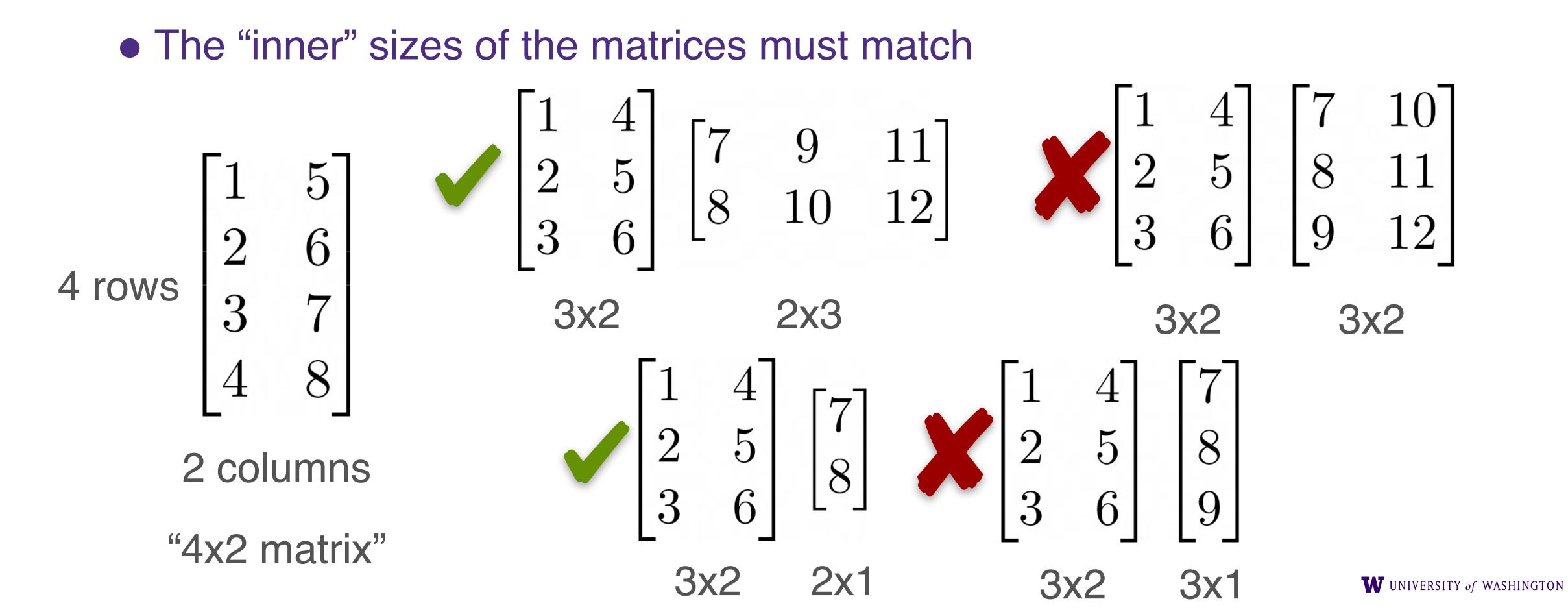
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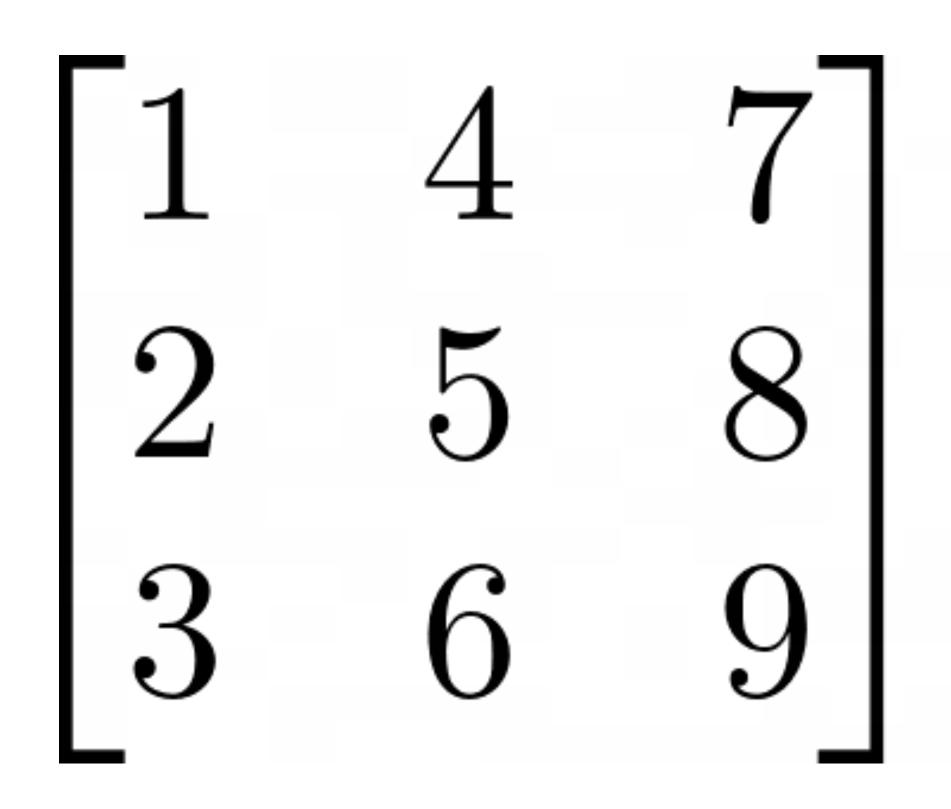


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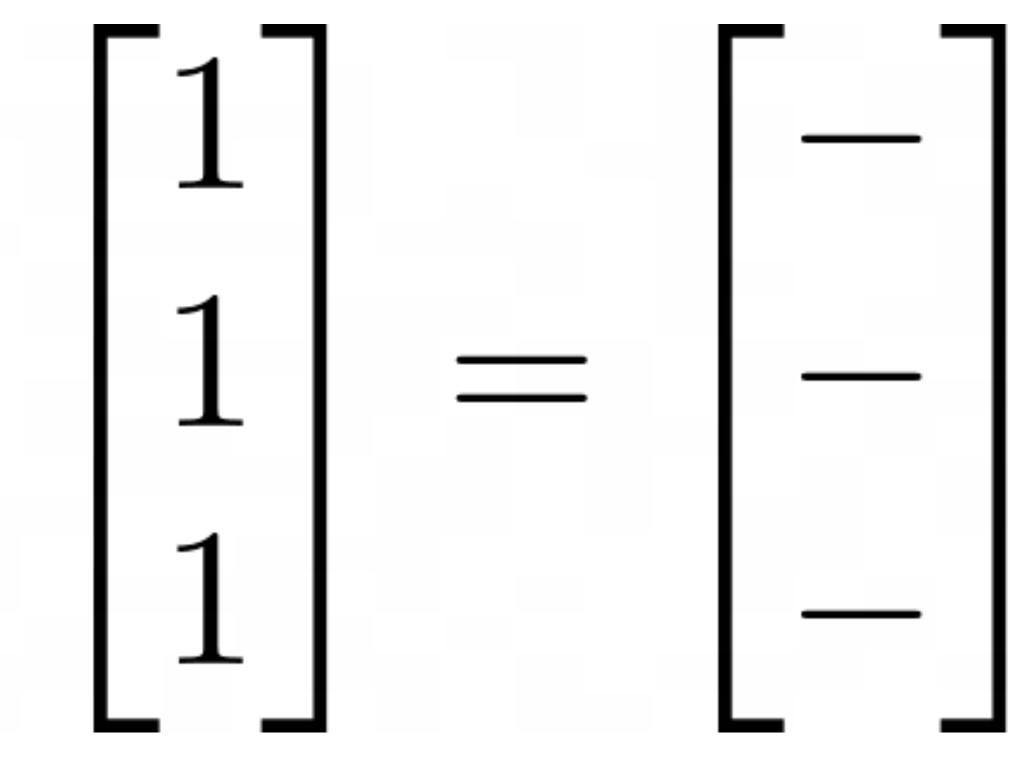








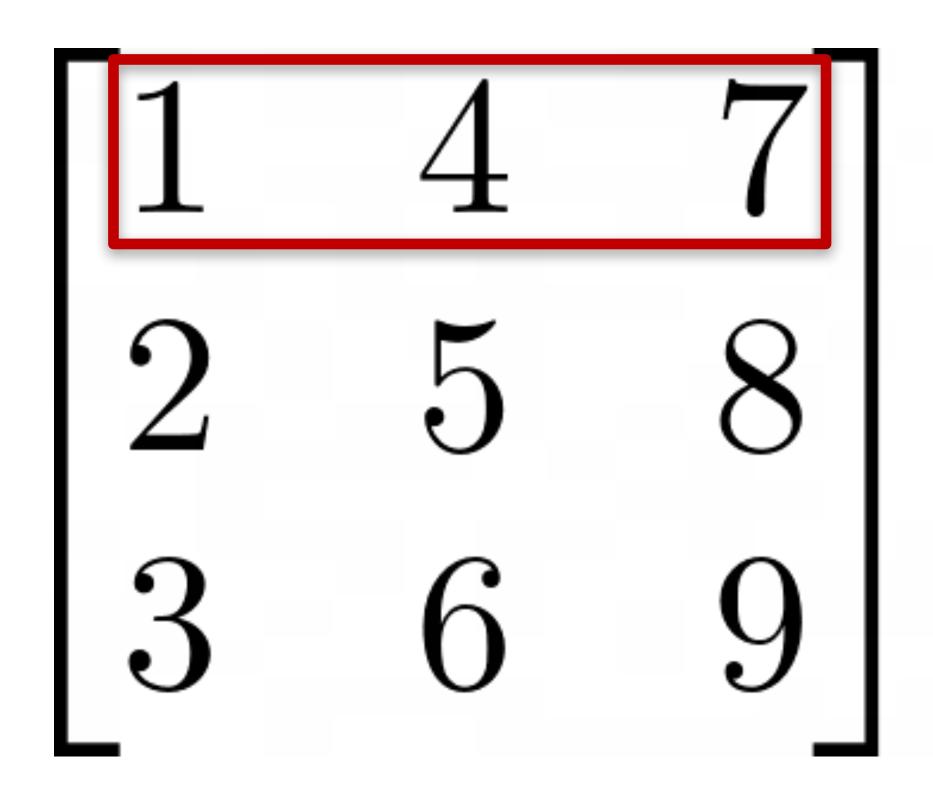
The Traditional Way

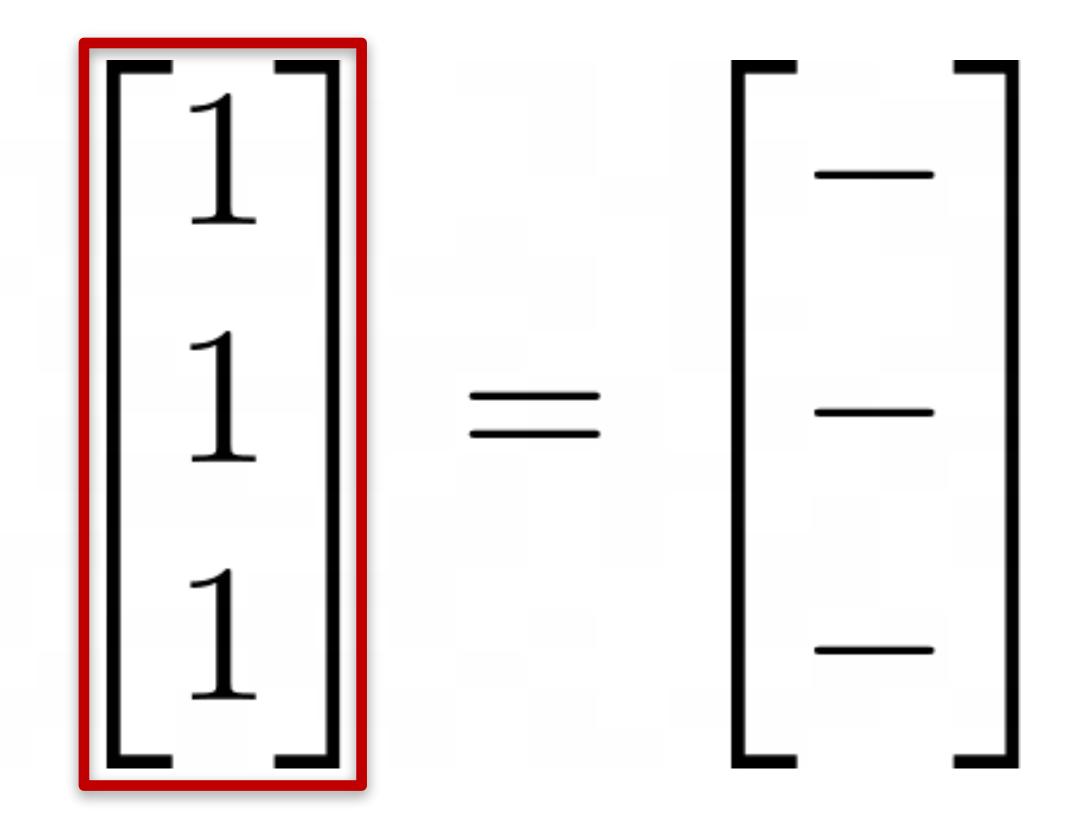


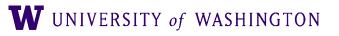




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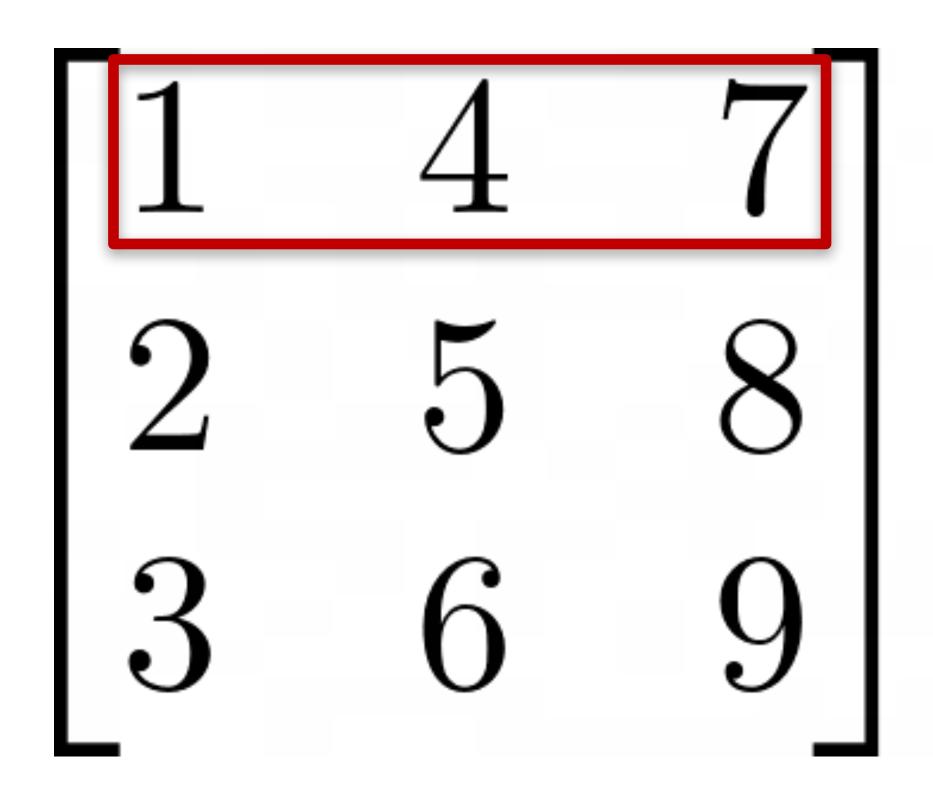


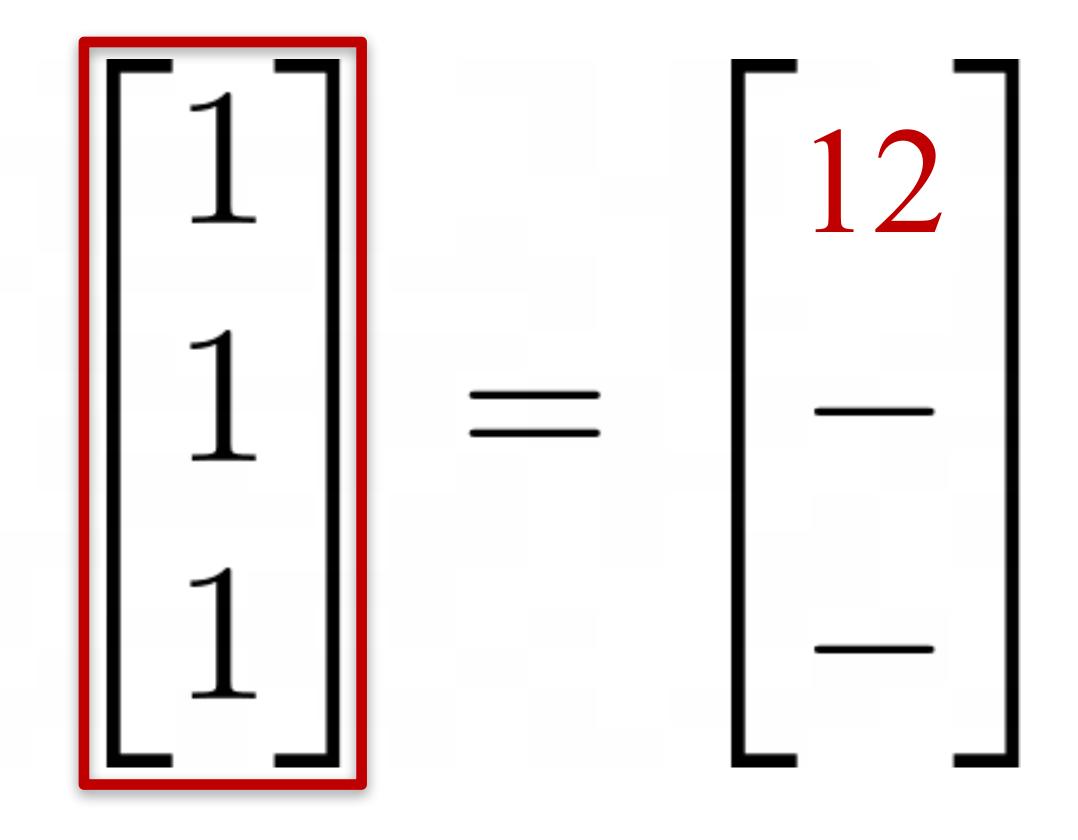






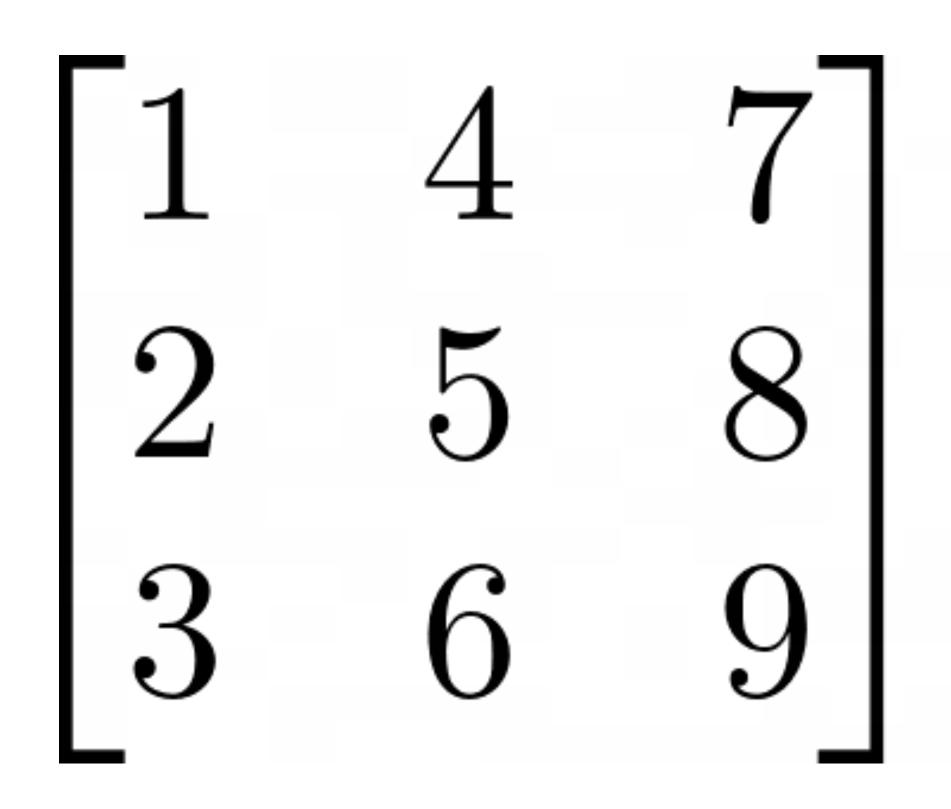
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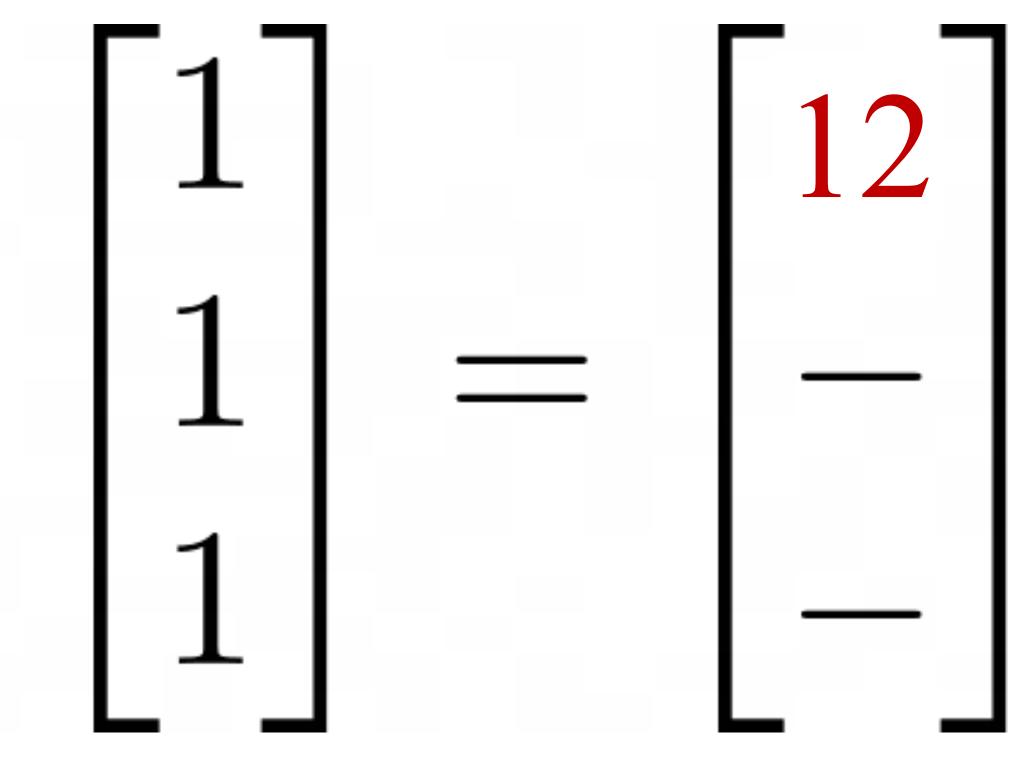






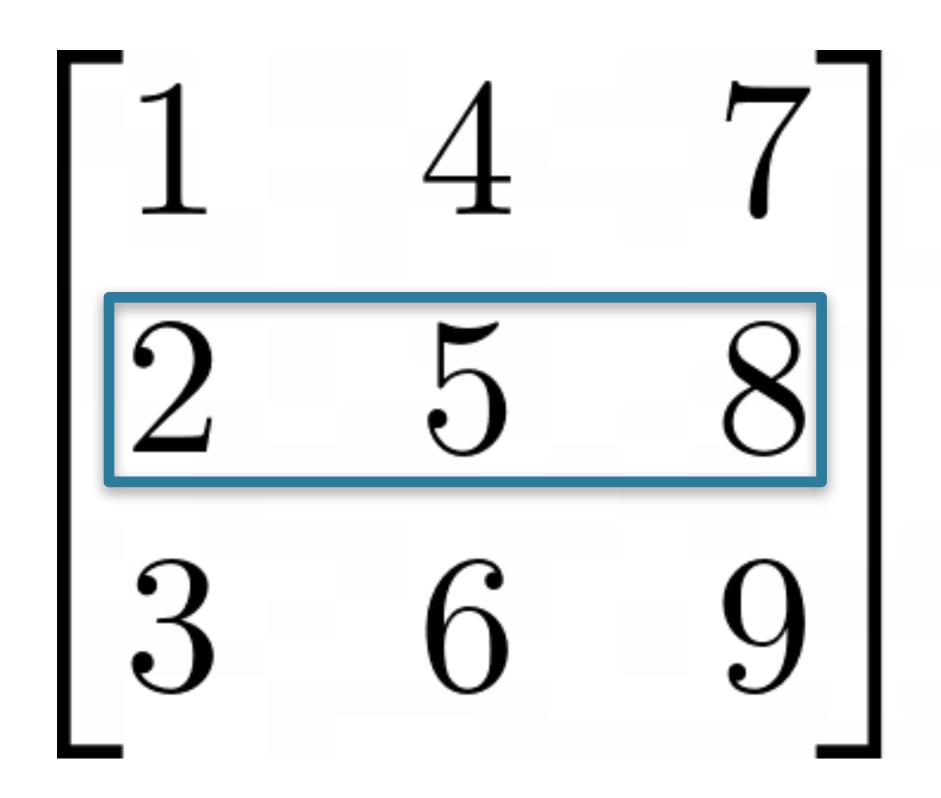


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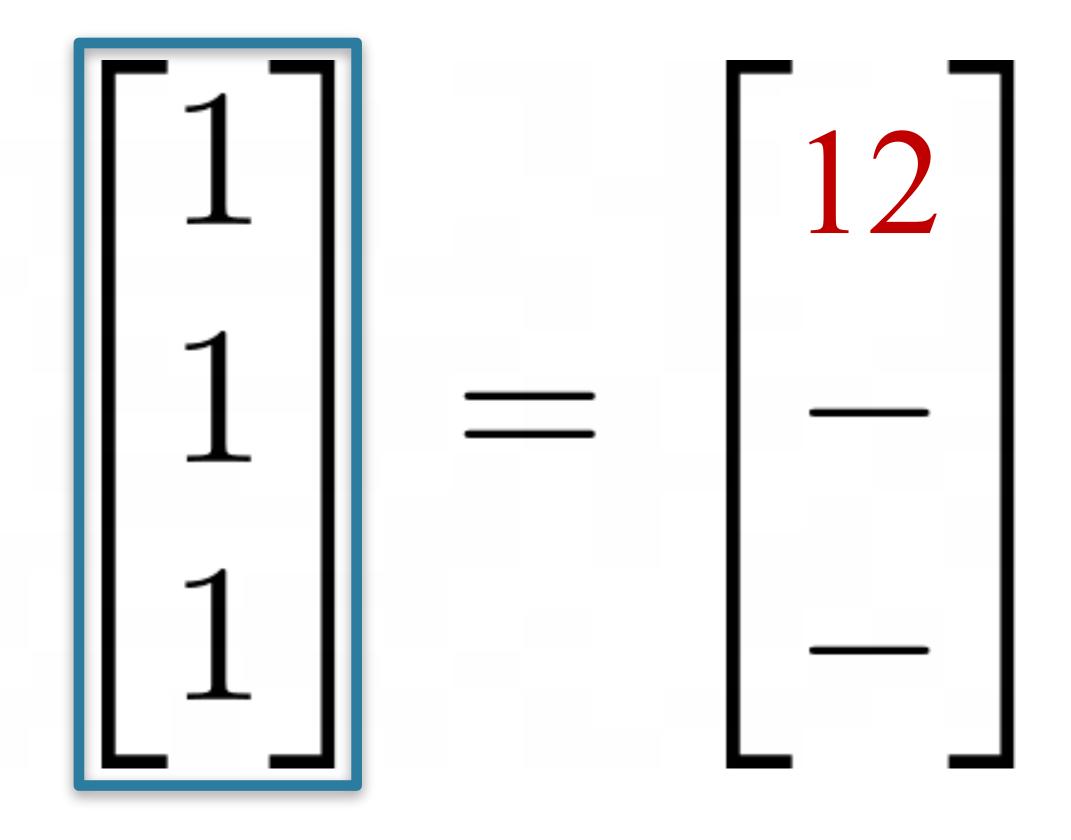






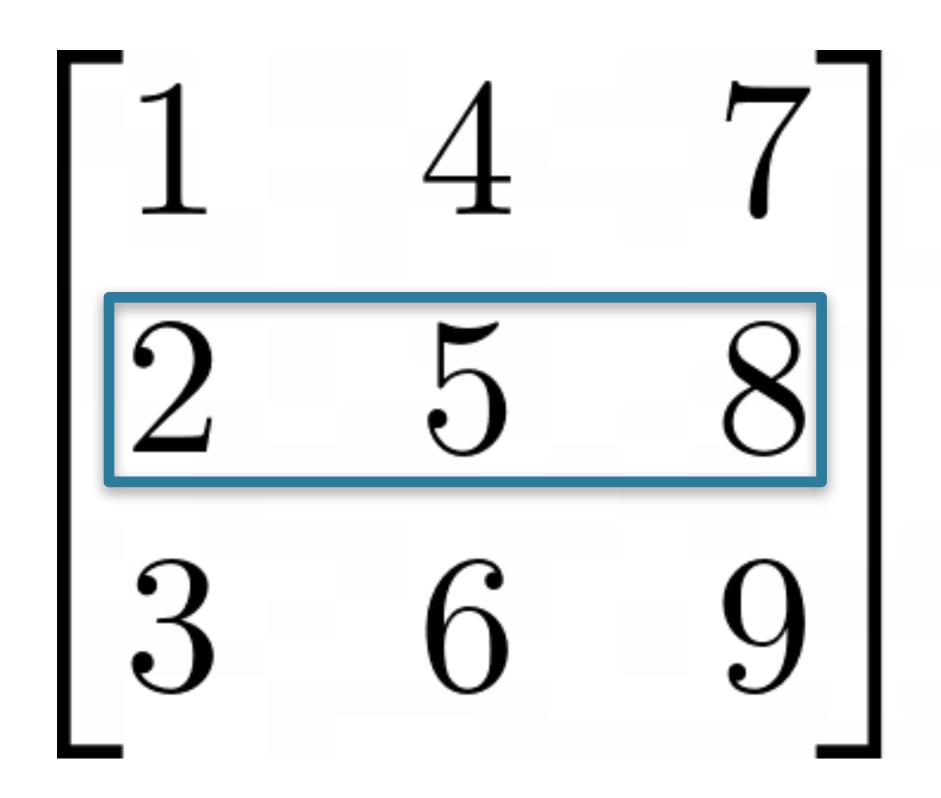


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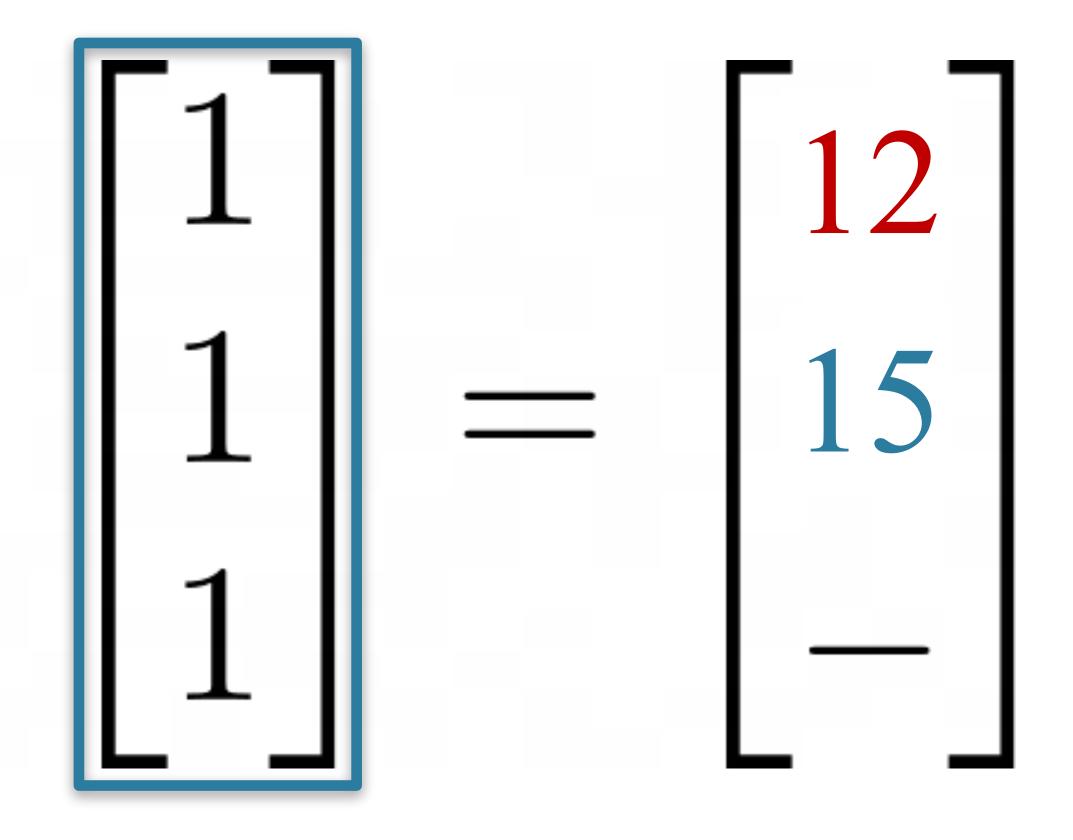






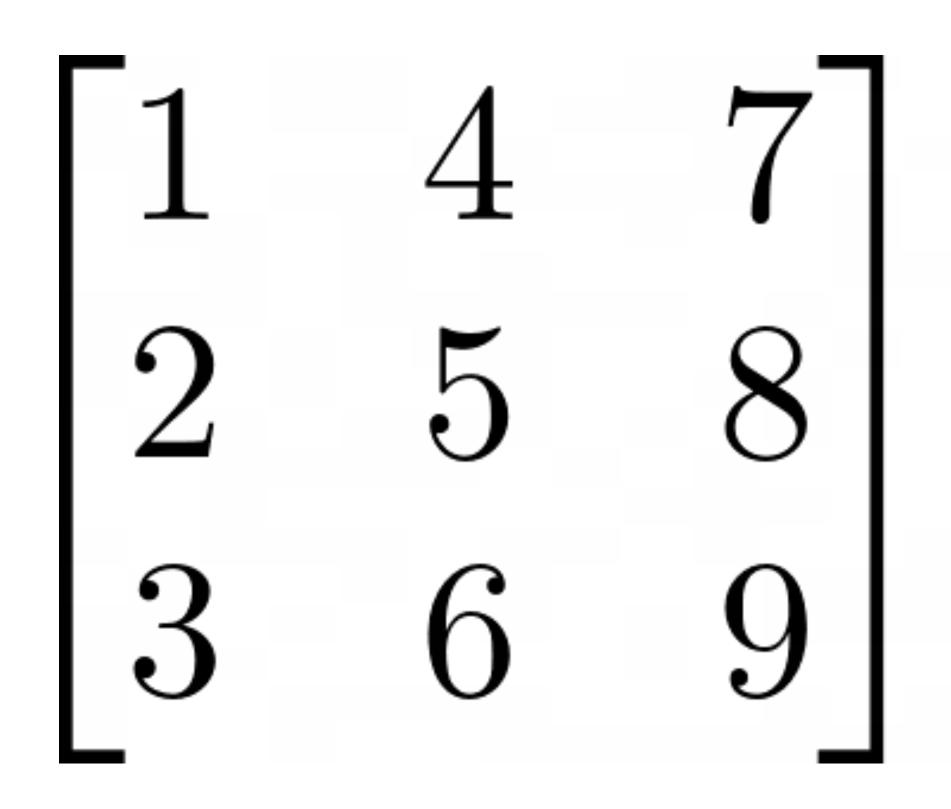


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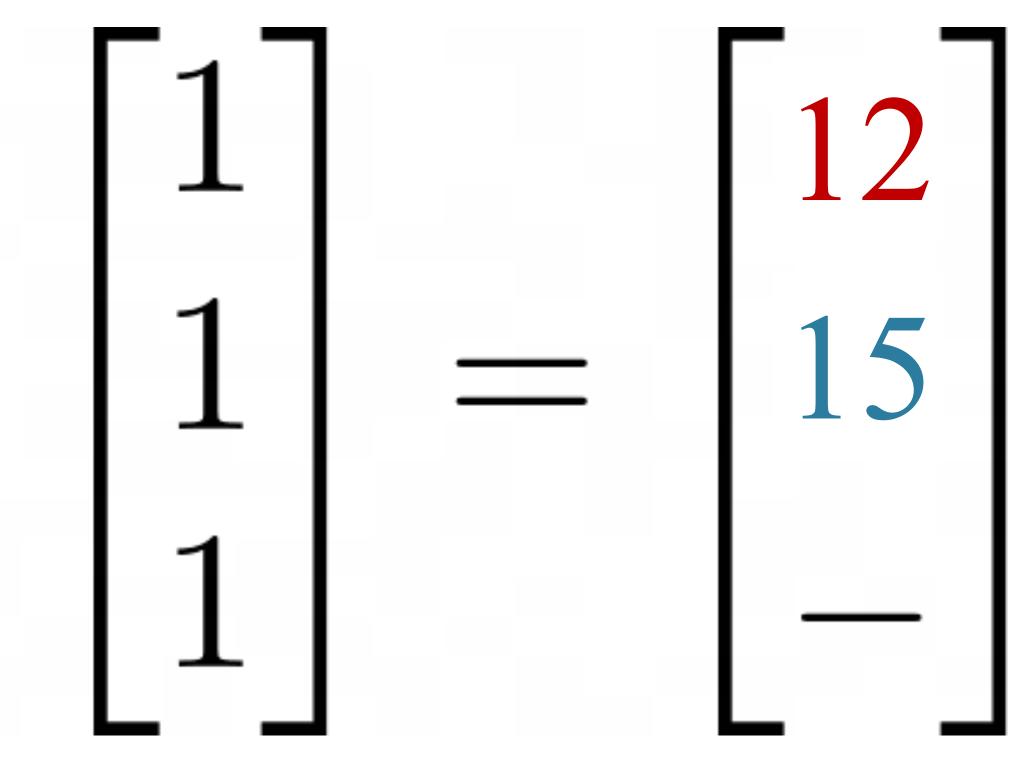








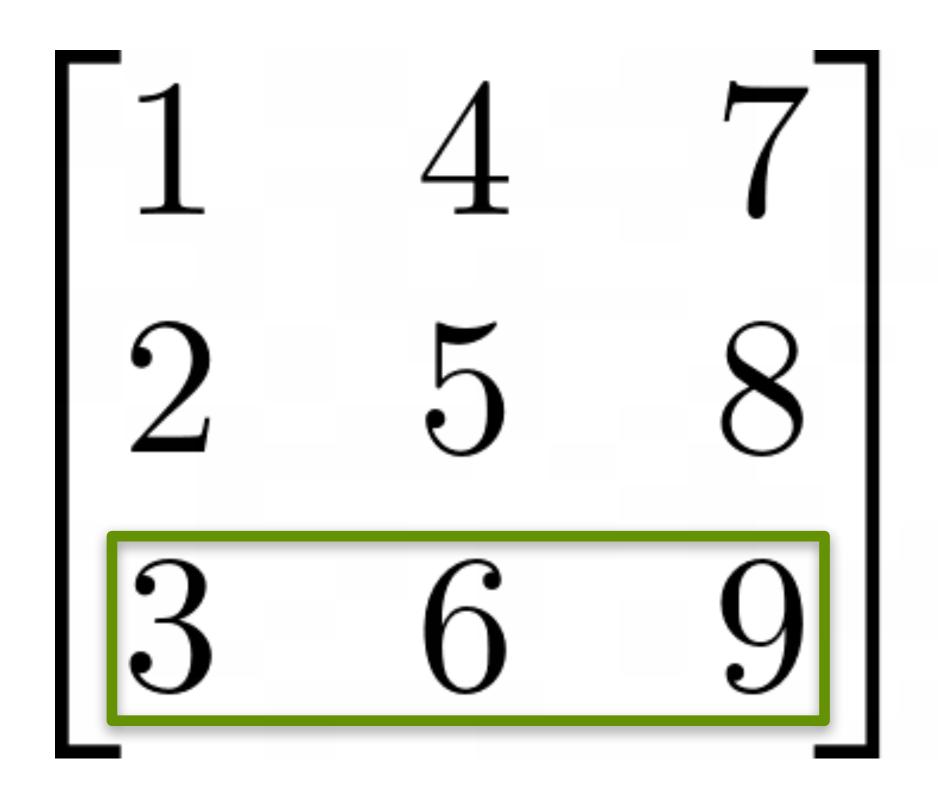
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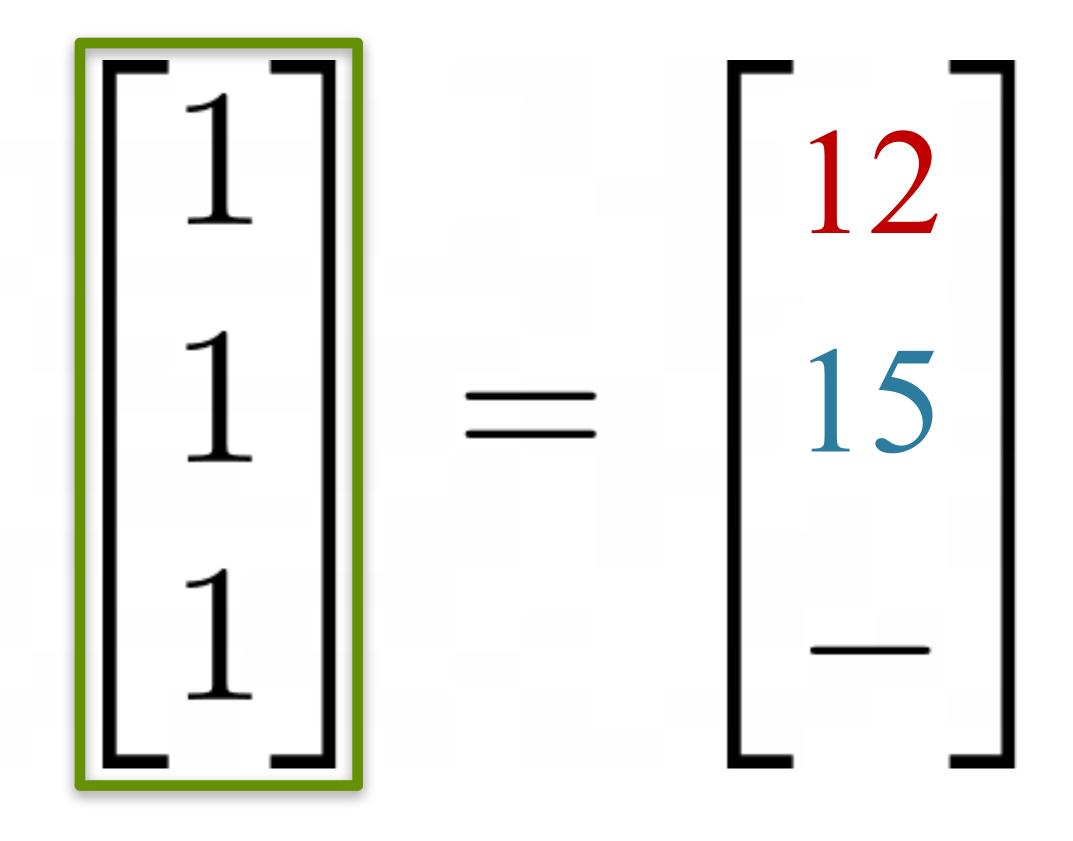








The Traditional Way

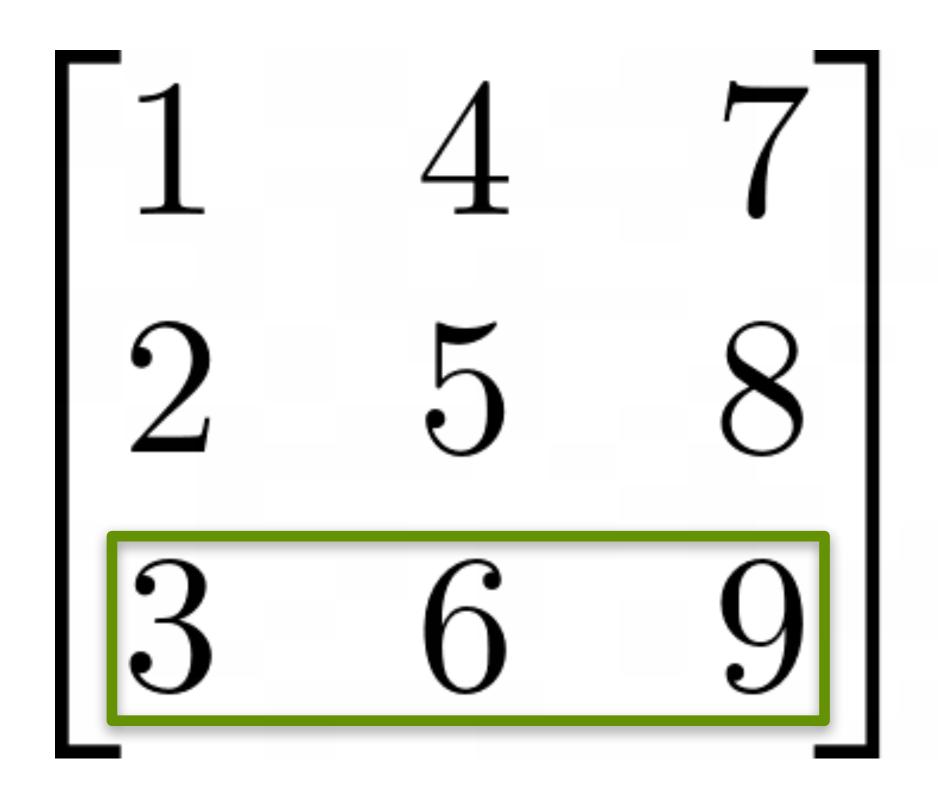




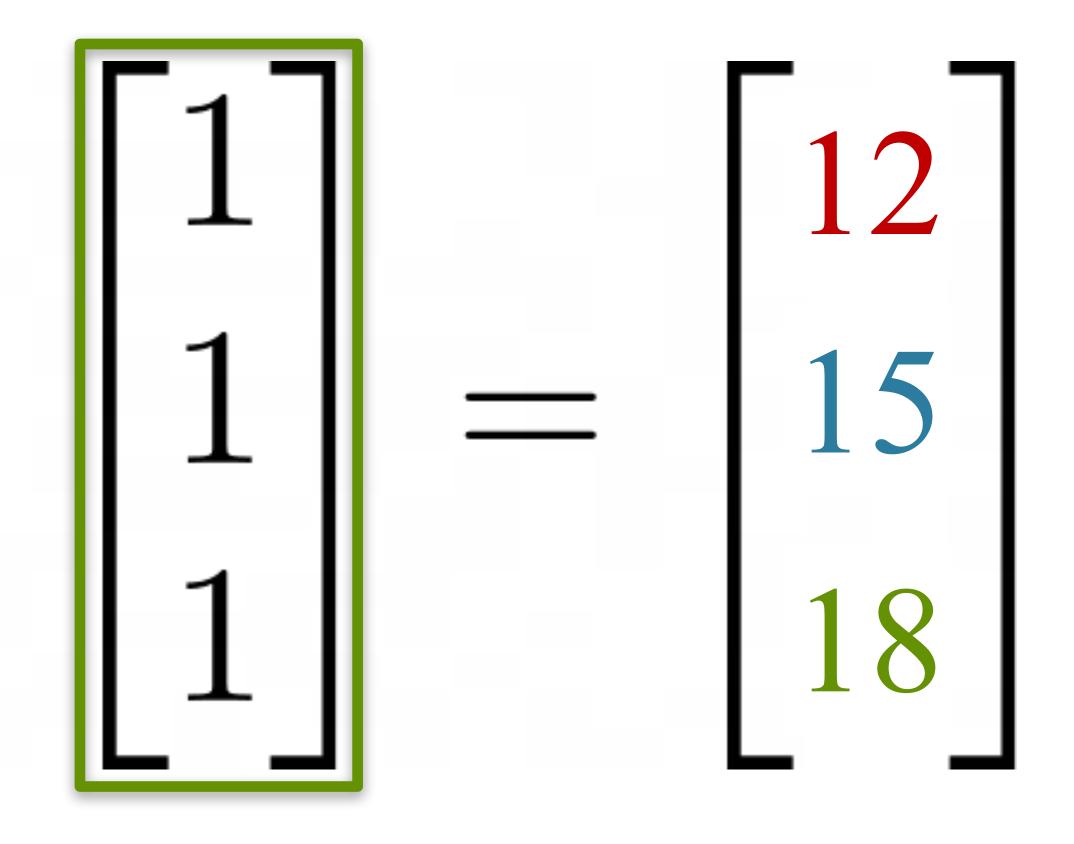








The Traditional Way















• Alternative way to think about this multiplication







Alternative way to think about this multiplication

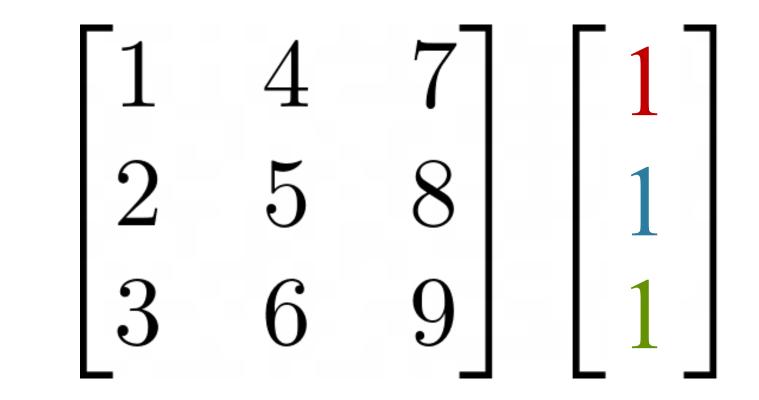
$\begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

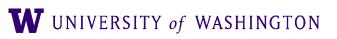






- Alternative way to think about this multiplication
 - The matrix consists of **column vectors**

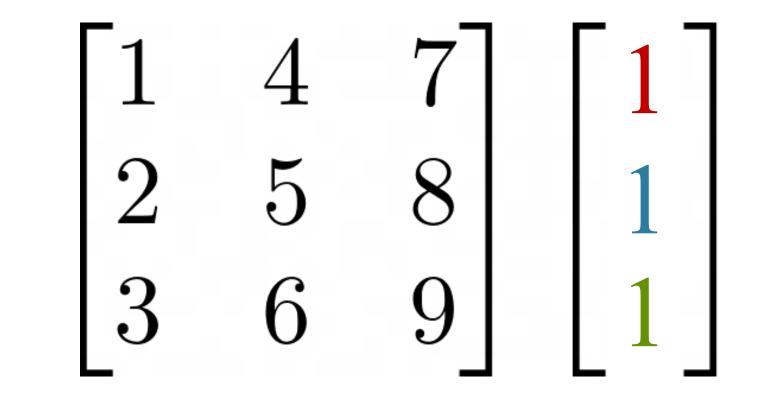


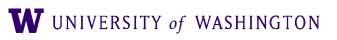






- Alternative way to think about this multiplication
 - The matrix consists of column vectors
 - The vector provides the constants for a linear combination of the columns

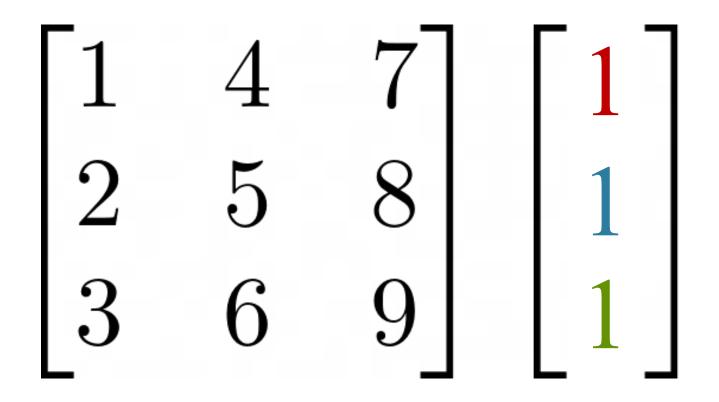


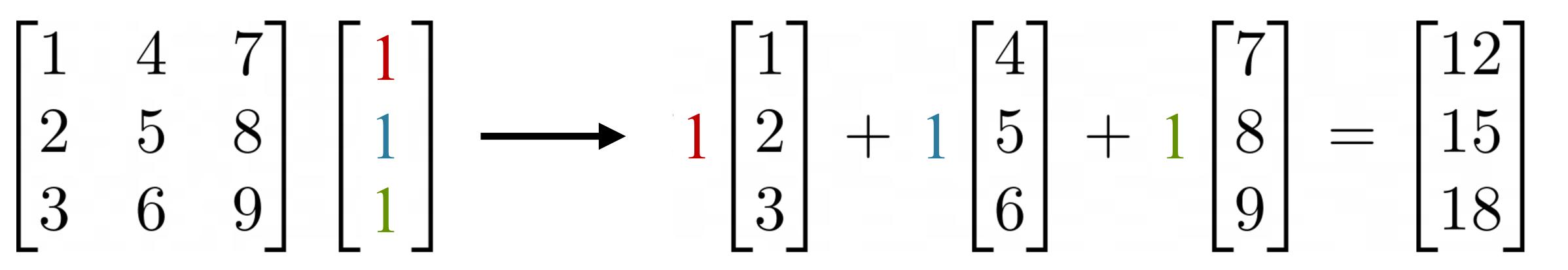






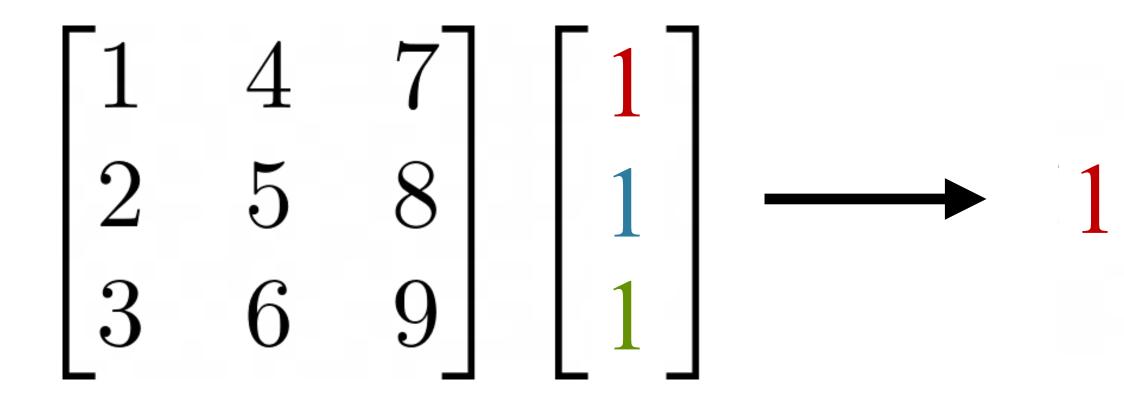
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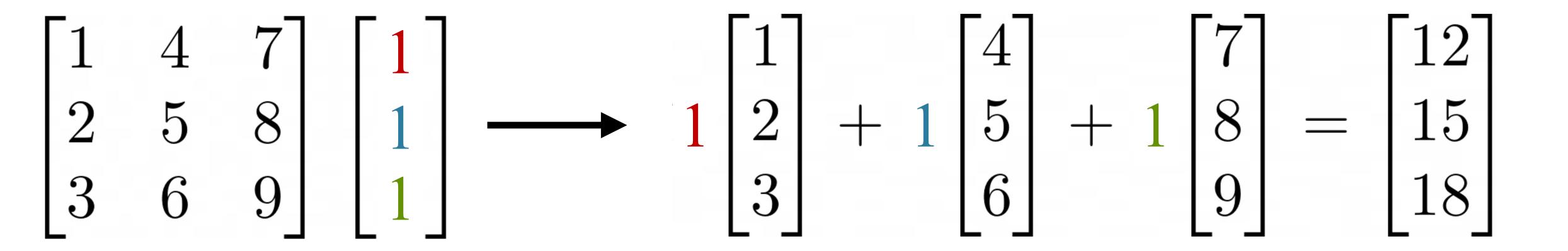










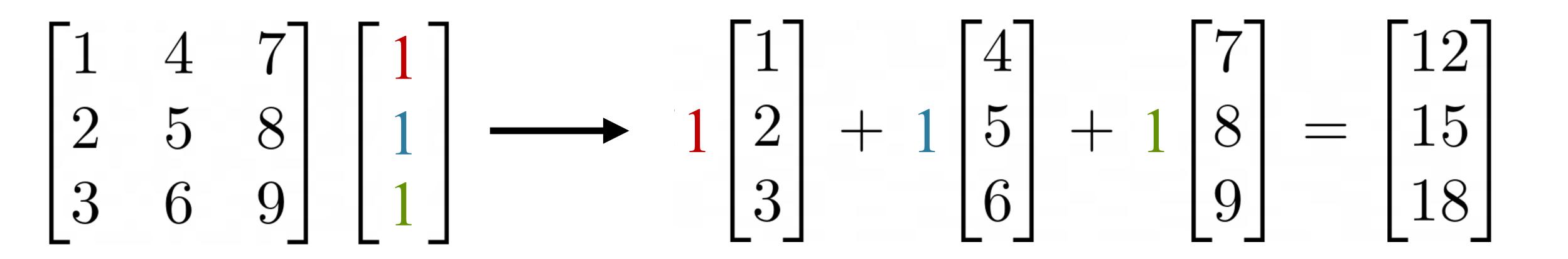








• What is the significance of this alternate view?

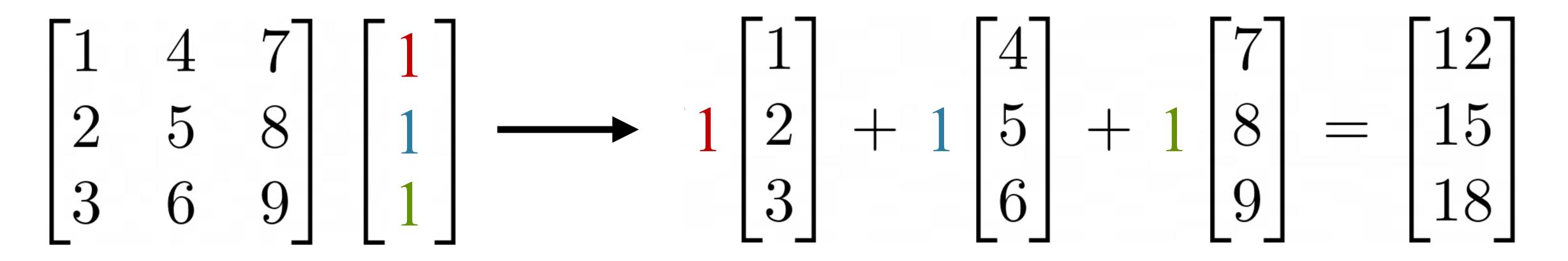








• What is the significance of this alternate view? • For all Ax = b, b is expressed as a linear combination of A's columns, and SO...

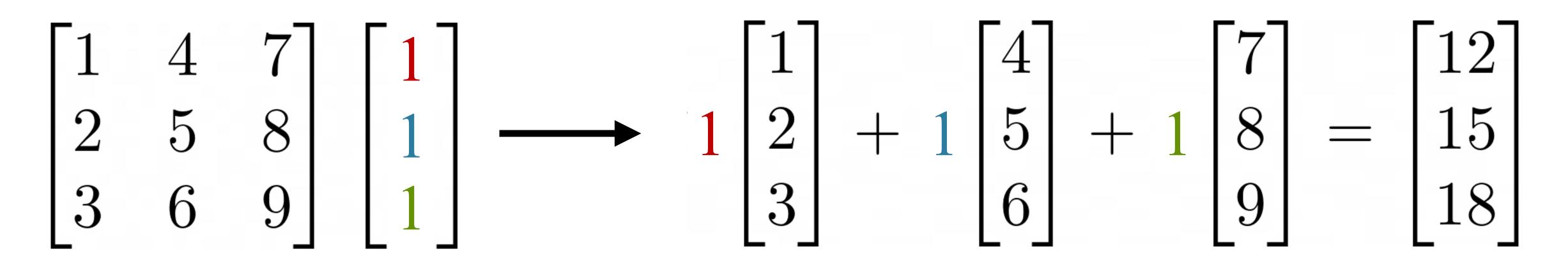








- What is the significance of this alternate view? • For all Ax = b, b is expressed as a linear combination of A's columns, and SO...
 - $\dots b$ is always in the span of A's columns

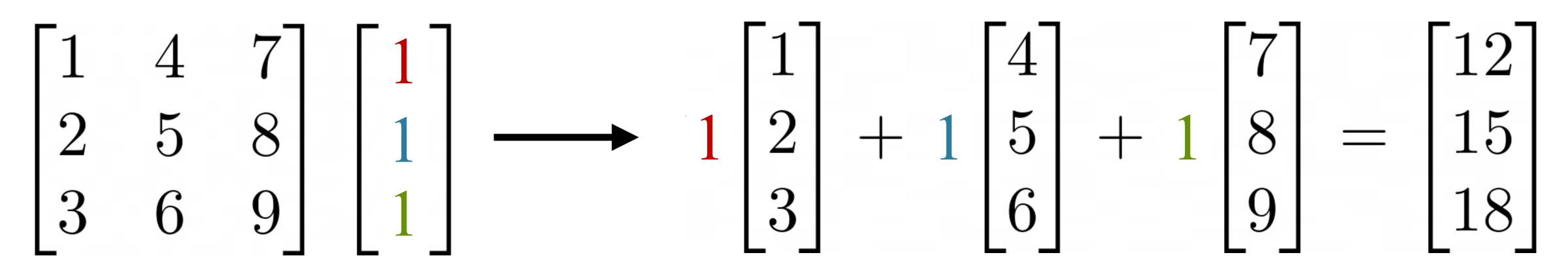








- What is the significance of this alternate view?
 - For all Ax = b, b is expressed as a linear combination of A's columns, and SO...
 - $\dots b$ is always in the span of A's columns
 - This is called the **Column Space of** A, C(A)









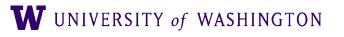
0 1 3







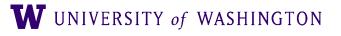
 What can you tell about the Column Space of this matrix?







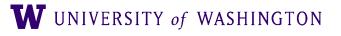
- What can you tell about the Column Space of this matrix?
 - 3 independent columns







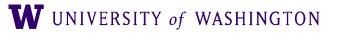
- What can you tell about the Column Space of this matrix?
 - 3 independent columns
 - C(A) spans R^3







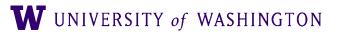
- What can you tell about the Column Space of this matrix?
 - 3 independent columns
 - C(A) spans R^3
 - Ax spans R^3







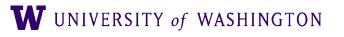
5 L '







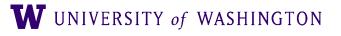
 What can you tell about the Column Space of this matrix?







- What can you tell about the Column Space of this matrix?
 - 2 independent columns







- What can you tell about the Column Space of this matrix?
 - 2 independent columns

third column not independent of first two





- What can you tell about the Column Space of this matrix?
 - 2 independent columns
 - C(A) spans a **2D** plane in R^3

third column not independent of first two



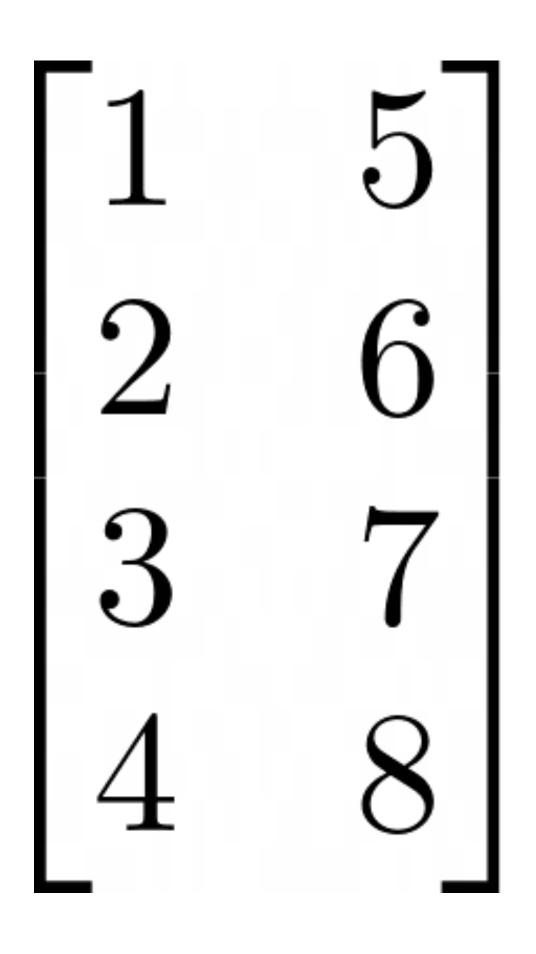


- What can you tell about the Column Space of this matrix?
 - 2 independent columns
 - C(A) spans a **2D** plane in R^3
 - Ax spans a **2D** plane in R^3

third column not independent of first two







 $oldsymbol{W}$ university of washington





 What can you tell about the Column Space of this matrix? What is the size of "input" vector *x*?

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- What can you tell about the Column Space of this matrix? What is the size of "input" vector *x*?
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 - x is length 4
 - C(A) spans a **2D** plane in R^4
 - Ax spans a **2D** plane in R^4





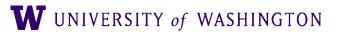








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- The rank determines the dimension of the column space









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• MxN matrix can be considered a **function** from R^N to R^M







- The number of independent columns in a matrix is called the **rank**
- The rank determines the **dimension of the column space**
 - Rank 1: line
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• etc.

• MxN matrix can be considered a **function** from R^N to R^M

• However, the function's range may not span R^M , unless it is rank M

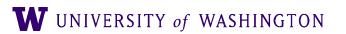






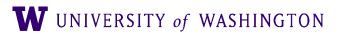


Linear Transformations







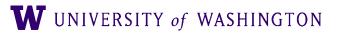






with

• The Identity Matrix I always returns the same vector/matrix it's multiplied







- with
 - e.g. Ix = x and IA = A

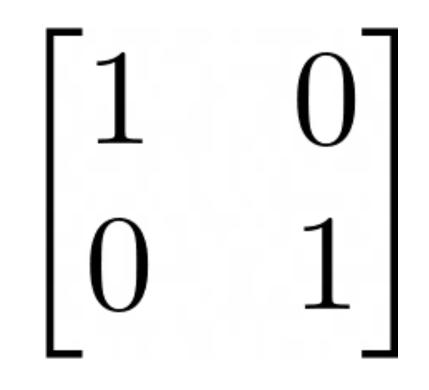
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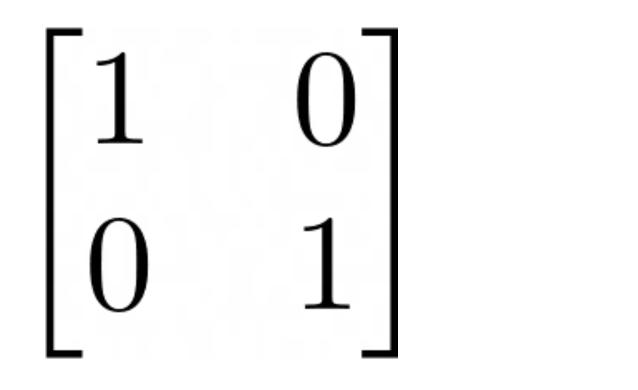
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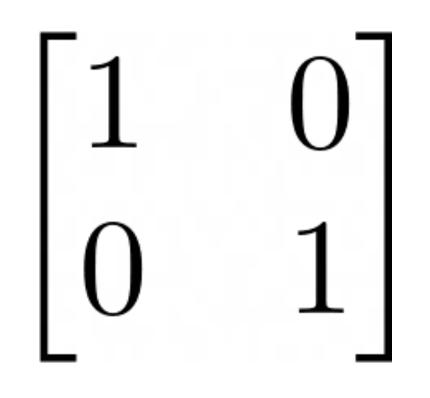
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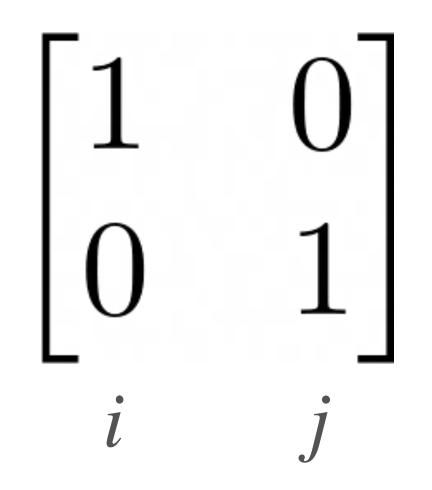
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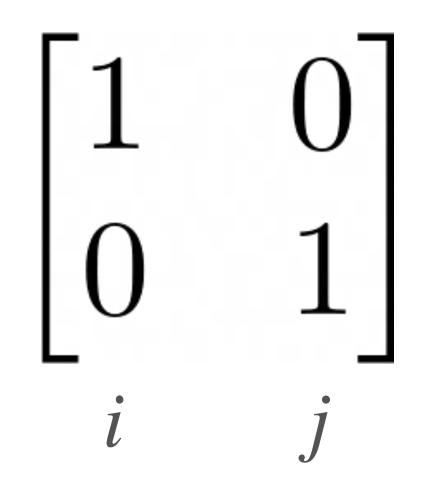
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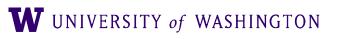




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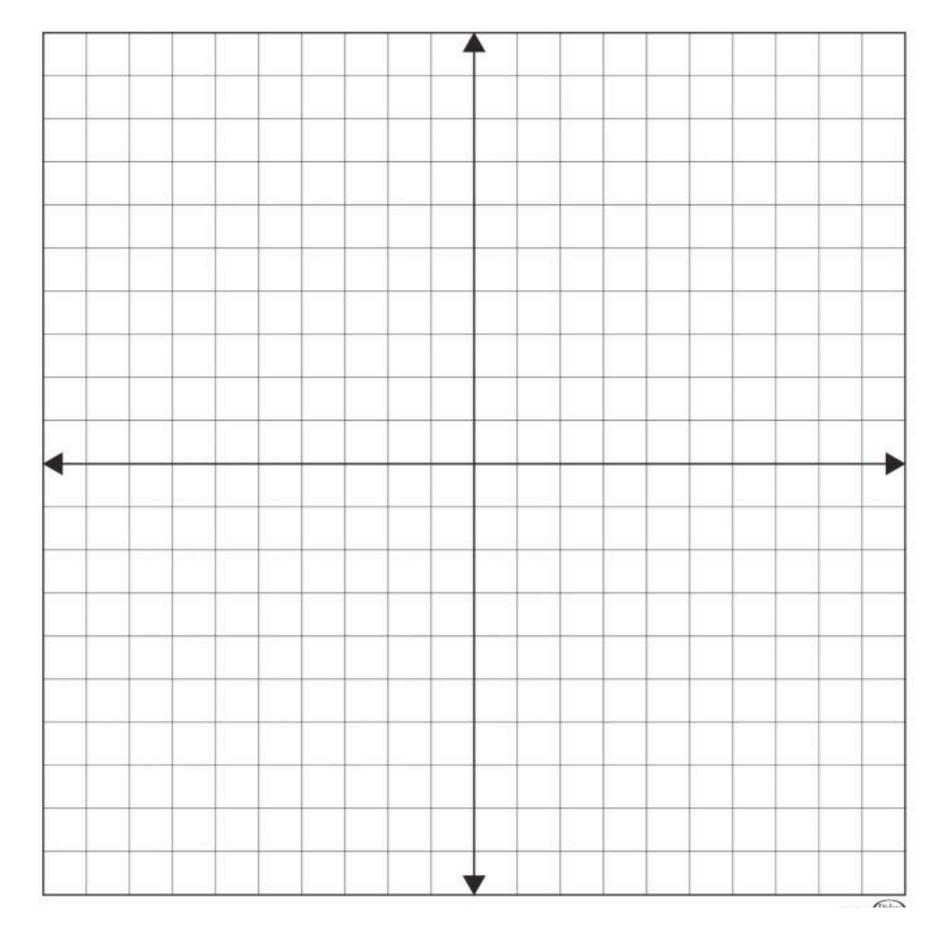
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$\begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 5 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$



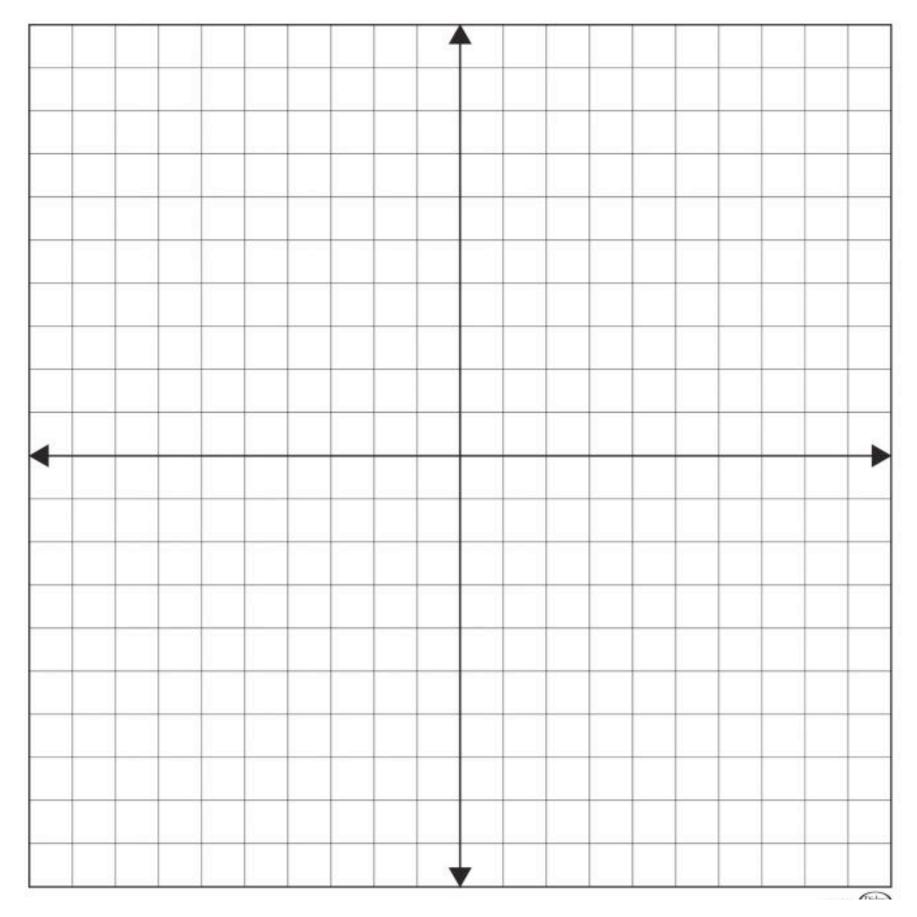






 Vectors can be viewed as being composed of the Standard Basis vectors

$\begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 5 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$



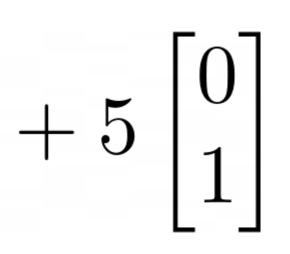


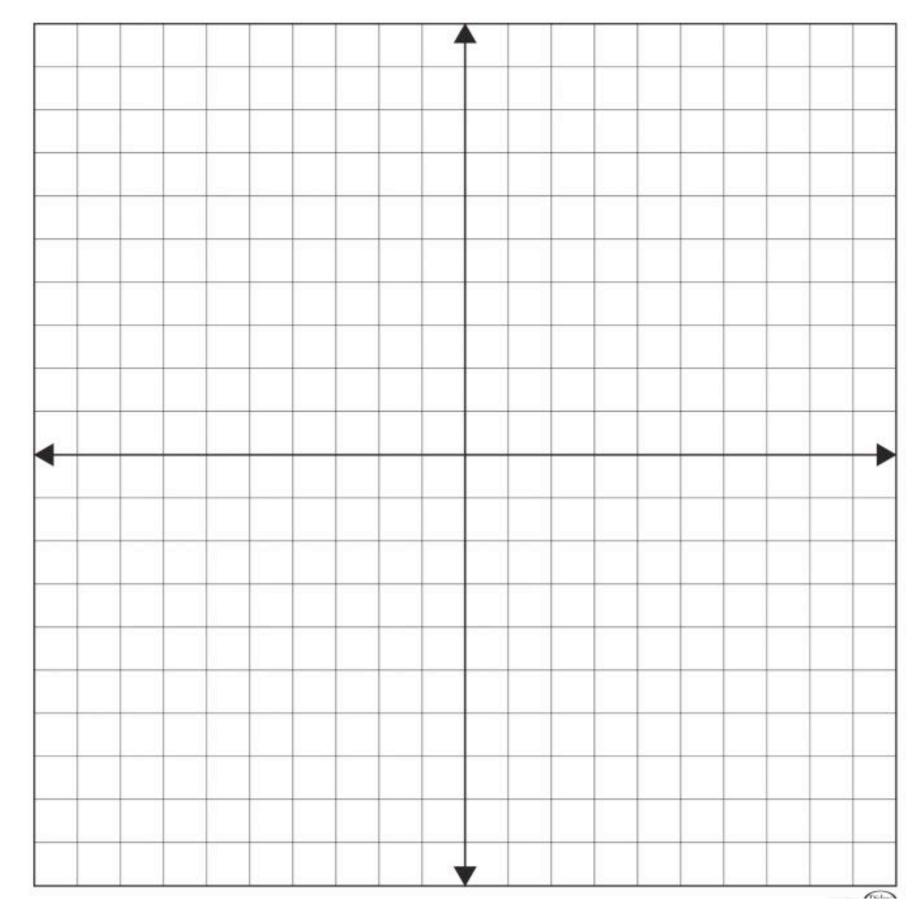




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$$\begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$





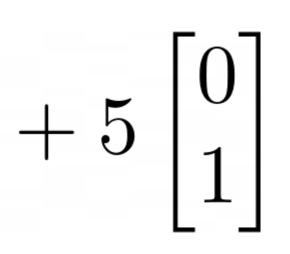


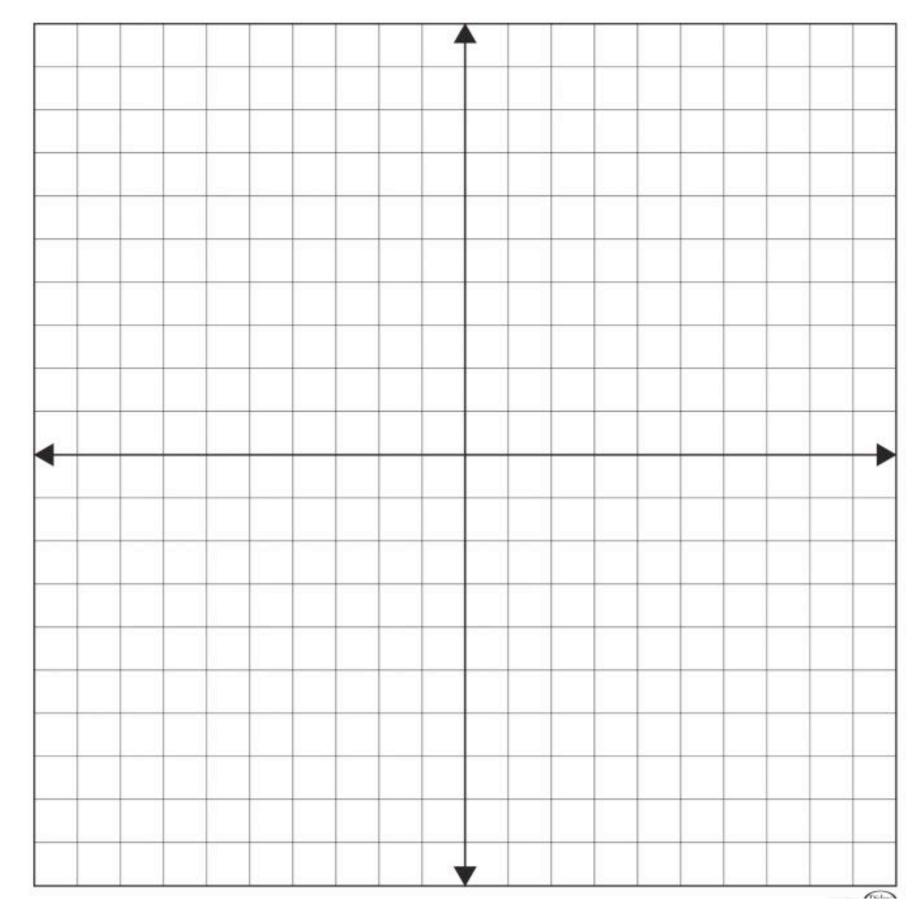




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i





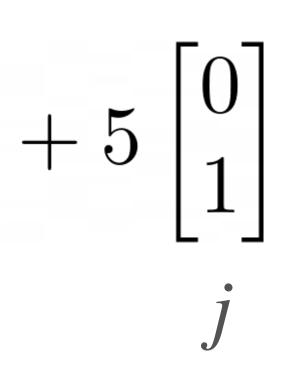


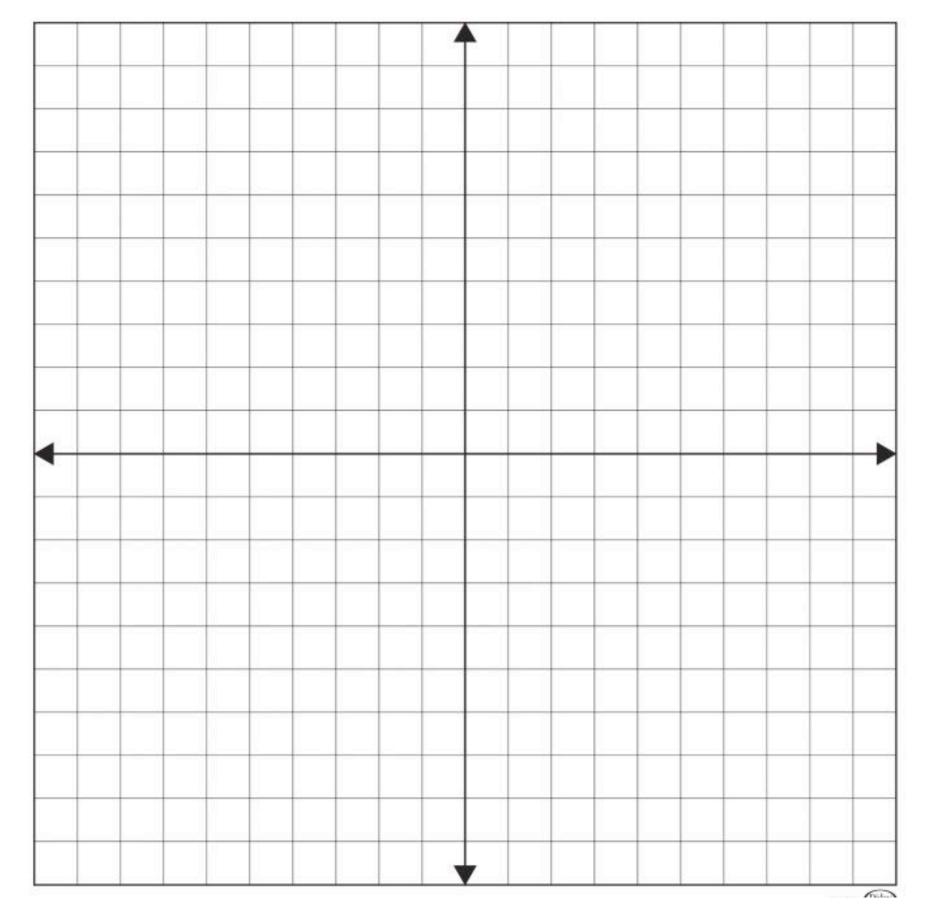




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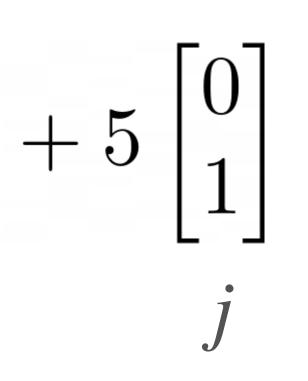


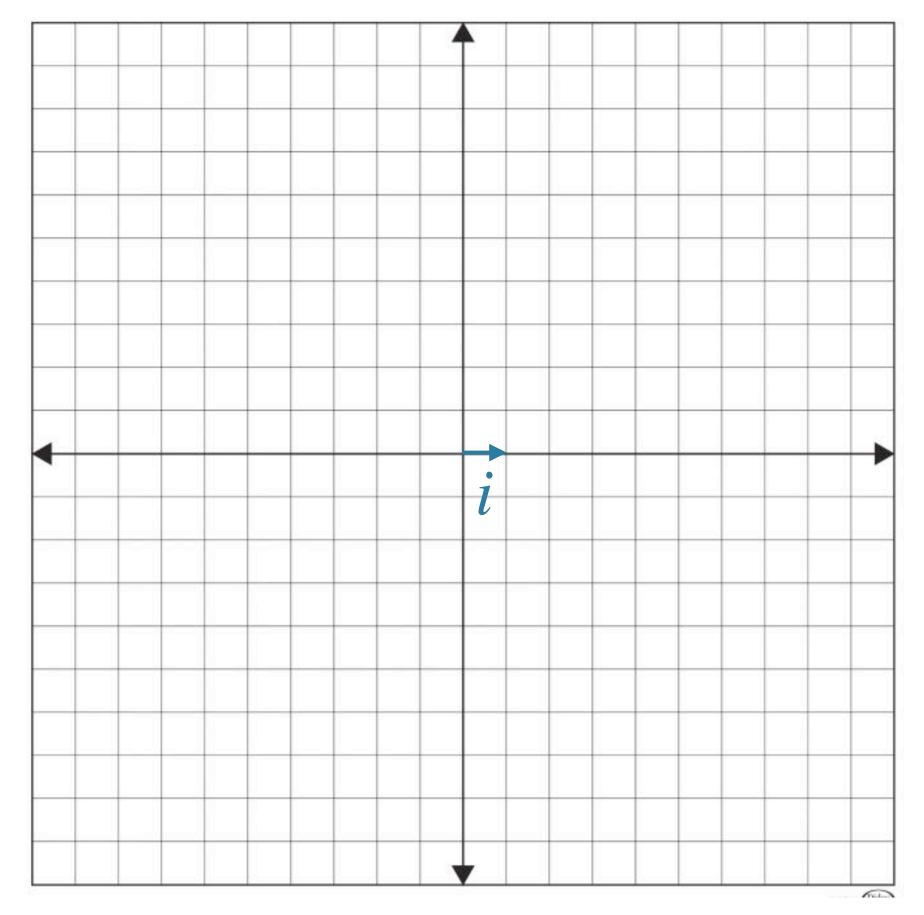




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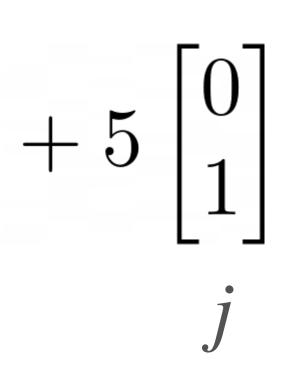


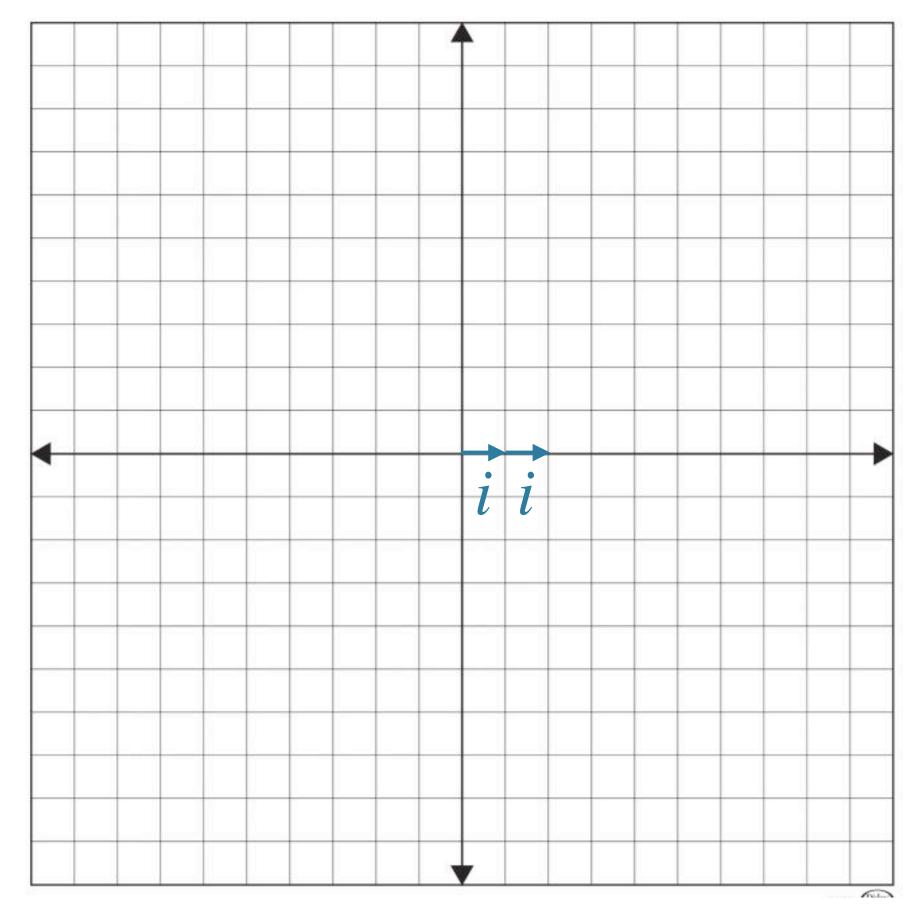




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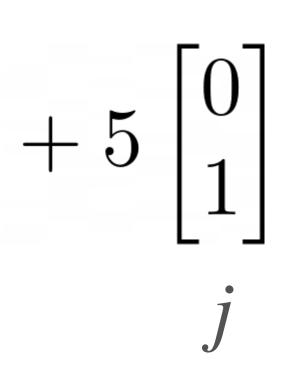


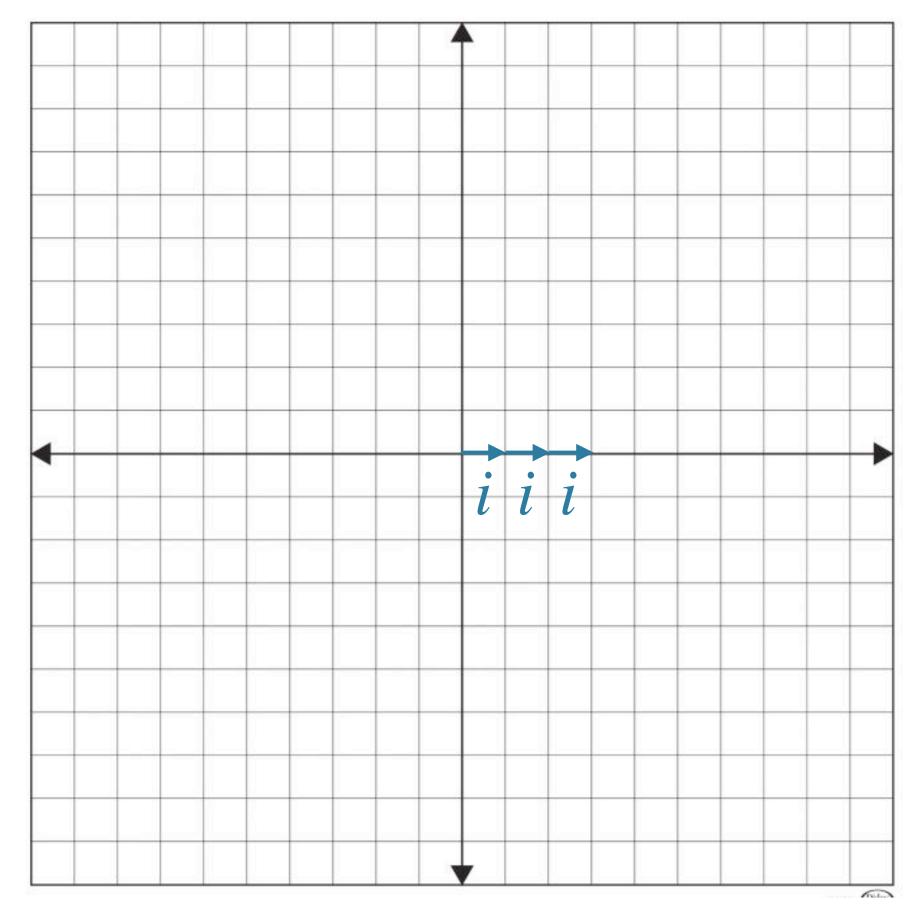




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i





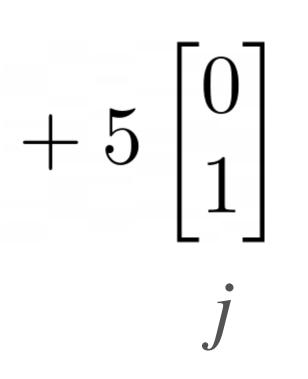


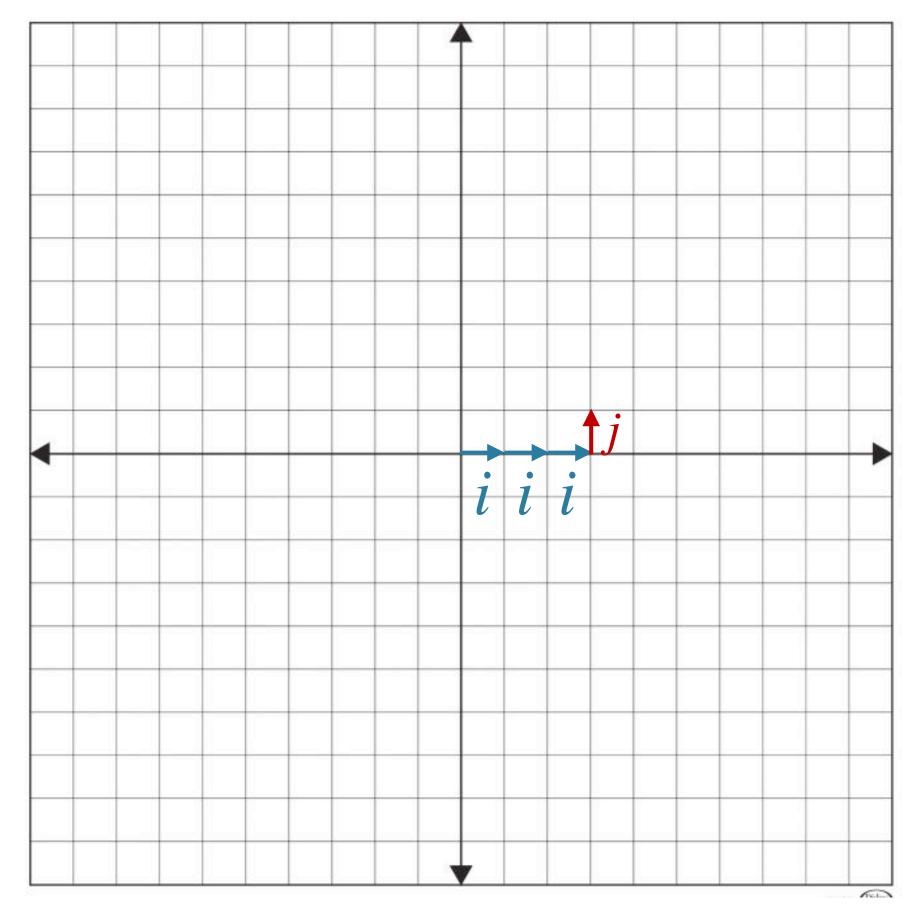




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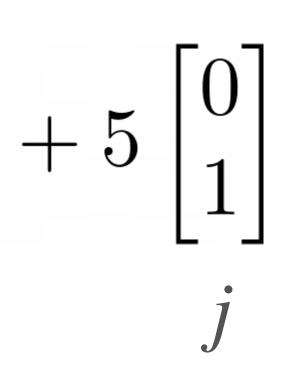


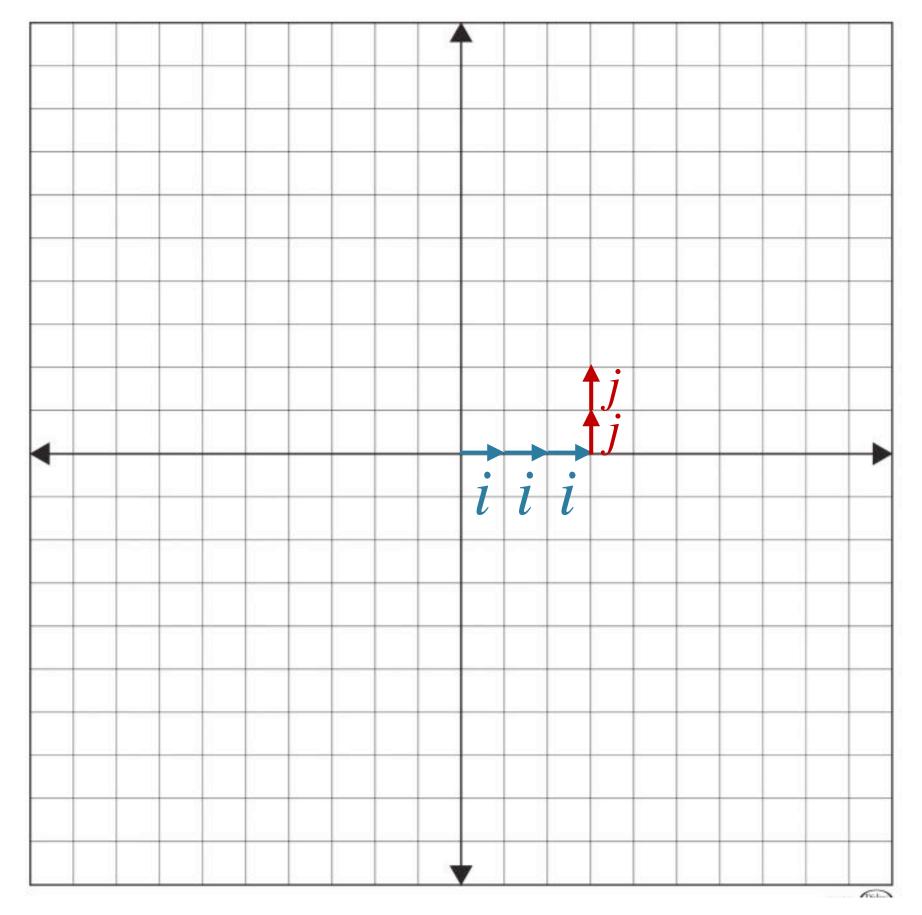




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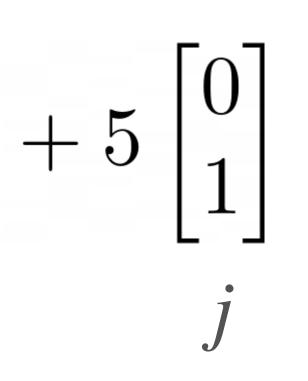


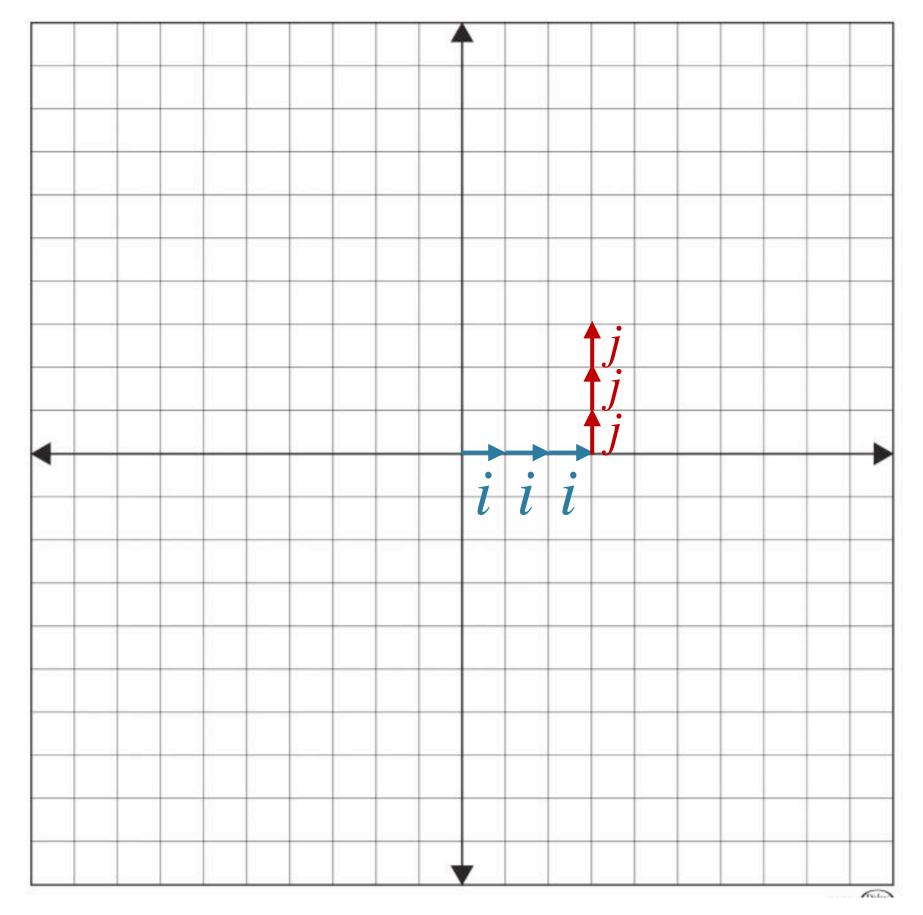




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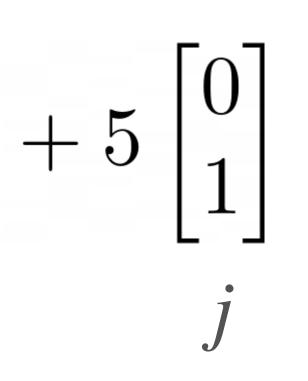


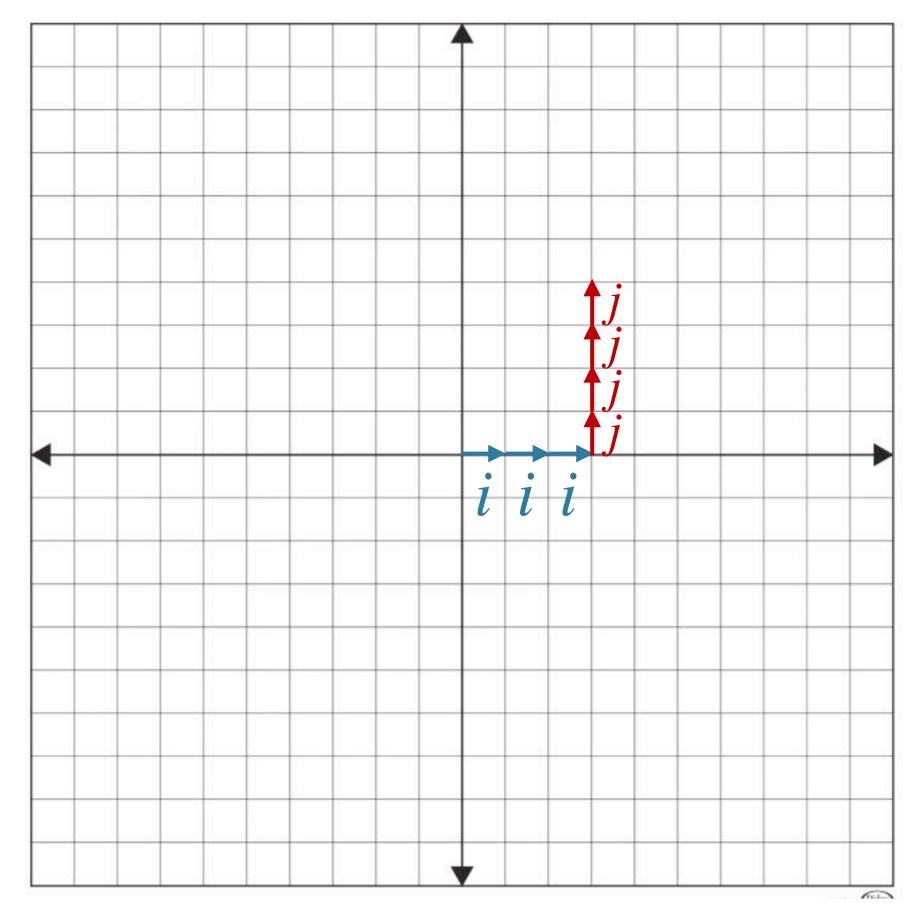




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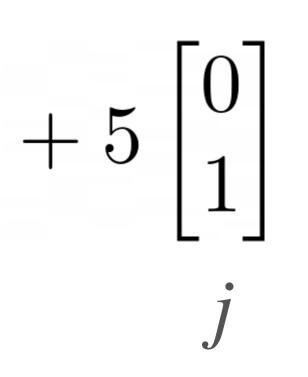


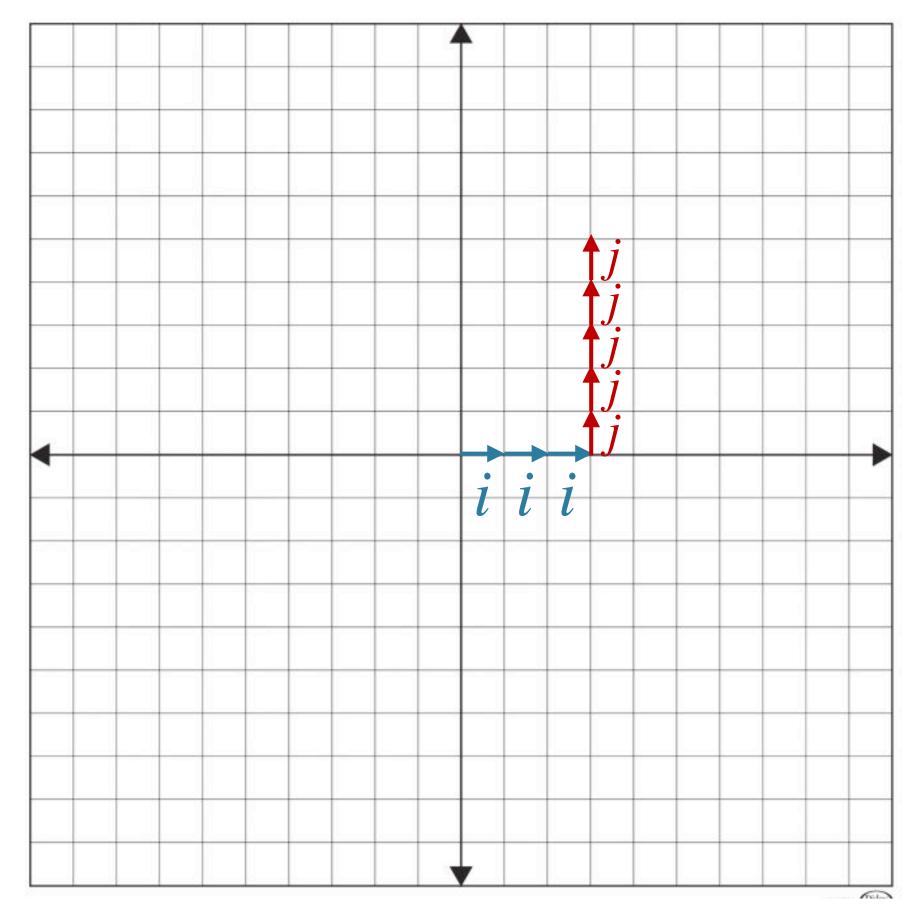




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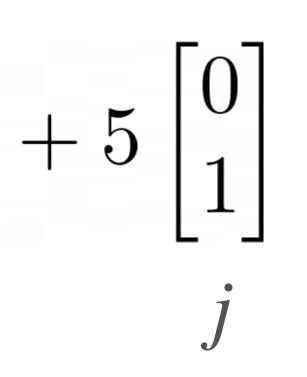


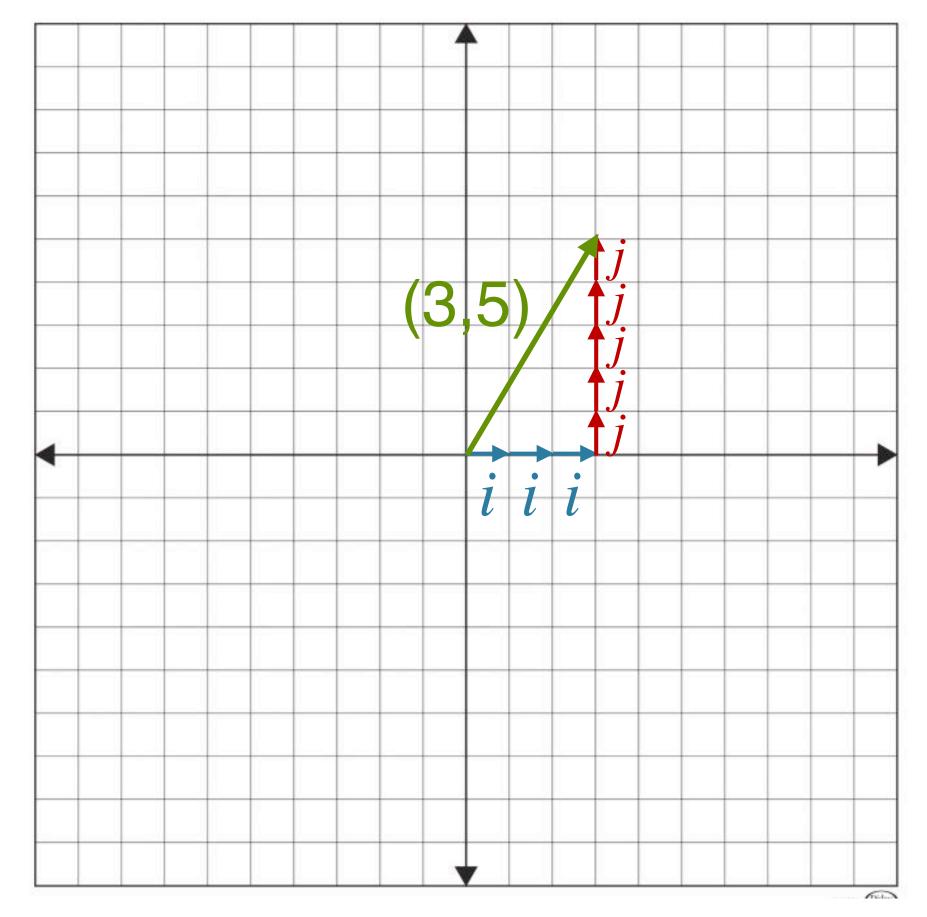
Identity Matrix as a Basis

 Vectors can be viewed as being composed of the Standard Basis vectors

• A vector is a linear combination of this basis

$$\begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
i



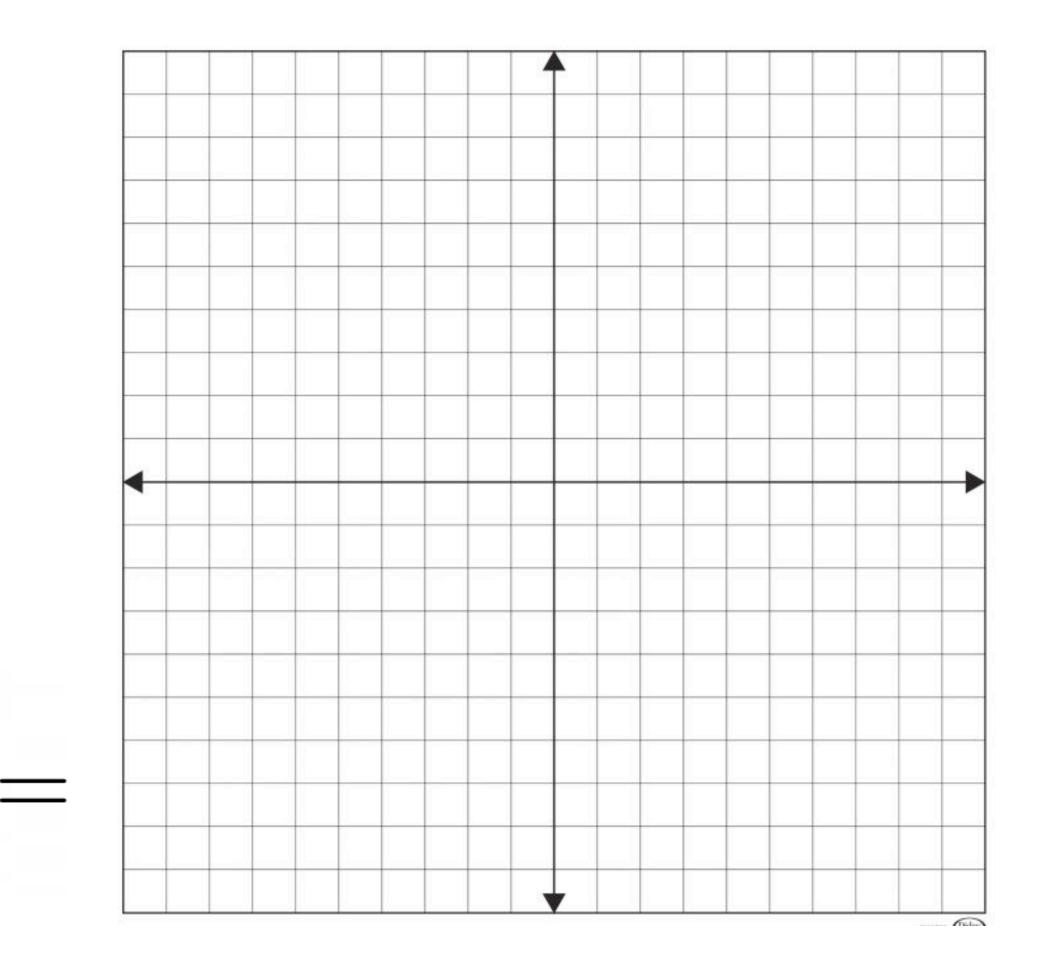


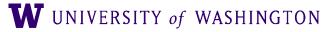






$\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 5 \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

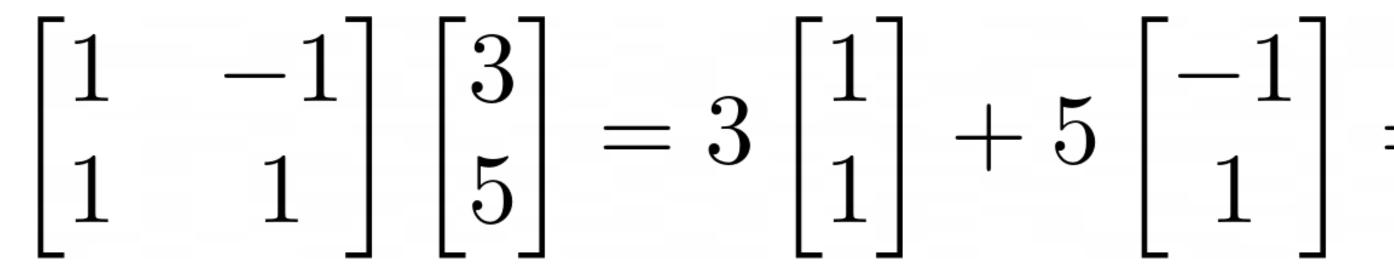








 Multiplying by a matrix converts a vector to a new basis

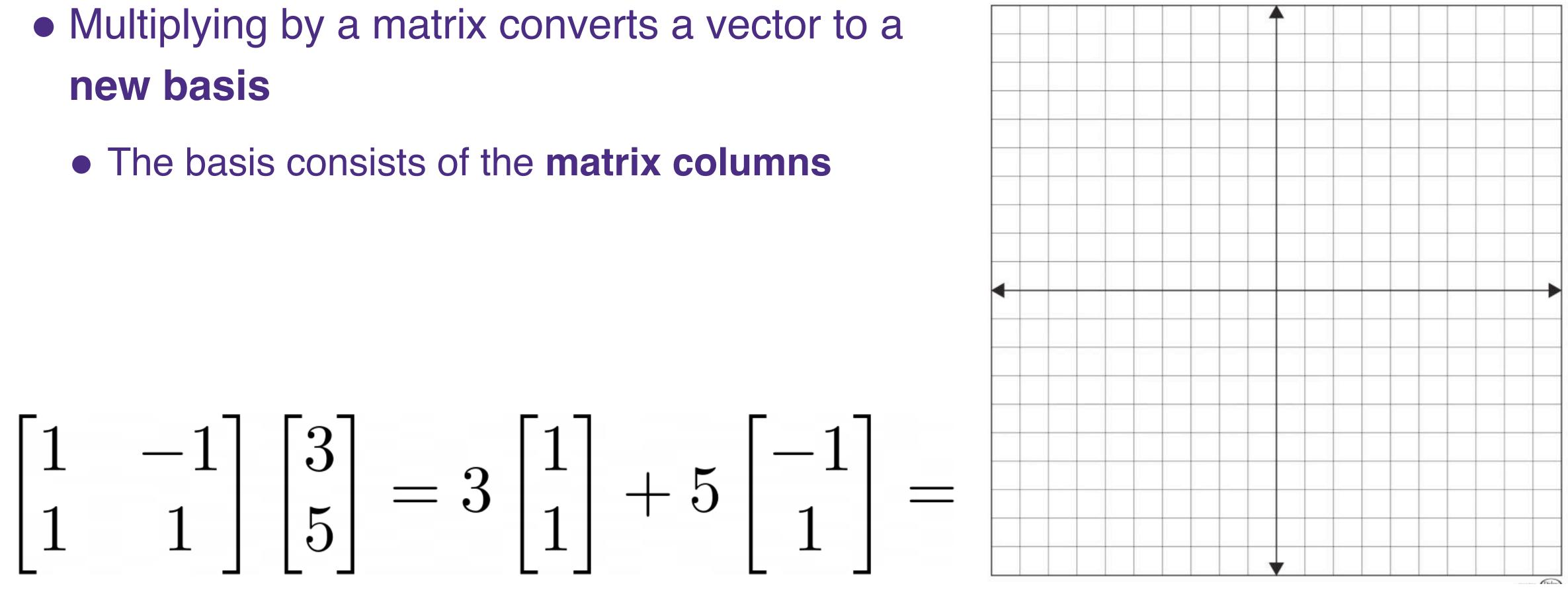


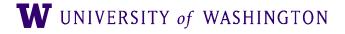






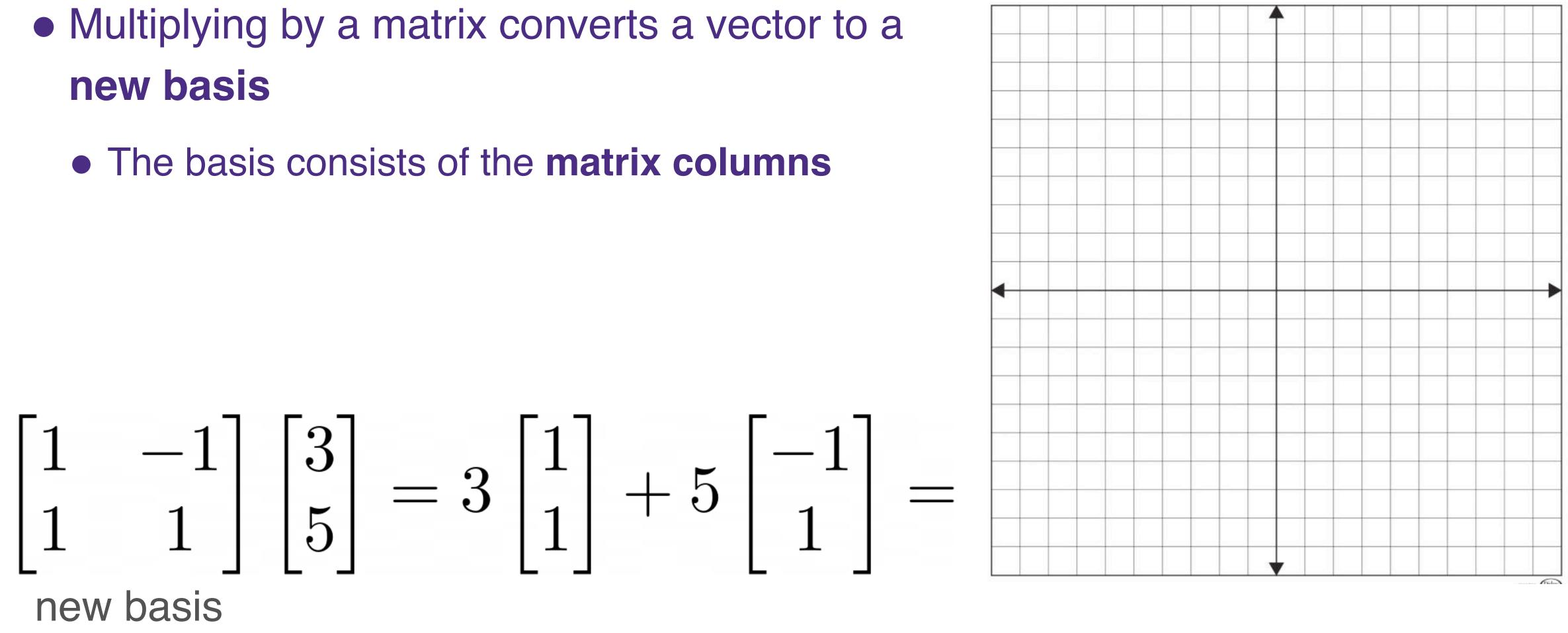
- new basis

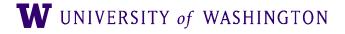






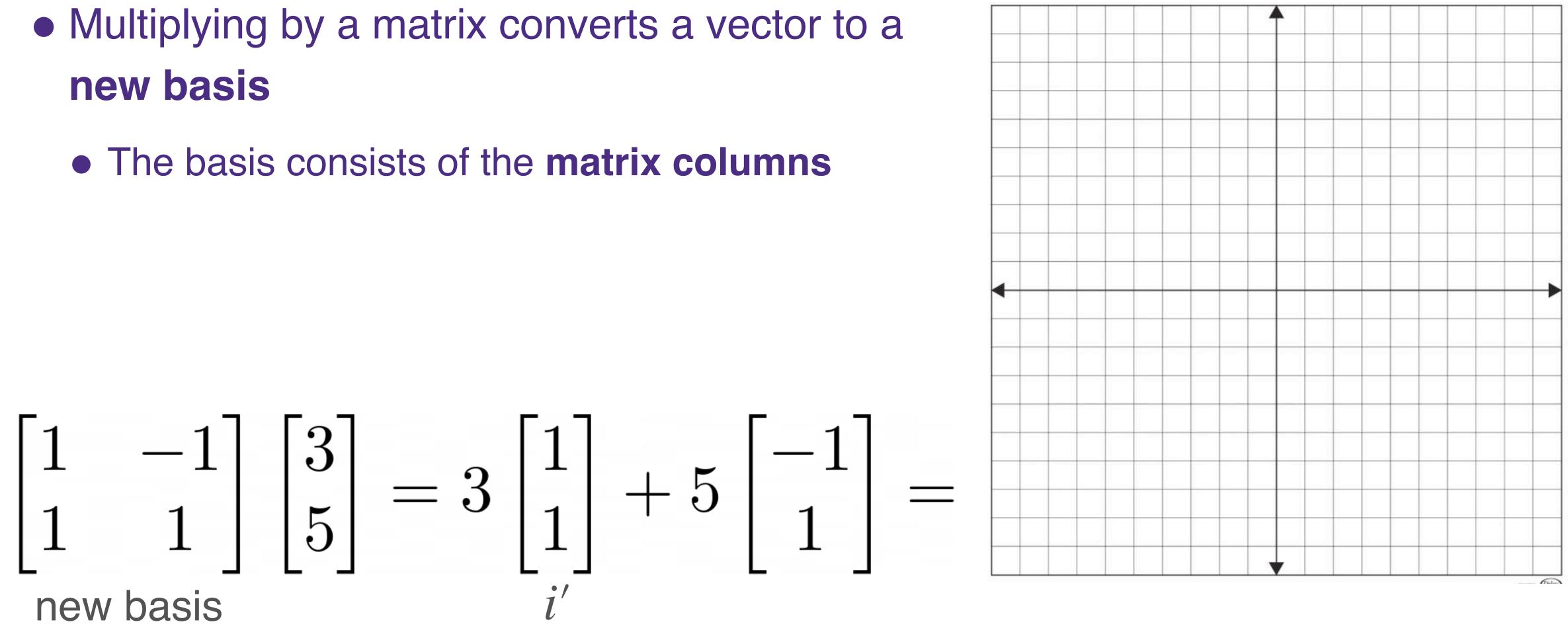
- new basis

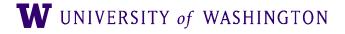






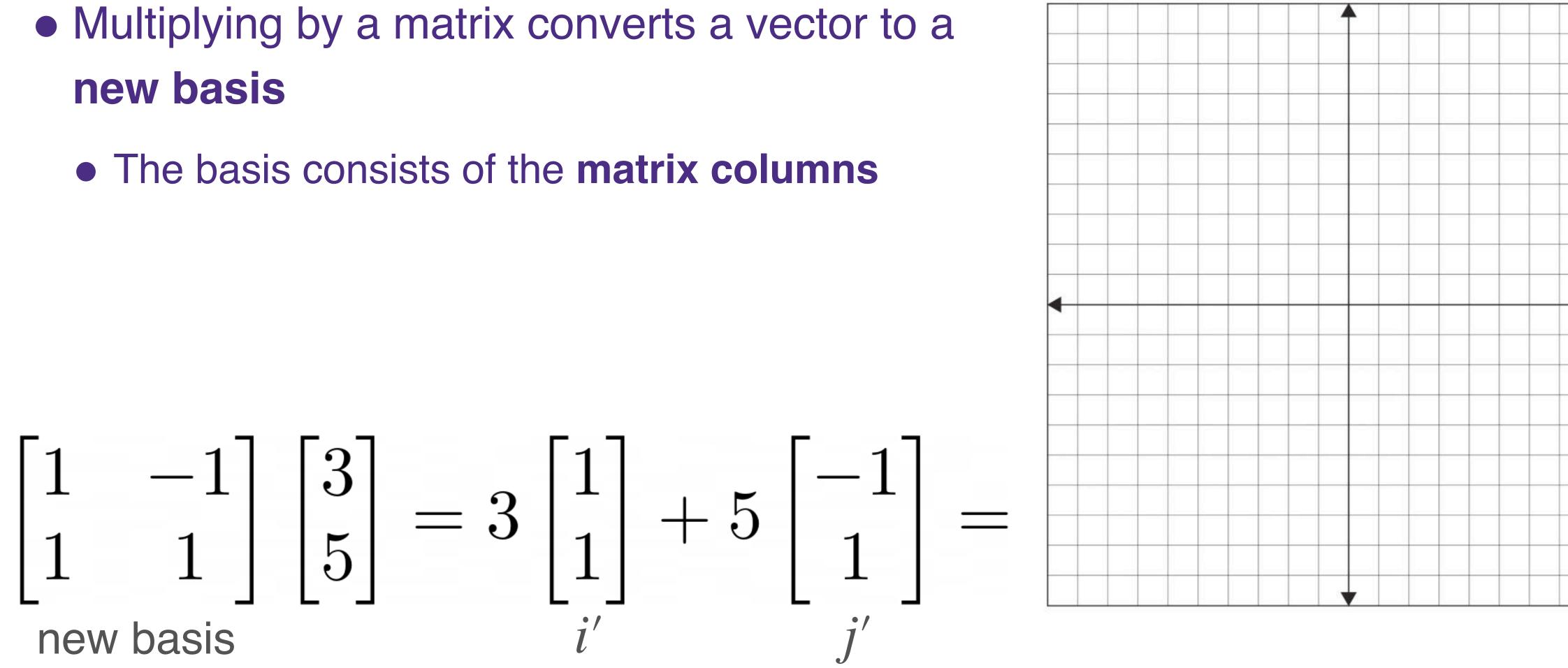
- new basis

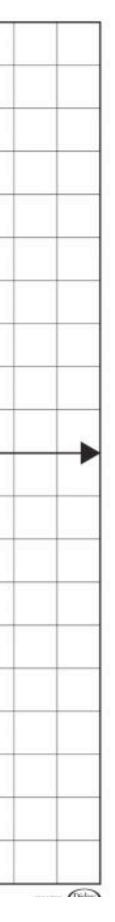






- new basis

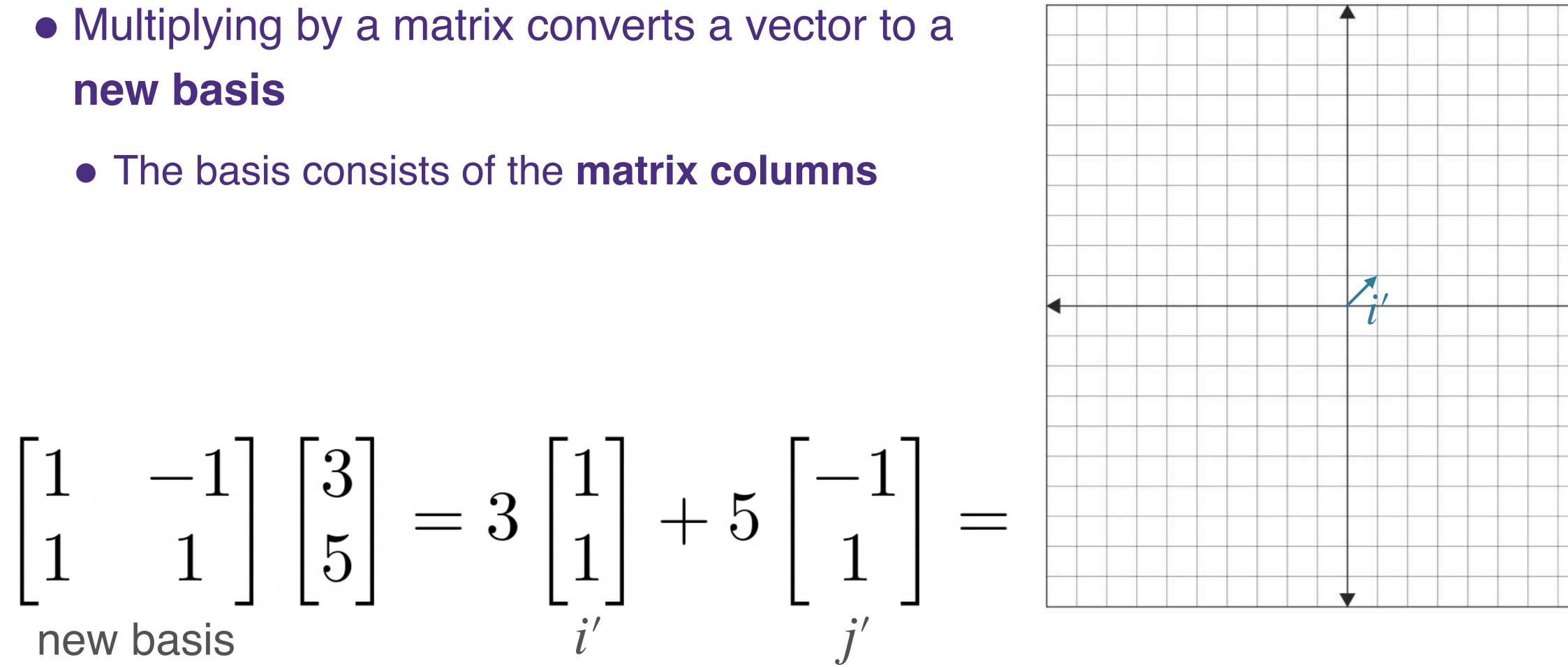








- new basis

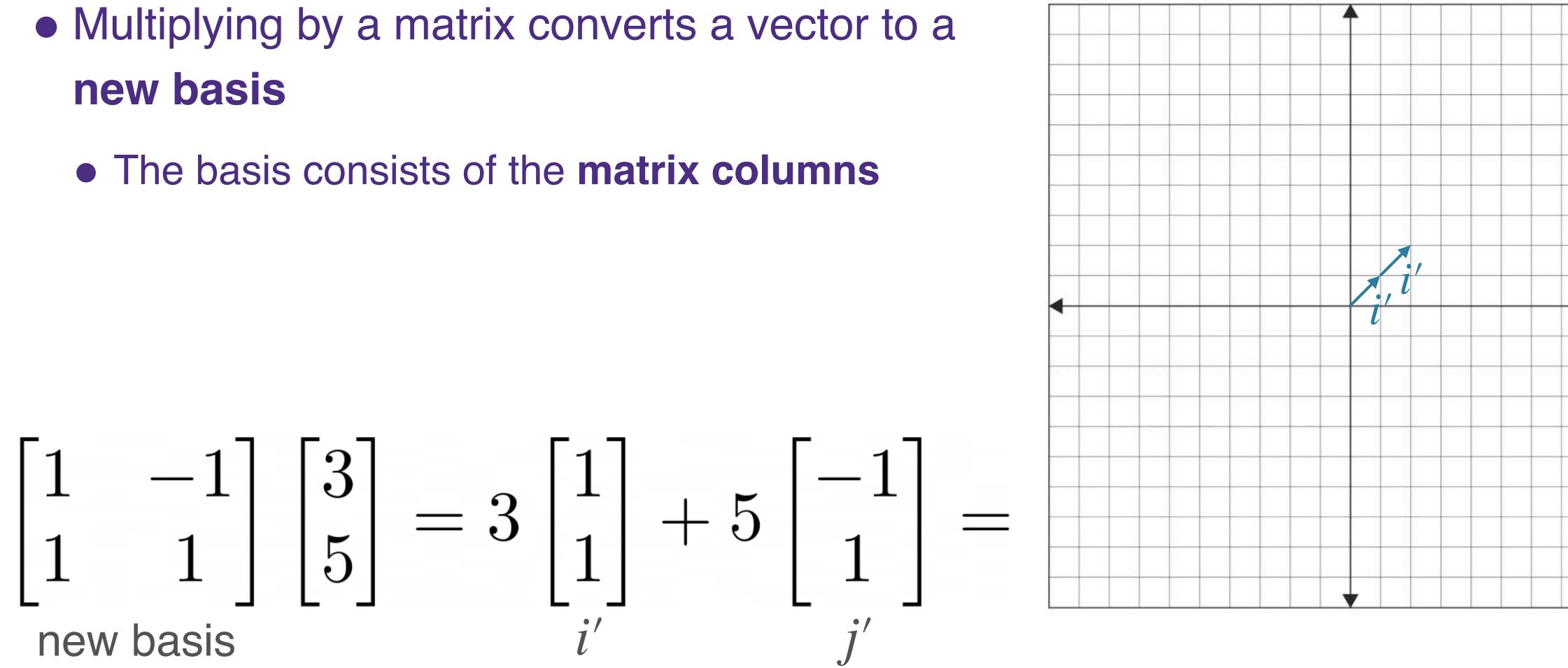








- new basis

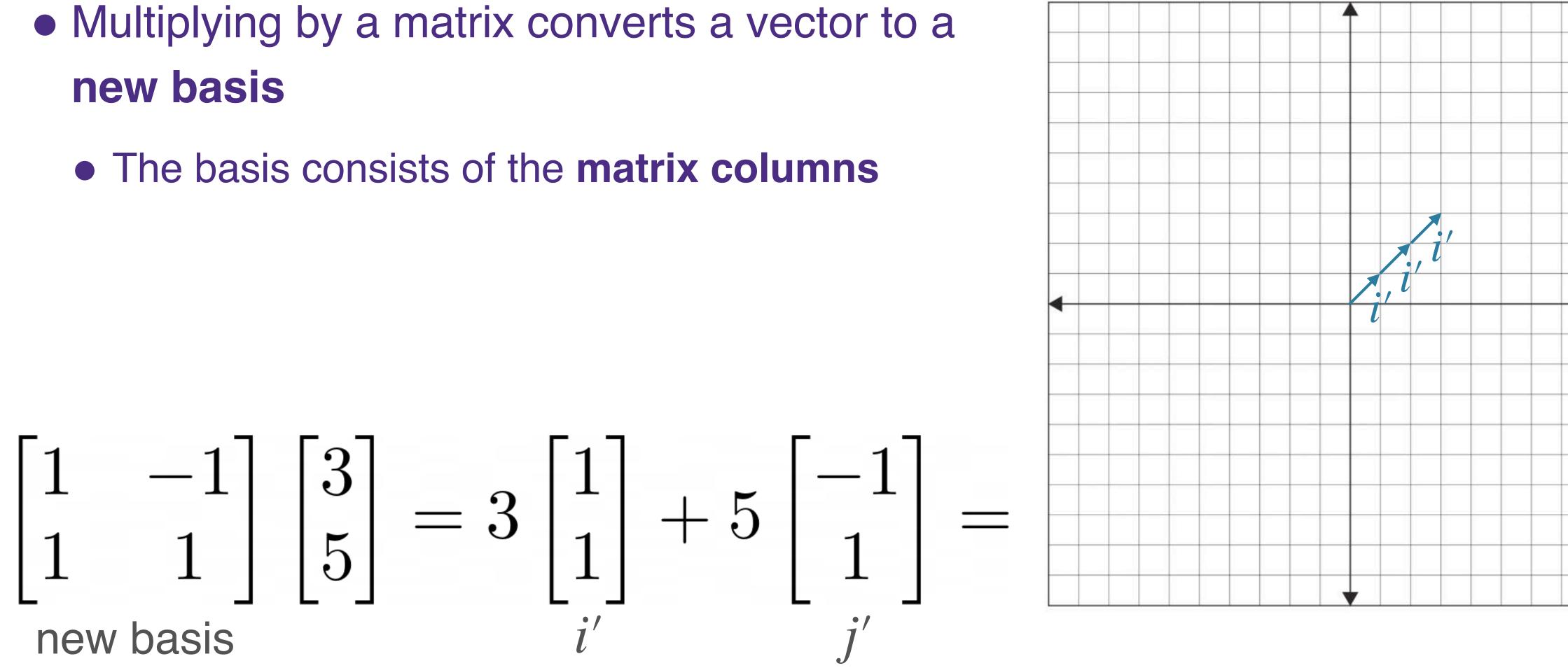








- new basis

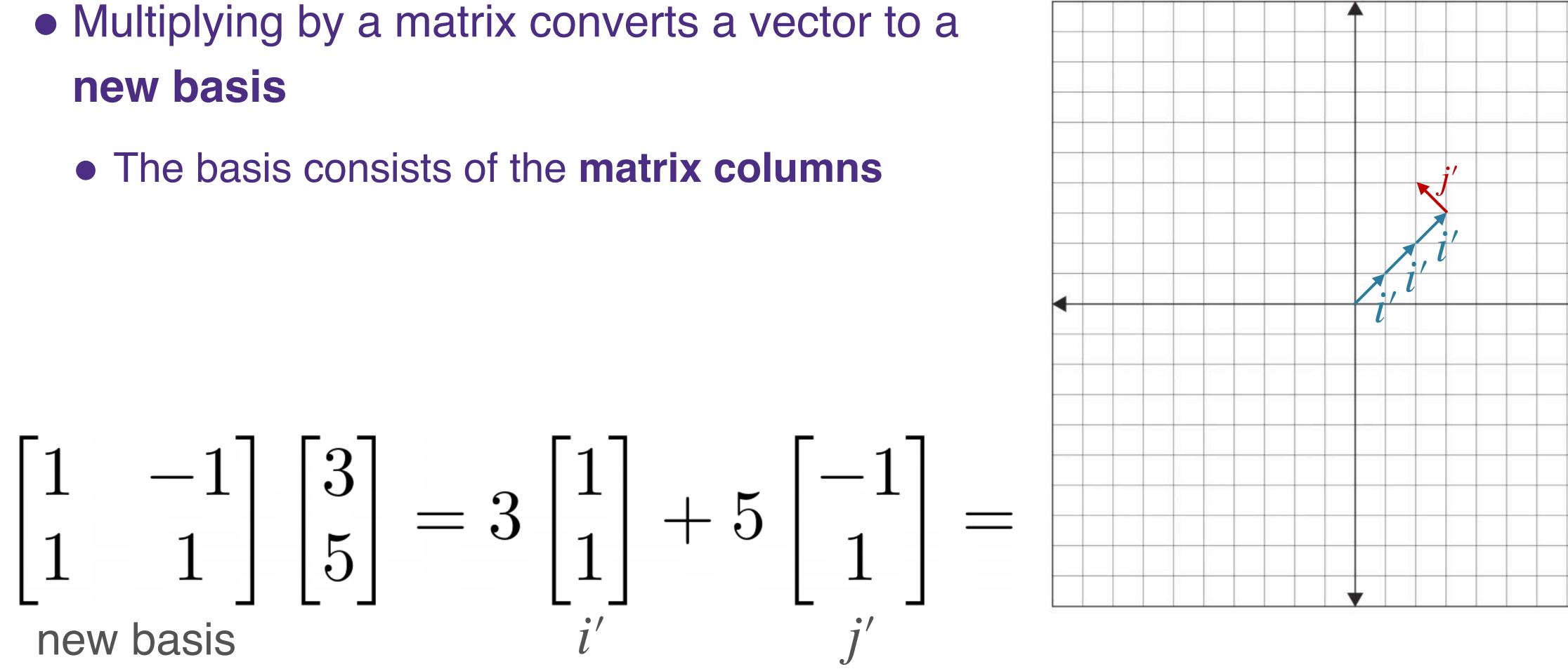








- new basis

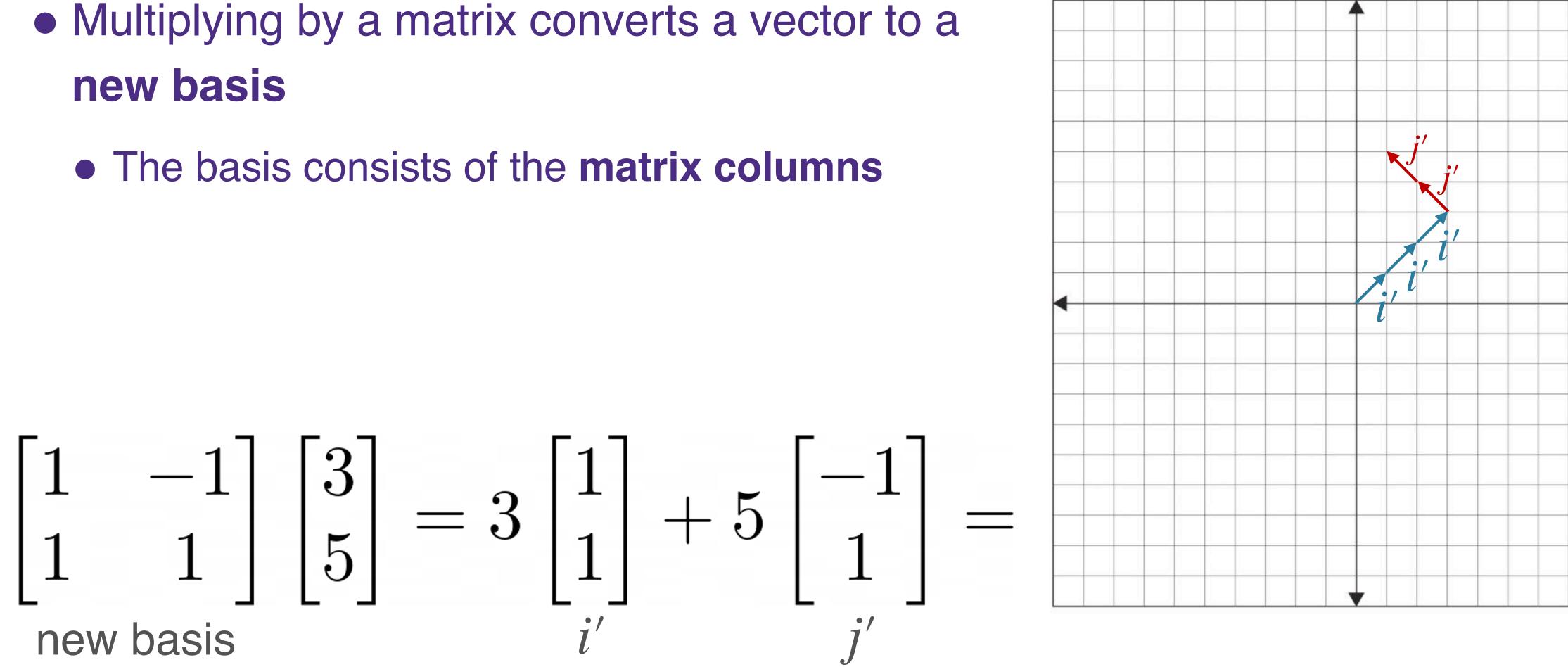


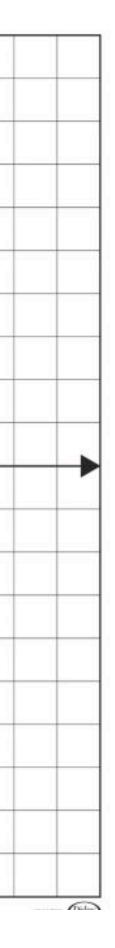






- new basis

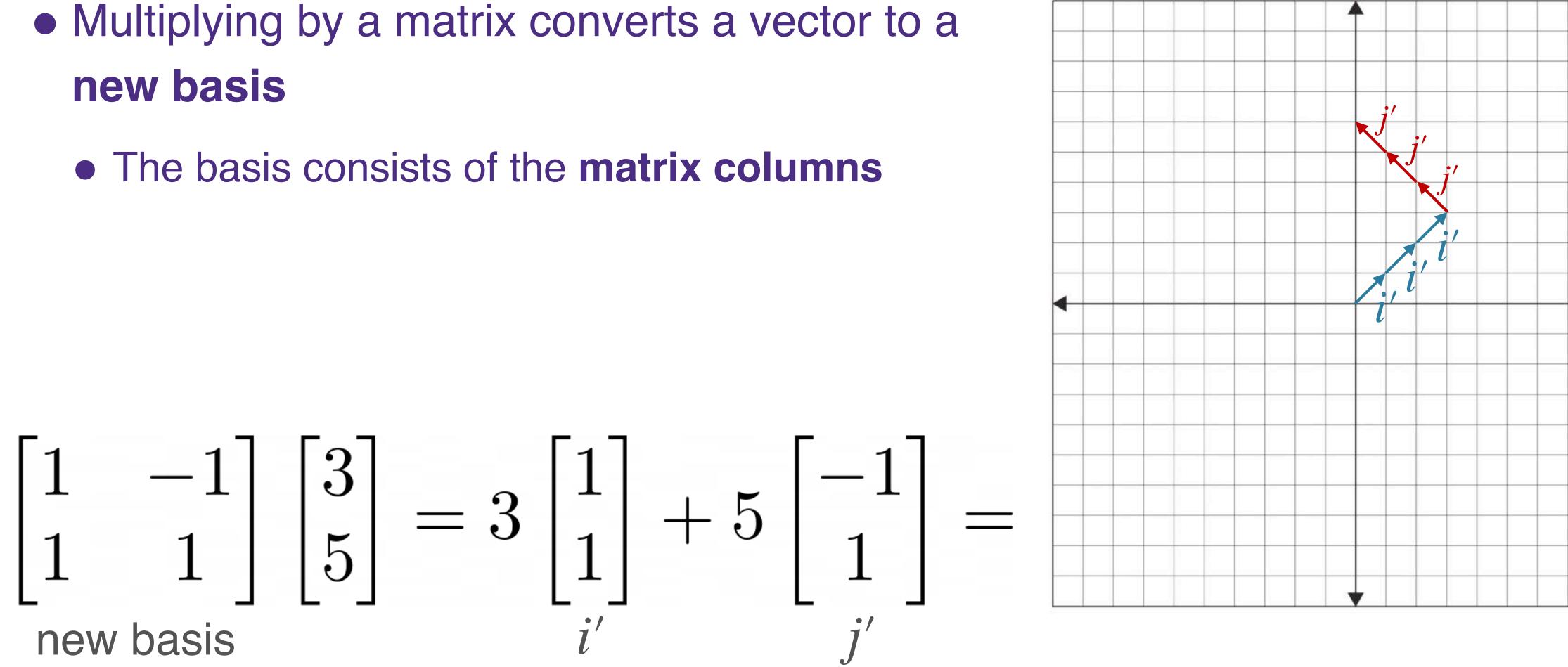








- new basis

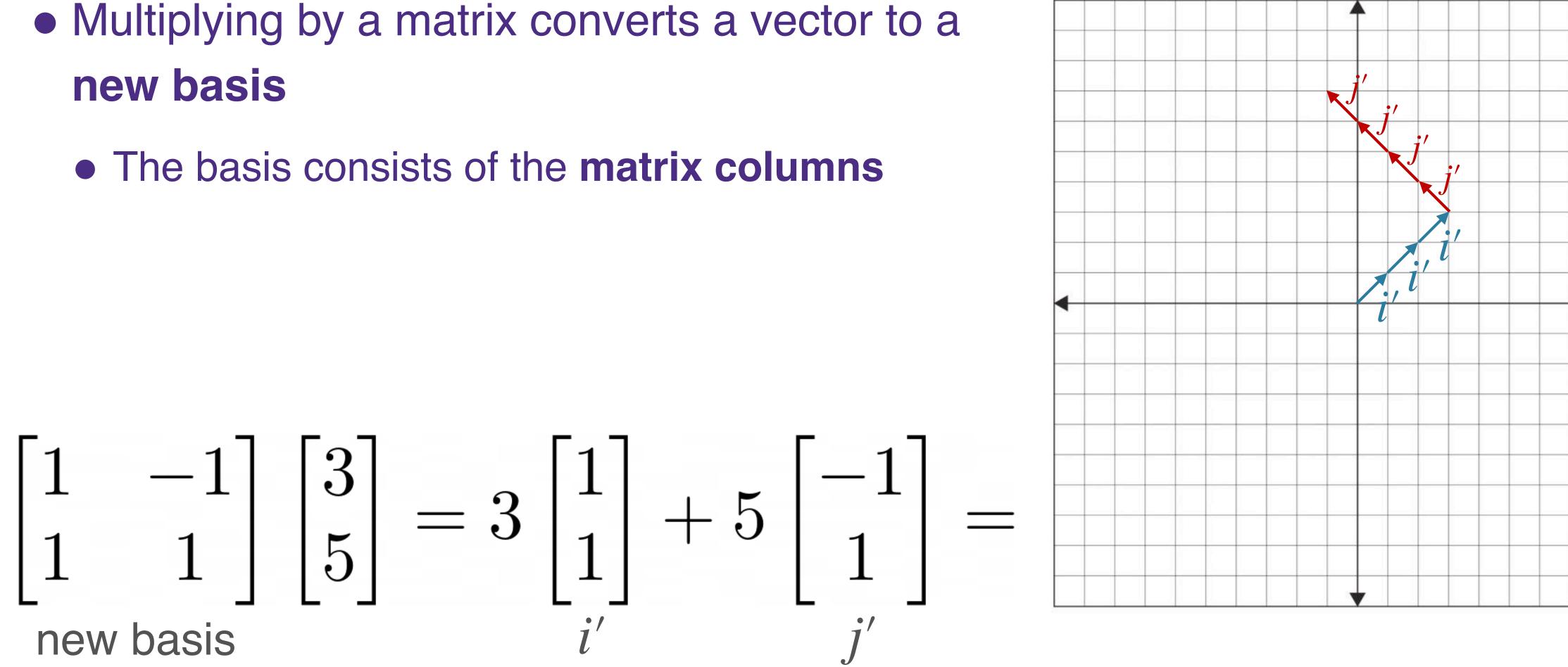








- new basis

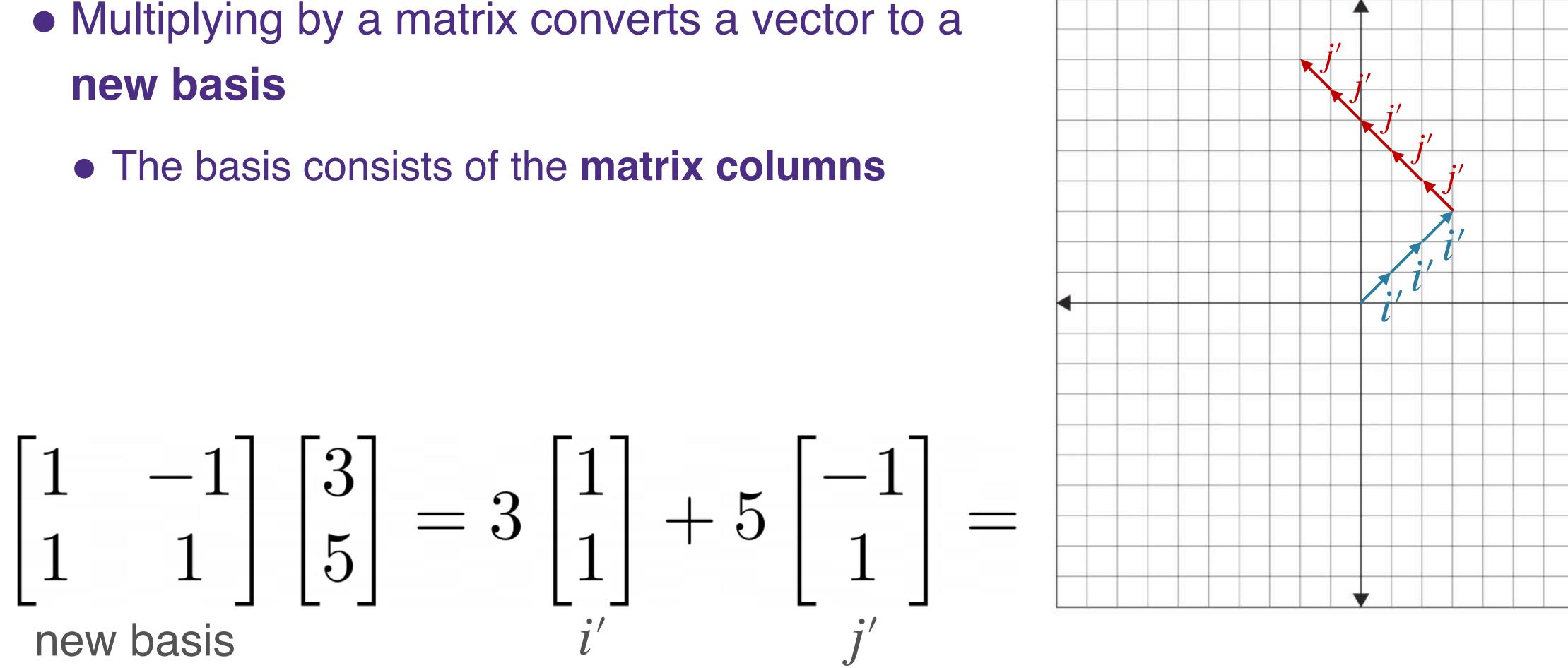


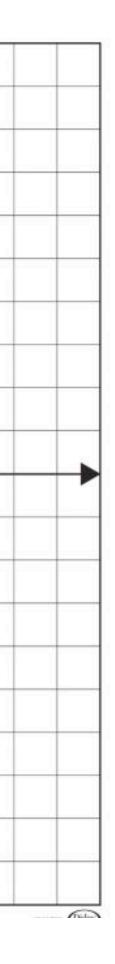






- new basis

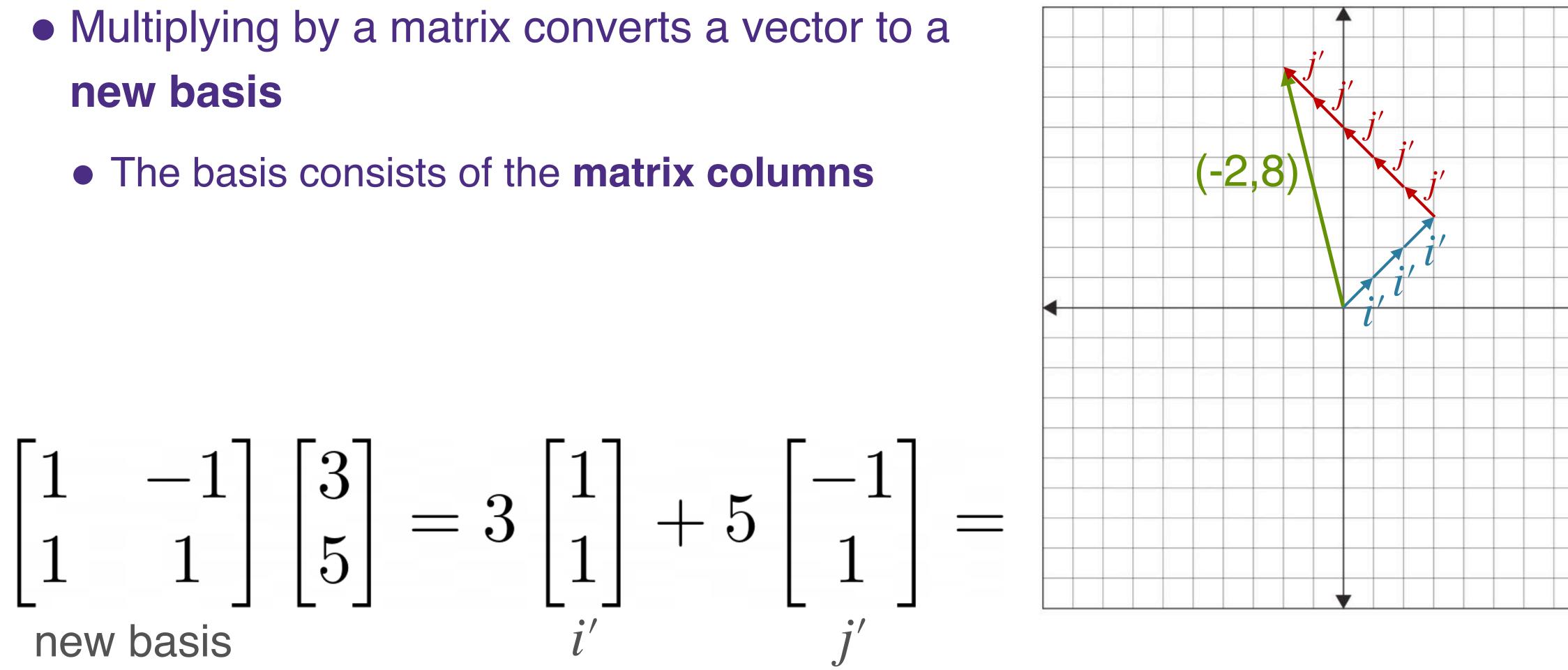








- new basis

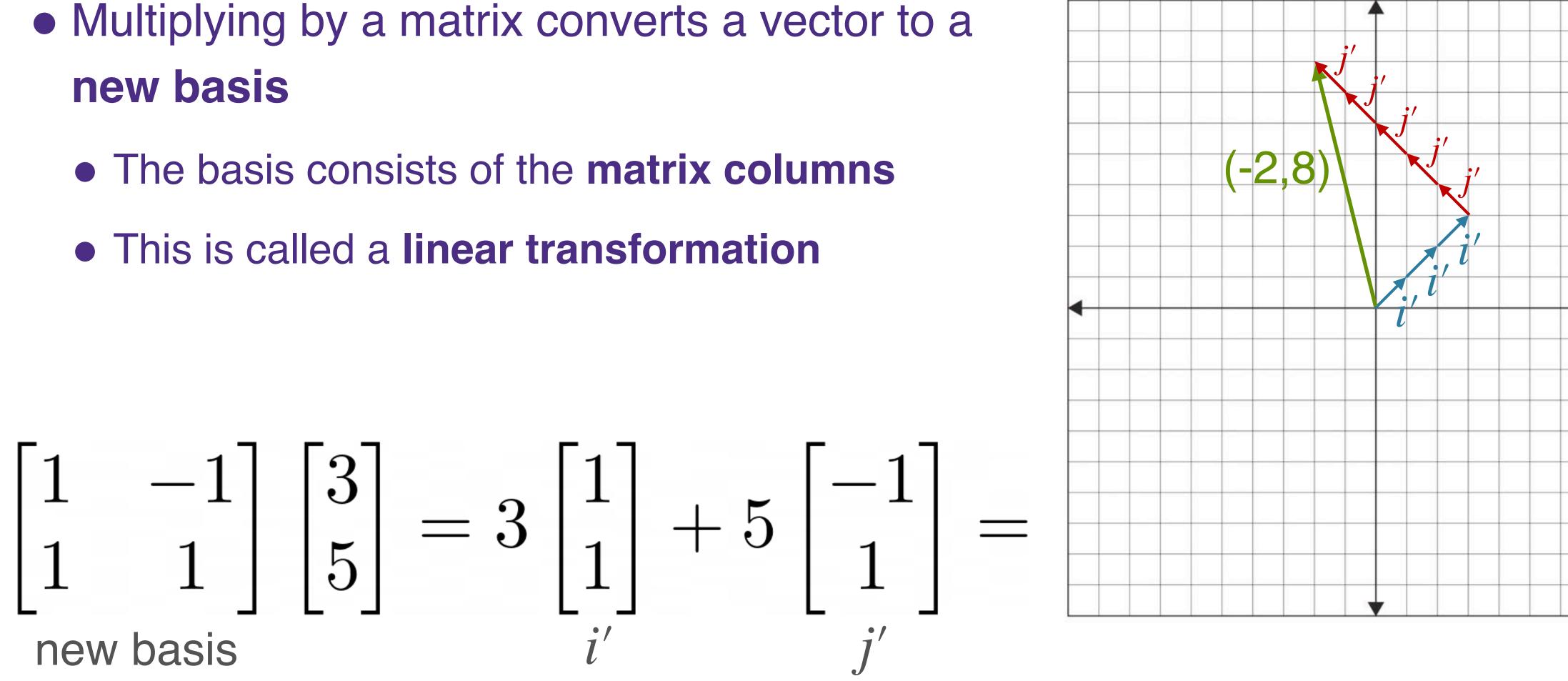








- new basis



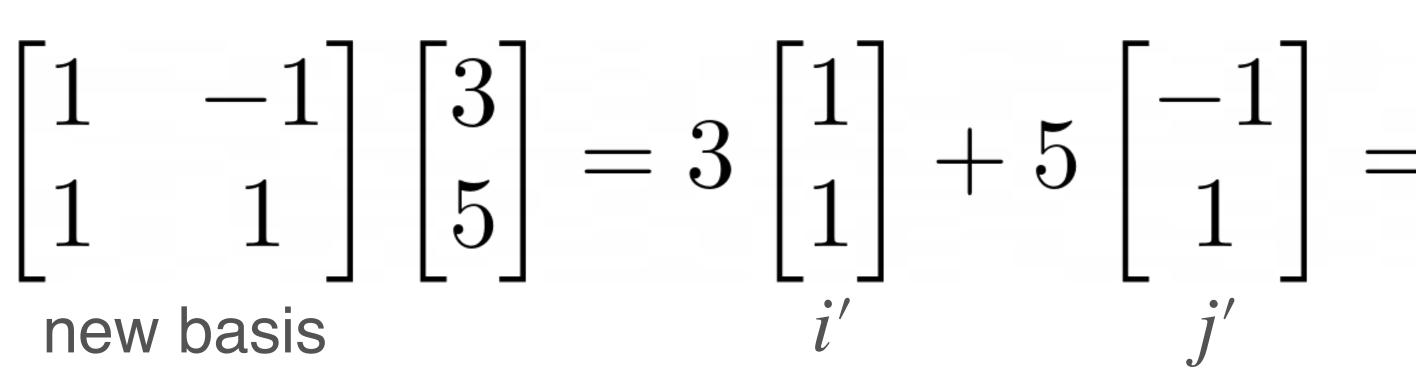


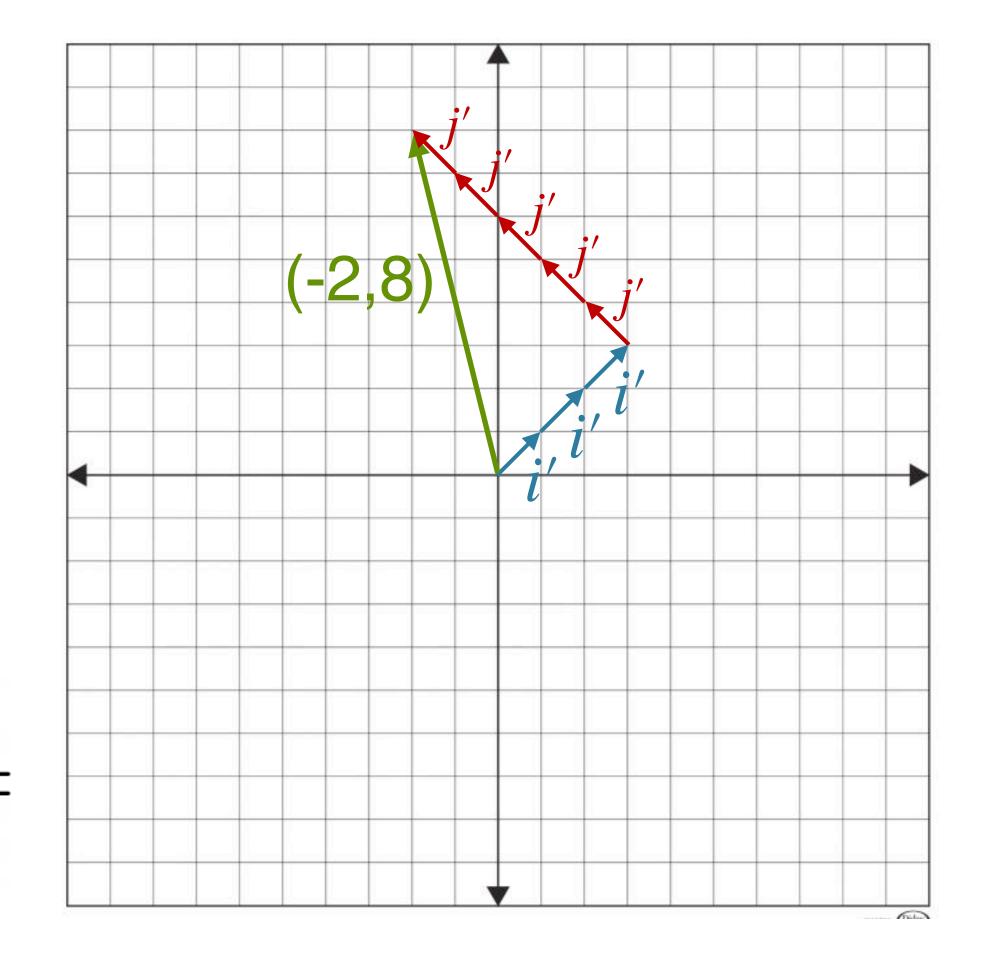




- Multiplying by a matrix converts a vector to a new basis • The basis consists of the matrix columns • This is called a **linear transformation**

 - This matrix **rotates** the space by 45° and stretches it

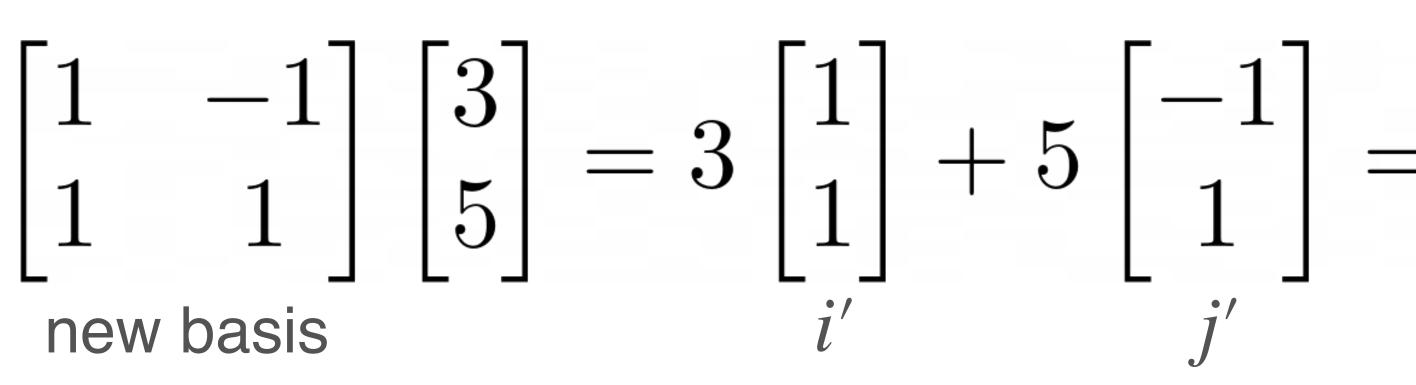


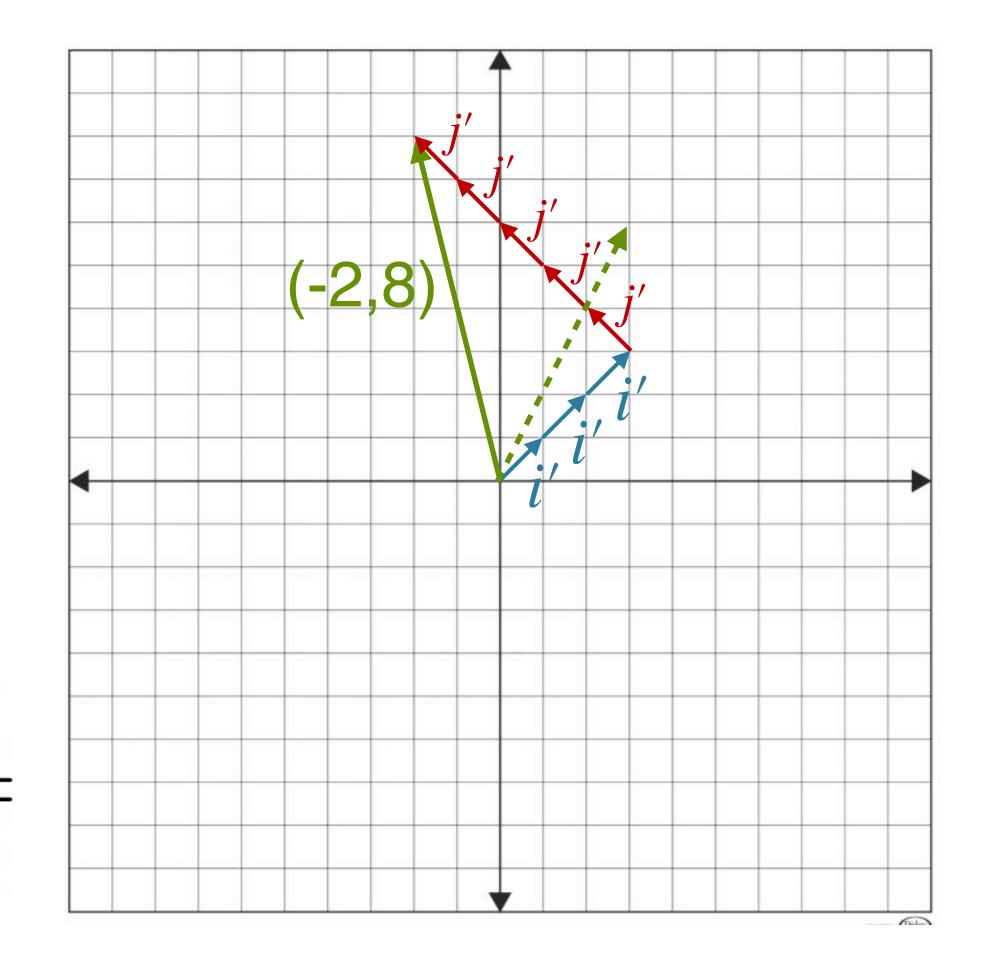


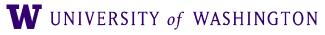




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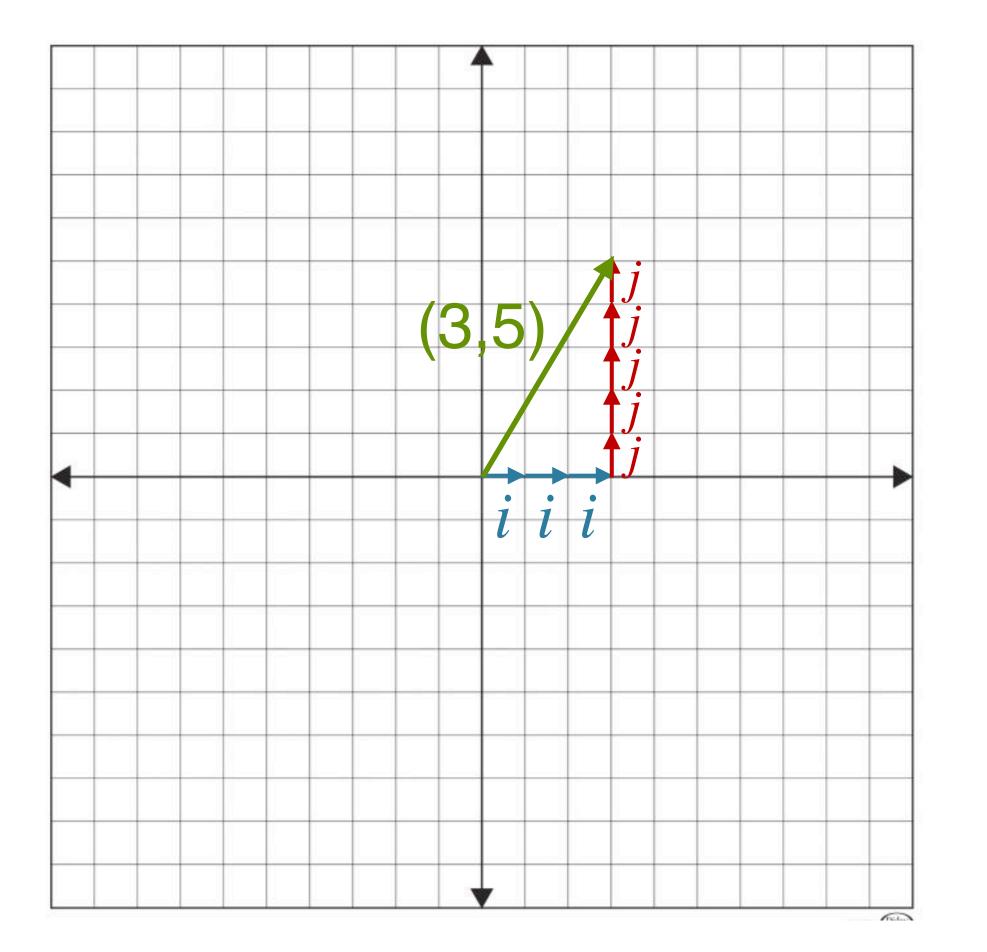


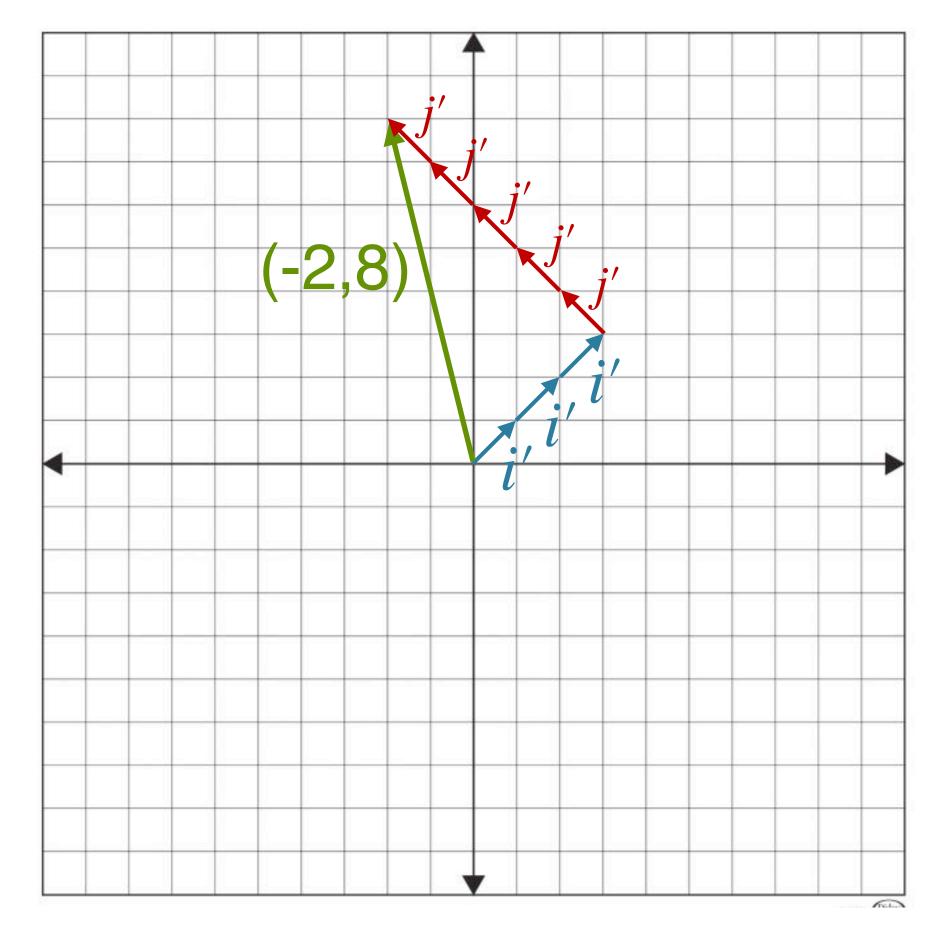








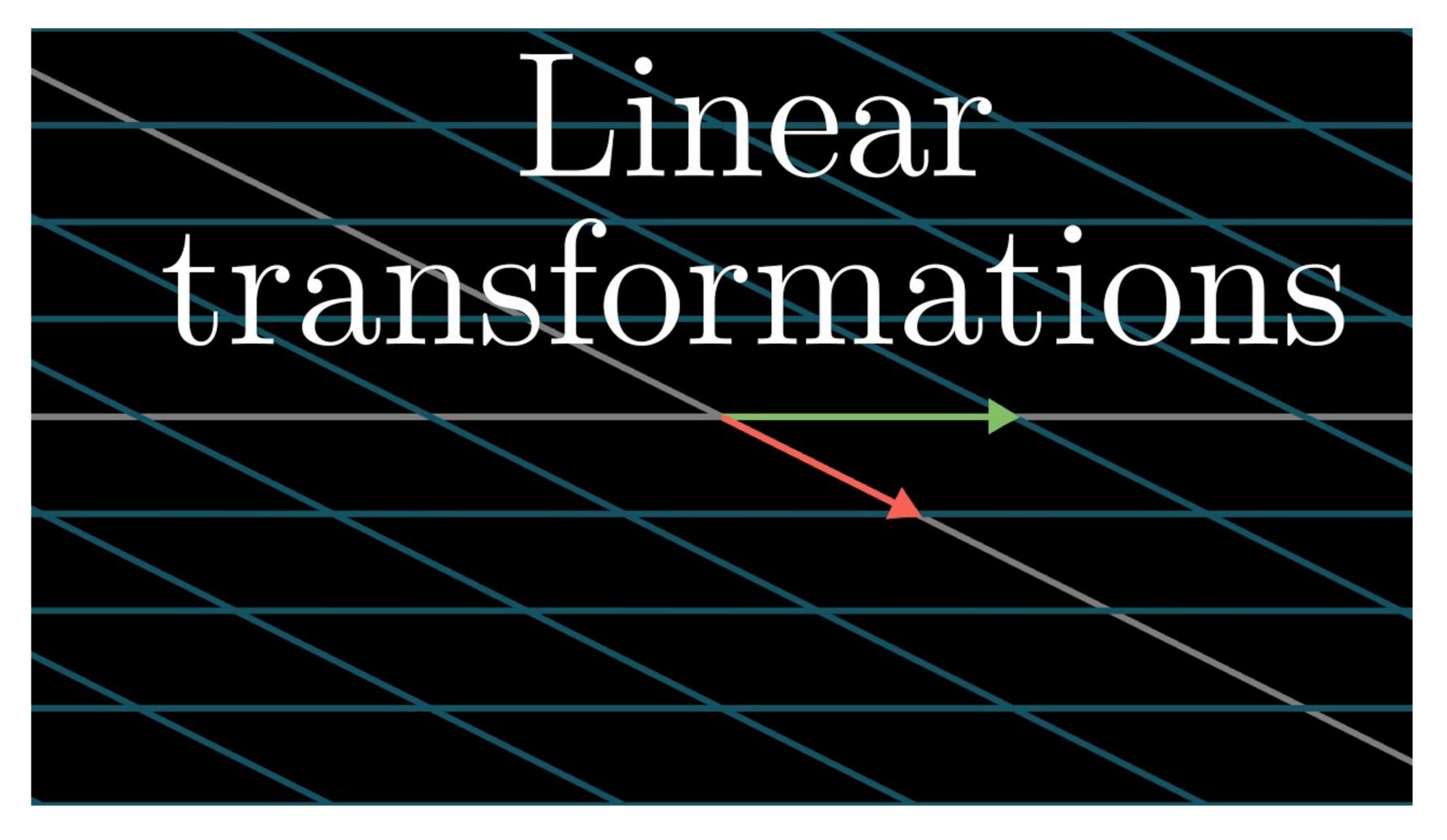








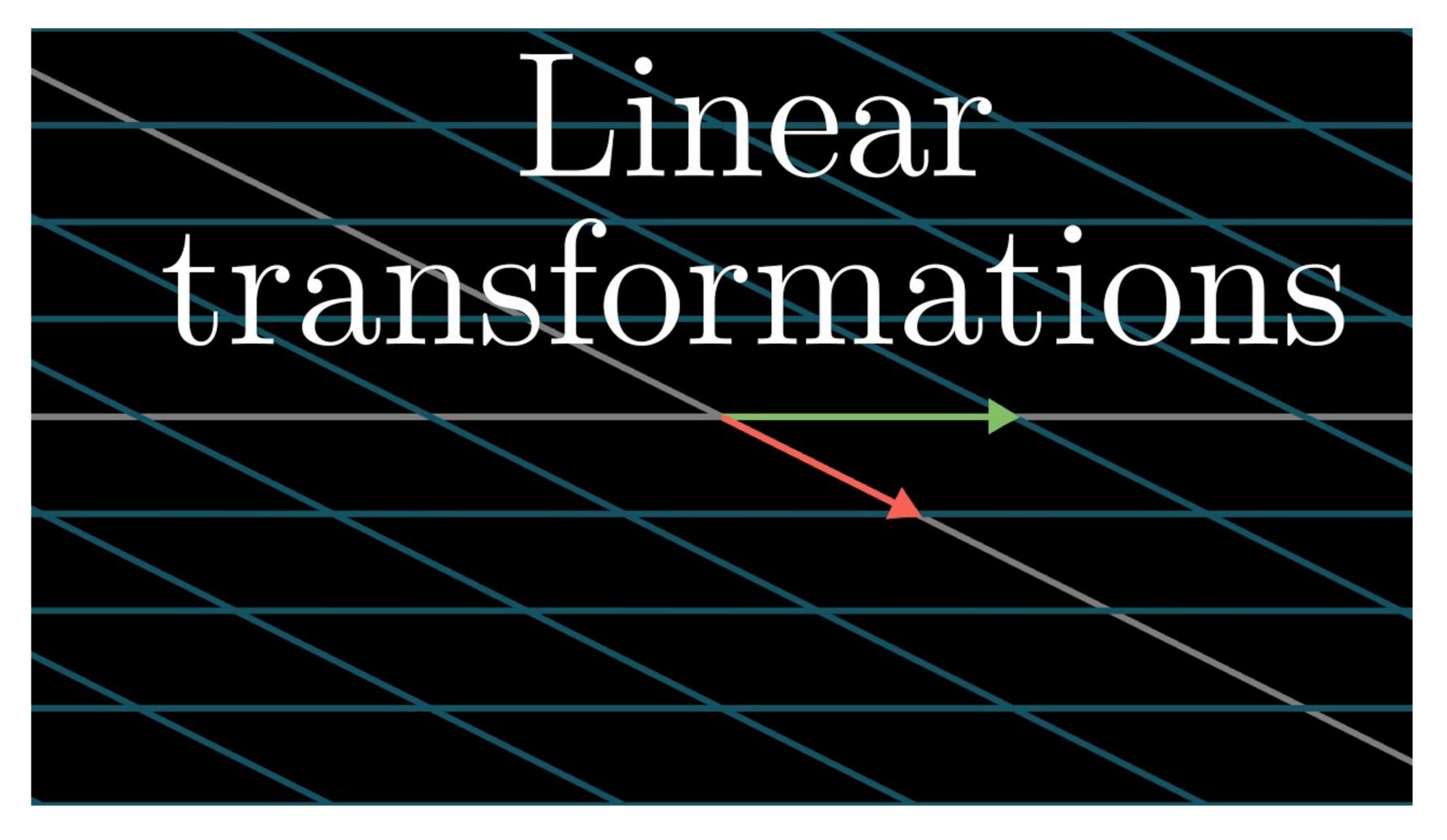
Visualizing Linear Transformations







Visualizing Linear Transformations







 $oldsymbol{W}$ university of washington





• Linear transformations (aka matrix multiplications) are the basic operation of neural networks







- of neural networks
- A feedforward NN layer:







- of neural networks
- A feedforward NN layer:
 - Takes in an **input vector**







- of neural networks
- A feedforward NN layer:
 - Takes in an input vector
 - Applies a linear transformation







- of neural networks
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 - Takes in an **input vector**
 - Applies a **linear transformation**
 - Adds a **non-linear activation function** (we'll cover this later)





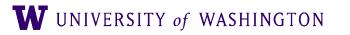


- of neural networks
- A feedforward NN layer:
 - Takes in an **input vector**
 - Applies a **linear transformation**
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- TLDR: Neural Nets transform vectors and vector spaces





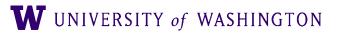








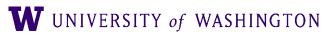
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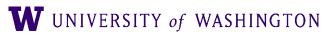
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 - You can also also reply to another student's question for credit



